Insurance Institute for Highway Safety Highway Loss Data Institute

Welcome

CAS Crash Course July 19, 2018

David Harkey, President

iihs.org

IIHS is an independent, nonprofit scientific and educational organization dedicated to reducing the losses — deaths, injuries and property damage — from crashes on the nation's roads.

HLDI shares this mission by analyzing insurance data representing human and economic losses from crashes and other events related to vehicle ownership.

Both organizations are wholly supported by auto insurers.



IIHS – HLDI supporting groups

AAA Carolinas Acceptance Insurance Alfa Alliance Insurance Corporation Alfa Insurance Allstate Insurance Group American Agricultural Insurance Company American Family Mutual Insurance Company American National Ameriprise Auto & Home Amica Mutual Insurance Company Auto Club Enterprises Auto Club Group Auto-Owners Insurance **Bitco Insurance Companies** California Casualty Group Celina Insurance Group Censtat Casualty Company CHUBB Colorado Farm Bureau Mutual Insurance Company **Concord Group Insurance Companies** COUNTRY Financial CSAA Insurance Group **Desiardins Insurance** ECM Insurance Company Elephant Insurance Company **EMC Insurance Companies** Erie Insurance Group Esurance Farm Bureau Financial Services Farm Bureau Insurance of Michigan Farm Bureau Mutual Insurance Company of Idaho Farmers Insurance Group Farmers Mutual of Nebraska Florida Farm Bureau Insurance Companies Frankenmuth Insurance Gainsco Insurance **GEICO** Corporation The General Insurance

Georgia Farm Bureau Mutual Insurance Company

Goodville Mutual Casualty Company Grange Insurance Grinnell Mutual Hallmark Financial Services Hanover Insurance Group The Hartford Haulers Insurance Company, Inc. Horace Mann Insurance Companies Imperial Fire & Casualty Insurance Company Indiana Farm Bureau Insurance Indiana Farmers Insurance Infinity Property & Casualty Kemper Corporation Kentucky Farm Bureau Mutual Insurance Companies Liberty Mutual Insurance Company Louisiana Farm Bureau Mutual Insurance Company The Main Street America Group Mercury Insurance Group MetLife Auto & Home Mississippi Farm Bureau Casualty Insurance Company MMG Insurance Munich Reinsurance America, Inc. Mutual Benefit Group Mutual of Enumclaw Insurance Company Nationwide New Jersey Manufacturers Insurance Group Nodak Mutual Insurance Company Norfolk & Dedham Group North Carolina Farm Bureau Mutual Insurance Company Northern Neck Insurance Company Ohio Mutual Insurance Group Old American Indemnity Company Oregon Mutual Insurance Company Paramount Insurance Company Pekin Insurance PEMCO Insurance **Plymouth Rock Assurance**

Progressive Insurance

Qualitas Insurance Company Redpoint County Mutual Insurance Company The Responsive Auto Insurance Company Rider Insurance Rockingham Group RSA Canada Safe Auto Insurance Company Safeco Insurance Samsung Fire & Marine Insurance Company SECURA Insurance Selective Insurance Company of America Sentry Insurance Shelter Insurance Companies Sompo America South Carolina Farm Bureau Mutual Insurance Company Southern Farm Bureau Casualty Insurance Company State Farm Insurance Companies Stillwater Insurance Group Tennessee Farmers Mutual Insurance Company Texas Farm Bureau Insurance Companies The Travelers Companies United Educators USAA Utica National Insurance Group Virginia Farm Bureau Mutual Insurance West Bend Mutual Insurance Company Western National Insurance Group Westfield Insurance

Funding associations

American Insurance Association National Association of Mutual Insurance Companies Property Casualty Insurers Association of America



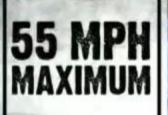
Haddon matrix

Recognizing opportunities to make a difference

	pre-crash	during crash	after crash
people	graduated licensing impaired driving laws automated enforcement	safety belts helmets	medical bracelets general health
vehicles	crash avoidance technology	airbags crashworthiness truck underride guards	automatic collision notification fuel system integrity
environment	roundabouts rumble strips	roadside barriers breakaway poles	emergency medical services long-term rehabilitation



CBS Evening News





Advanced Driver Assistance Technology: The Latest Insights

iihs.org

CAS Crash Course July 19, 2018 David Zuby, EVP and Chief Research Officer David Aylor, Manager of Active Safety Testing Jessica Cicchino, VP of Research Matt Moore, SVP of HLDI

Evaluations of Advanced Driver Assistance Systems (ADAS)

II<mark>H</mark>S

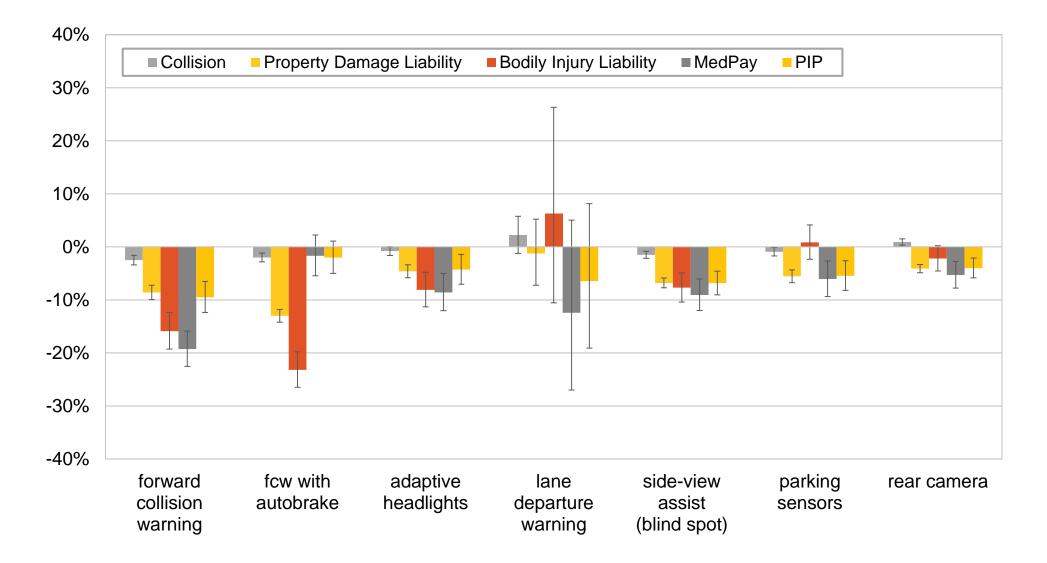
HLDI collision avoidance analysis

- The HLDI database includes data from companies that represent 85% of private passenger auto insurance in the U.S.
- On a monthly basis, HLDI processes 320 million insurance data transactions
- The insurance data includes the garaging zip code and rated driver demographics
- Manufacturers shared with us 17 digit VINs and information about collision avoidance systems fitted to those vehicles
- Our collision avoidance analysis used the manufacturer supplied feature data along with our geographic and demographic data
- Large amount of timely data
- Limited information on crash circumstances



Summary of technology effects on insurance claim frequency

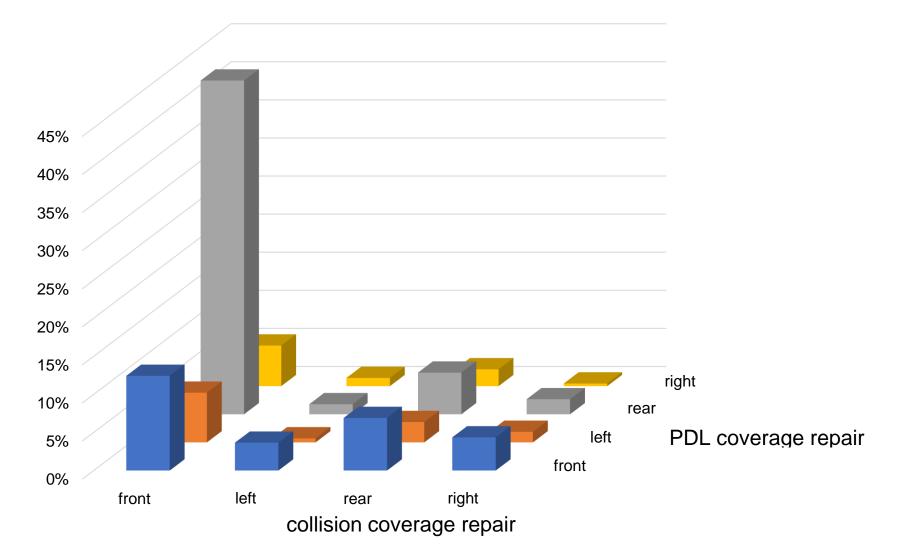
Results pooled across automakers





Percent distribution of matched pairs of collision & PDL estimates by point of impact

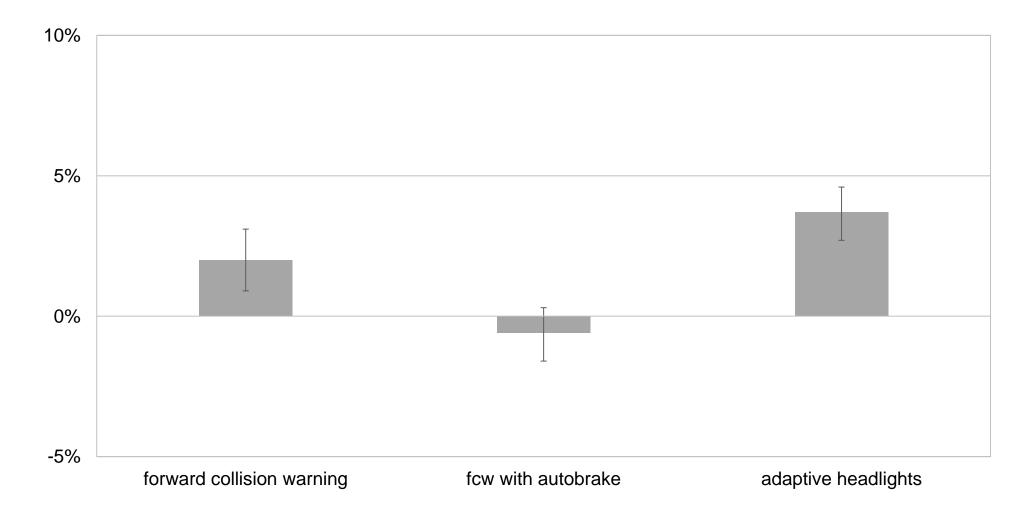
1981-2017 models, 2016 calendar year





Summary of technology effects on collision claim severity

Results pooled across automakers





HLDI and police-reported crash data

Insurance data

- Large amount of timely data
- Limited information on crash circumstances

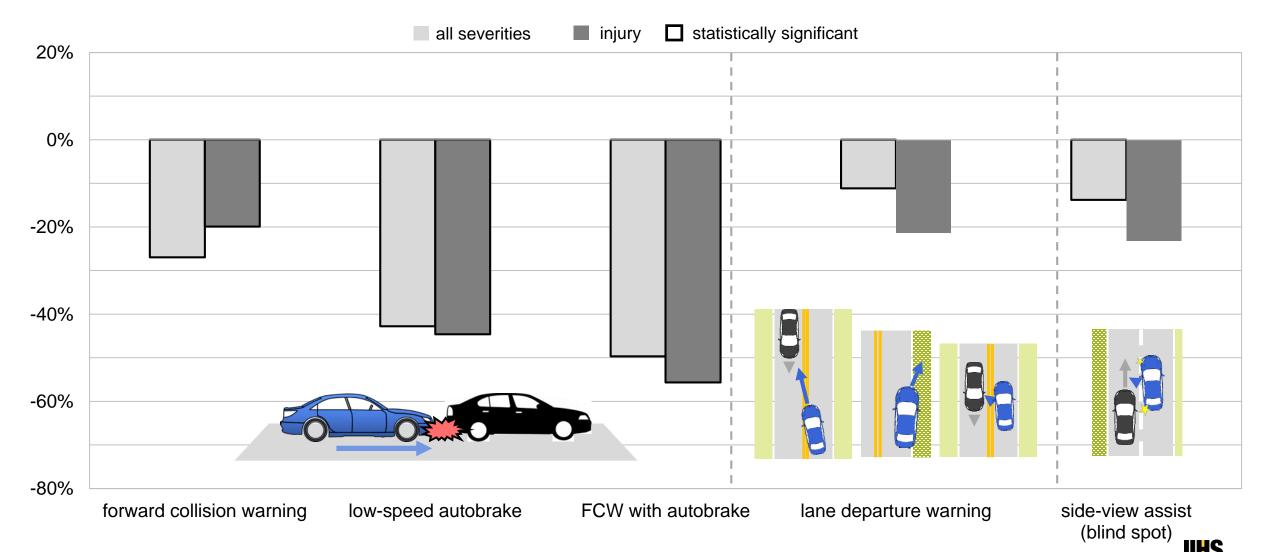
Police-reported crash data

- More detailed information on crash type
- Limitations
 - Some crashes not reported to police
 - Delay in obtaining data
 - Data collected not uniform among states, and not all states have information to determine crash types



Most crash avoidance technologies are living up to expectations

Effects on relevant police-reported crash types



Front crash prevention testing and rating

Front crash prevention ratings



vehicles without forward collision warning or autobrake; or vehicles equipped with a system that doesn't meet NHTSA or IIHS criteria



vehicles earning 1 point for forward collision warning or 1 point in either 12 or 25 mph test



vehicles with autobrake that achieve 2-4 points for forward collision warning and/or performance in autobraking tests



vehicles with autobrake that achieve 5-6 points for forward collision warning and/or performance in autobraking tests



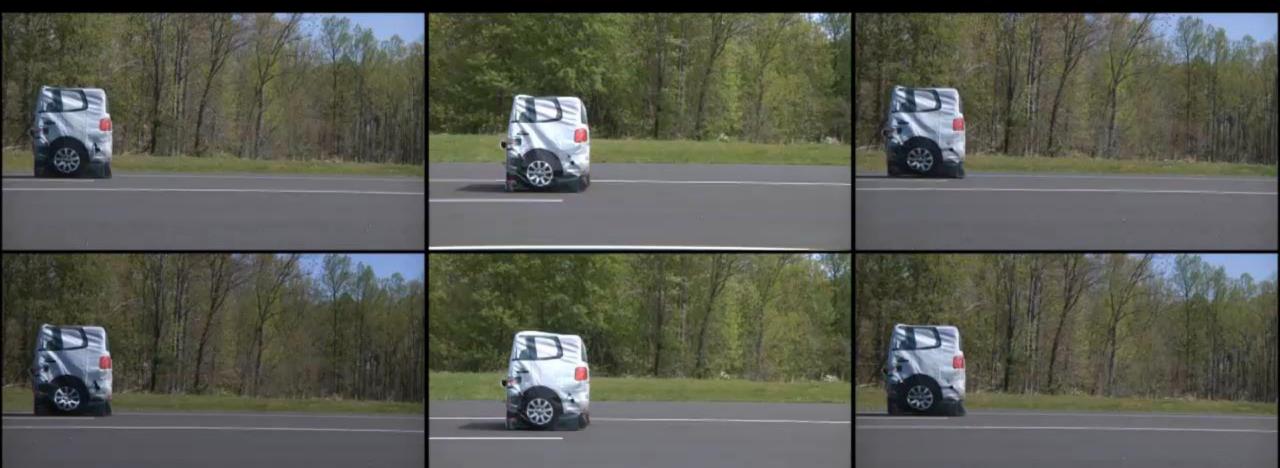


25 mph \$28,131

12 mph \$5,715

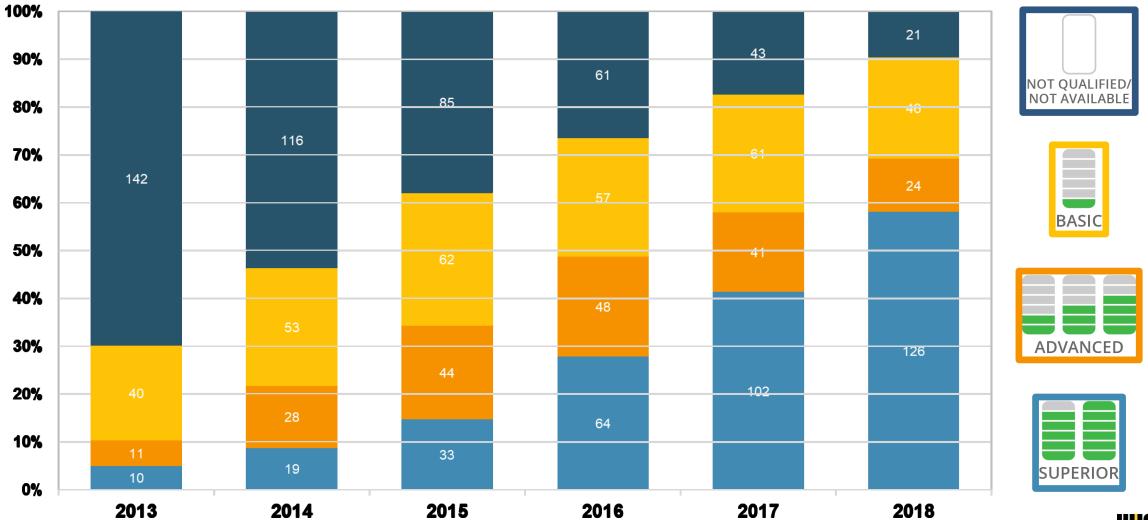
Speed reduction in 12 and 24 mph tests

Volvo S60 2 point advanced Dodge Durango 3 point advanced Subaru Outback 6 point superior



Front crash prevention ratings

2013-18 models, as of July 13, 2018





20 automakers have committed to make AEB a standard feature by September 2022





What kinds of front-to-rear crashes are vehicles with autobrake still involved in?

Not all rear-end crashes are the same





Not all rear-end crashes are the same





2014 Infiniti Q50

2015 Subaru Legacy

2014 Volvo S80



Speed reduction

7 mph

6 mph

4 mph

Headlight testing and ratings

IIHS HLDI

Motivation for headlight evaluation program

19,310 annual crash deaths in dark, dawn, dusk light conditions (2016 FARS)

HLDI analyses point to benefits for curve-adaptive headlights

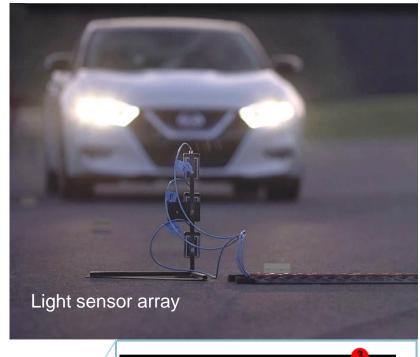
(2012 HLDI analyses of Mazda, Acura, Mercedes-Benz, Volvo claims)

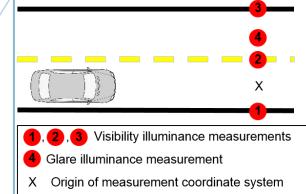
- Human factors experiments have established link between detection performance and improved lighting
- FMVSS 108 produces wide range of on-road visibility
 - -Large variation in allowable intensity
 - Performance is not measured when installed, so factors like lamp height and spread are not captured
 - -Aim is not regulated



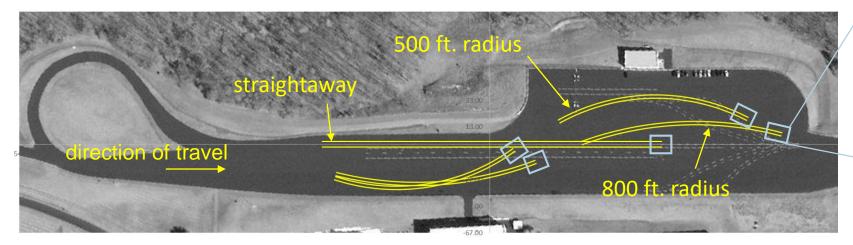
Dynamic headlight test setup

- Vehicle approaches:
 - -500 ft. radius left and right curves at 40 mph
 - -800 ft. radius left and right curves at 50 mph
 - Straightaway at 40 mph
- Record illuminance readings for:
 - -Visibility edges of road at 10 in. above ground
 - -Glare center of oncoming lane (3 ft. 7 in.)









Headlight releases



Midsize car ratings – March 2016 31 models – 82 headlight combinations 65.7 million viewers



Pickup truck ratings – October 2016 11 models – 23 headlight combinations 54.5 million viewers



Small SUV ratings – July 2016 21 models – 47 headlight combinations 67.5 million viewers



Midsize SUV ratings – June 2017 37 models – 79 headlight combinations 72.2 million viewers



Consumer comments on headlight ratings

I wanted to thank IIHS for the headlight ratings report that you released last week.

-EH (Medford, New Jersey)

I own a 2013 Ford Edge. It should have come with a Seeing Eye Dog. For the first time in my life, I am afraid to drive at night. -AM (Buckingham, Virginia)

Thank you for proving to my friends that I'm not crazy or blind. -RW (Mentor, Ohio)

Thanks for the great work! -RV (Tiverton, Rhode Island)



Toyota Prius v LED and BMW 3 series halogen

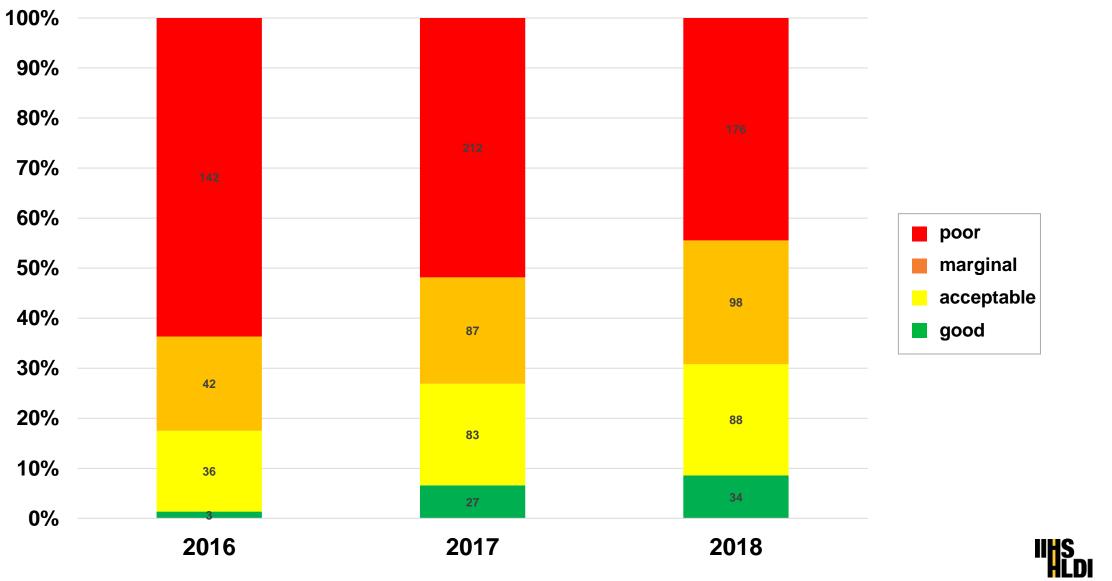
On-road comparison





Headlight ratings (as of 7/13/18)

2016-2018 model years - all headlight variants

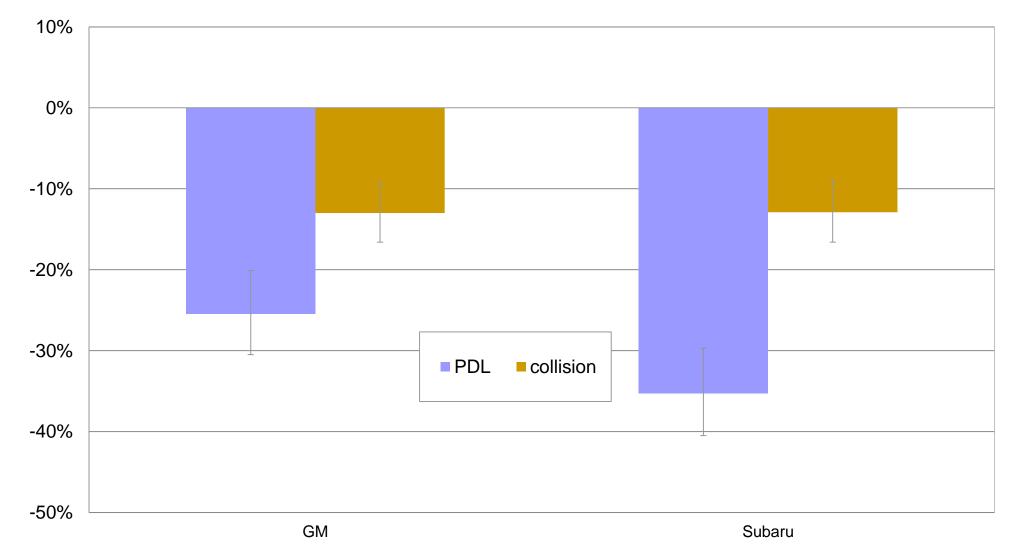


Rear crash prevention real world results



Rear automatic braking

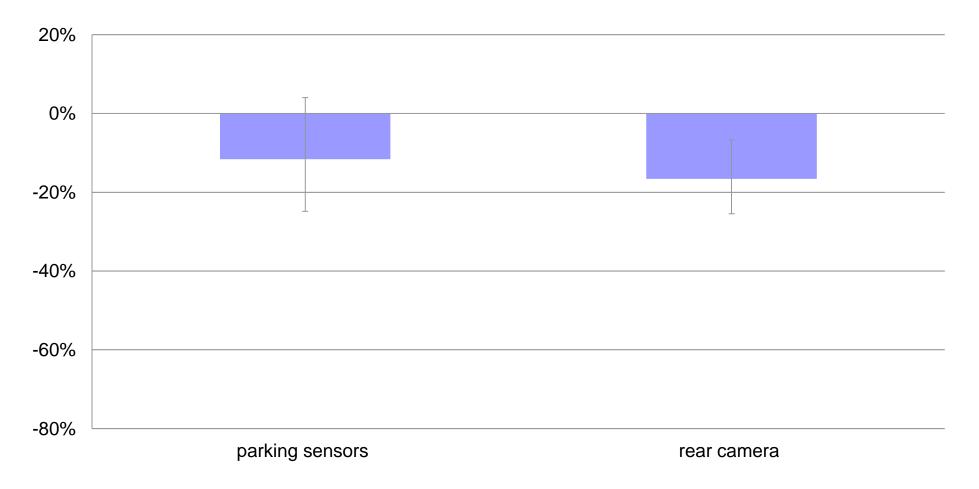
Change in claim frequency





Rear camera and parking sensors have modest effects on backing crashes

Percent difference in police-reported backing crash rates





Drivers must respond to sensors for them to work





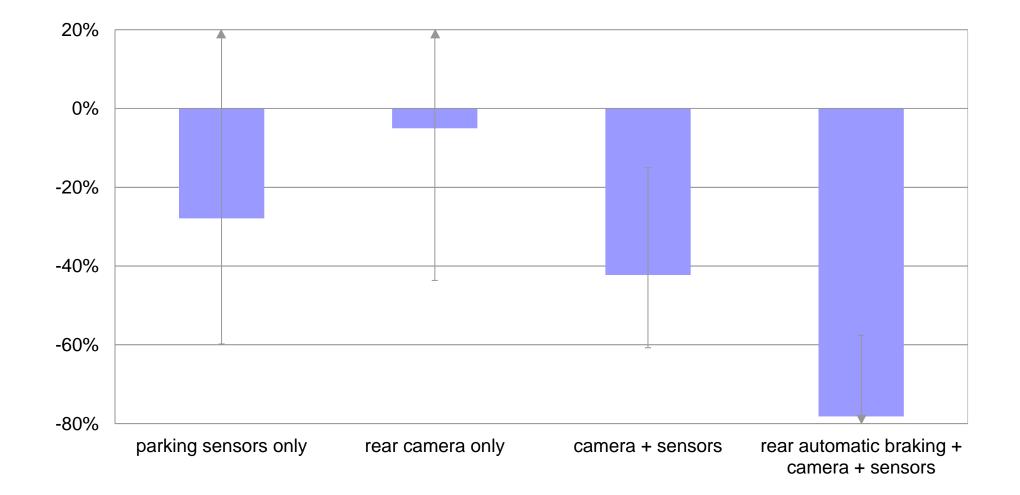
Objects are not always easy to see in the camera display





Rear automatic braking increases effectiveness

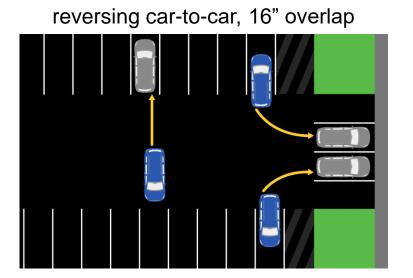
Percent difference in police-reported backing crash rates for General Motors vehicles



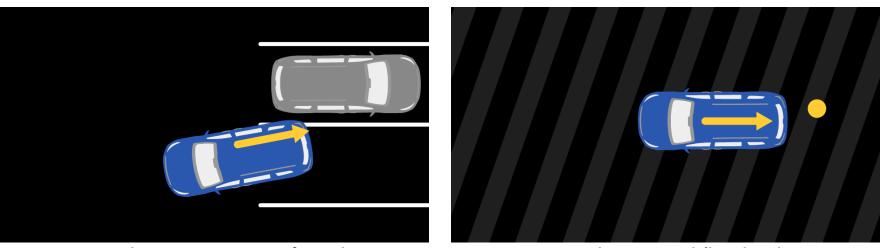


Rear crash prevention testing and ratings

Rear crash prevention test scenarios



reversing car-to-car, 45° angle



reversing car-to-car, 10° angle

reversing toward fixed pole



Rear crash prevention ratings

Unavailable

- Vehicles without rear parking sensors, rear cross traffic alert, or rear autobrake rear cross traffic alert
- Basic
 - Vehicles with rear cross traffic alert only
 - Vehicles with parking sensors only
 - Vehicles with cross traffic alert and parking sensors
 - Vehicles with parking sensors and/or RCTA and minimal rear autobrake performance

Advanced

 Vehicles with rear parking sensors, rear cross traffic alert, and more capable rear autobrake system

Superior

 Vehicles with rear parking sensors, rear cross traffic alert, and the best performing rear autobrake systems

NOT AVAILABLE









How vehicles rate for rear crash prevention, 2017 models



Jeep Cherokee

Toyota Prius



Subaru Outback



Benefit of rear autobrake







SUPERIOR CONFIDENCE

The 2018 Cadillac XT5 has received an IIHS rating of Superior for rear crash prevention.



The Insurance Institute for Highway Safety has launched a rear crash prevention ratings program that can help consumers identify vehicles with the technology that can prevent or mitigate low-speed backing crashes. The 2018 Cadillac XT5 has earned the highest rating of Superior when equipped with optional Driver Assist Package. The Driver Assist Package includes Reverse Automatic Braking and is only available on vehicles equipped with Rear Cross Traffic Alert and Rear Park Assist.





Lane departure prevention performance

On-off status of front crash prevention systems

By manufacturer

	percent with system on	number observed
Cadillac	92	206
Chevrolet	87	142
Honda	98	239
Mazda	95	20
Volvo	94	52
total	93	659



Low use is likely limiting effectiveness of lane maintenance systems

2016 IIHS observations at dealership service centers

1

	percent with system on	number observed
Ford/Lincoln	23	93
Honda	36	239
Chevrolet	50	147
Cadillac	56	204
Lexus/Toyota	68	147
Volvo	75	105
Mazda	77	26
total	52	961



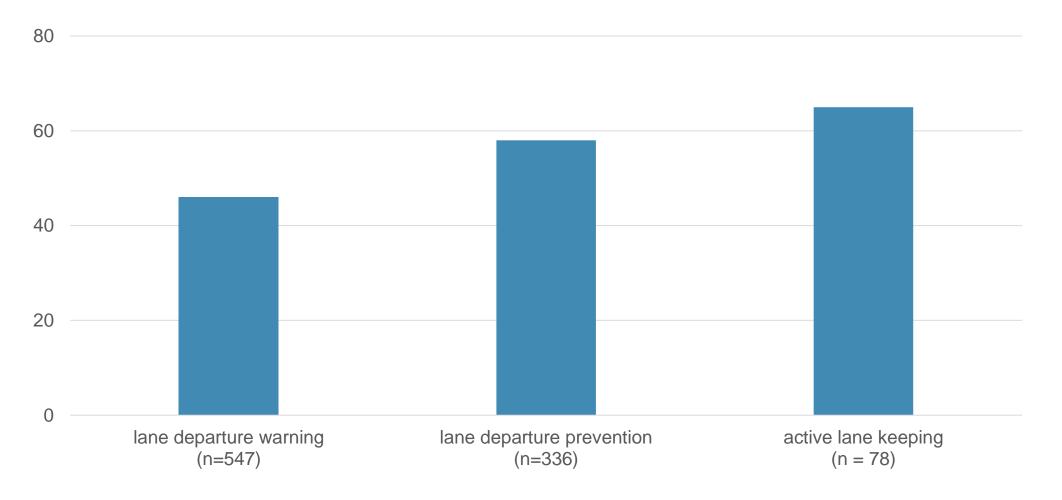
GM lane departure warning on-off status by warning modality

		percent with system on	number observed
beep	Cadillac	33	18
	Chevrolet	39	66
	total	38	84
vibrating seat	Cadillac	58	142
	Chevrolet	49	49
	total	56	191



On-off status by maximum observable lane-maintenance intervention level

Percent with system on





Advertisement:

Lane valet

Method for testing lane departure prevention performance





- ▶ 80 lane drifts on four-lane divided highway
 - 40 departures in 1,000-meter-radius curve, departed opposite direction of curve
 - Drive straight into curve to induce departure in opposite direction
 - -40 departures on straightaway
 - Slight steering input by driver to induce departure
 - Departures balanced between left/right and dashed/solid lines
 - -50 mph test speed

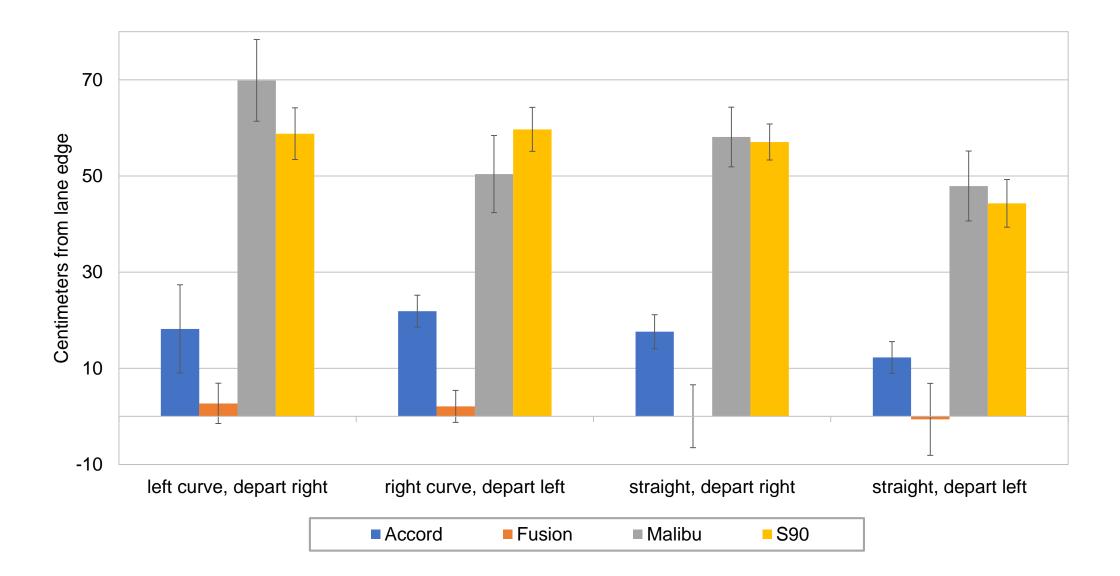


Video fed to datalogger to code and measure performance

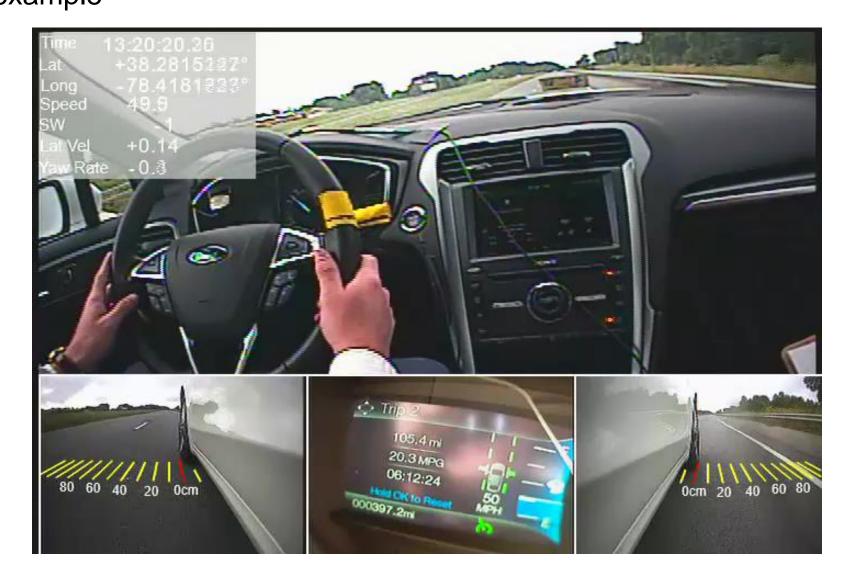




Mean distance to inside lane edge when steering input first occurred



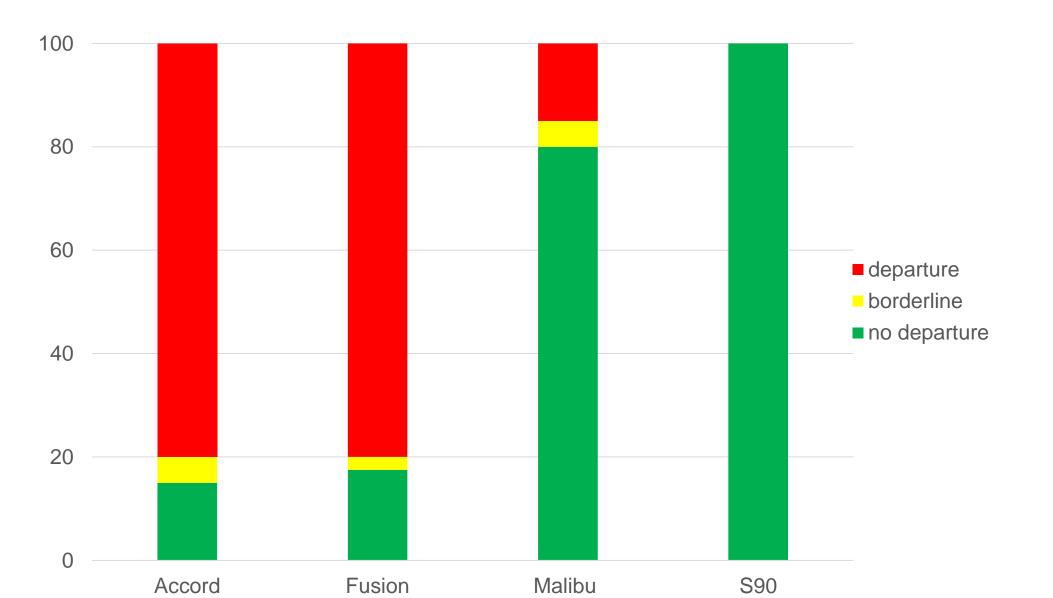
Judgements of whether departure greater than 35 cm occurred Departure example





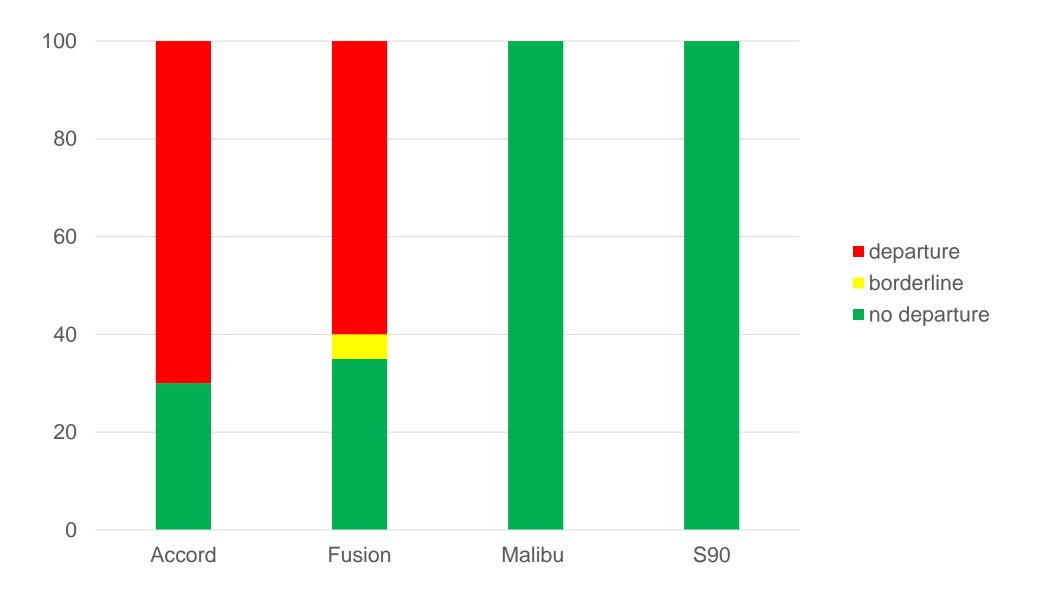
Did car depart lane by more than 35 cm?

Percentage of trial outcomes across all scenarios with a solid lane marker



Did car depart lane by more than 35 cm?

Percentage of trial outcomes in curve scenarios with a solid lane marker



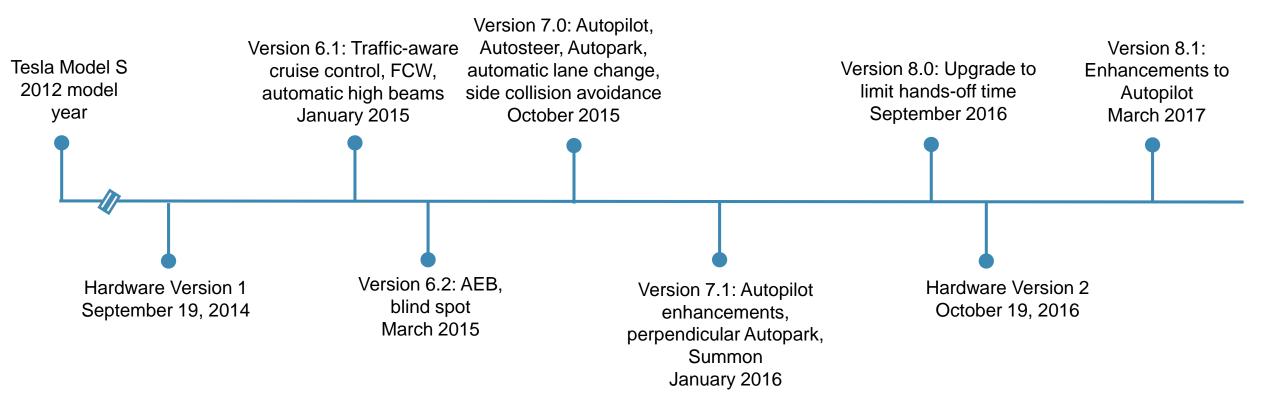
SAE International's automation levels

	Who or what is driving?			Where and
	Sustained control	Detection & response	Fallback	when does it operate?
Level 0: none	R	R	none	n/a
Level 1: assistance			æ	limited
Level 2: partial		æ	R	limited
Level 3: conditional			æ	limited
Level 4: high				limited
Level 5: full				unlimited



Tesla Model S driver assistance technologies

Tesla timeline





Tesla Model S insurance losses by model year Methods

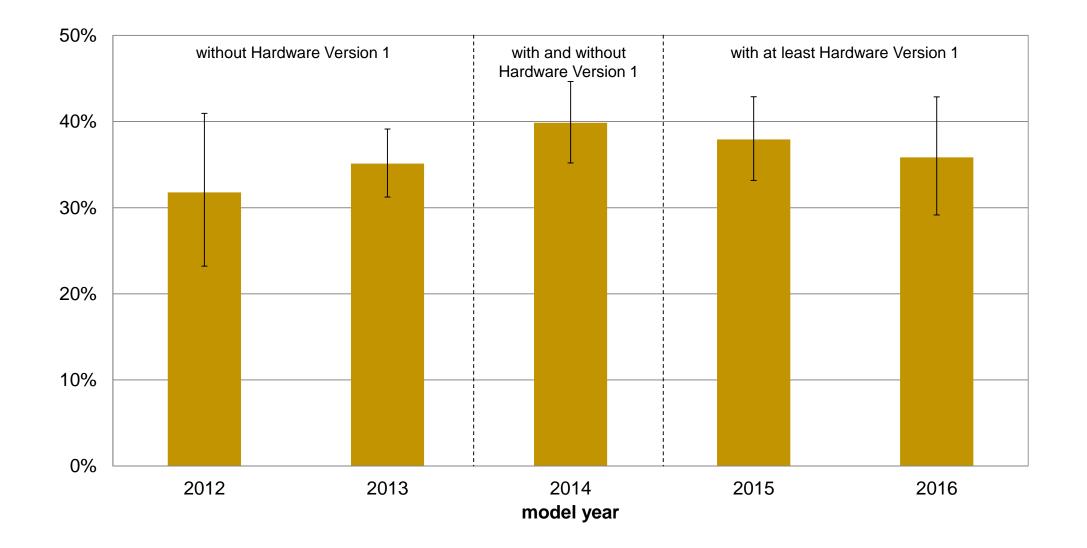
collision exposure (in years)	3,271,318
model years	2012-16
covariates	model year, calendar year, state, vehicle density, rated driver age, gender, and marital status, deductible, risk, drive type (4WD vs. 2WD), miles per day, model year * Tesla
control group	large luxury vehicles

Т



Tesla Model S versus large luxury vehicles

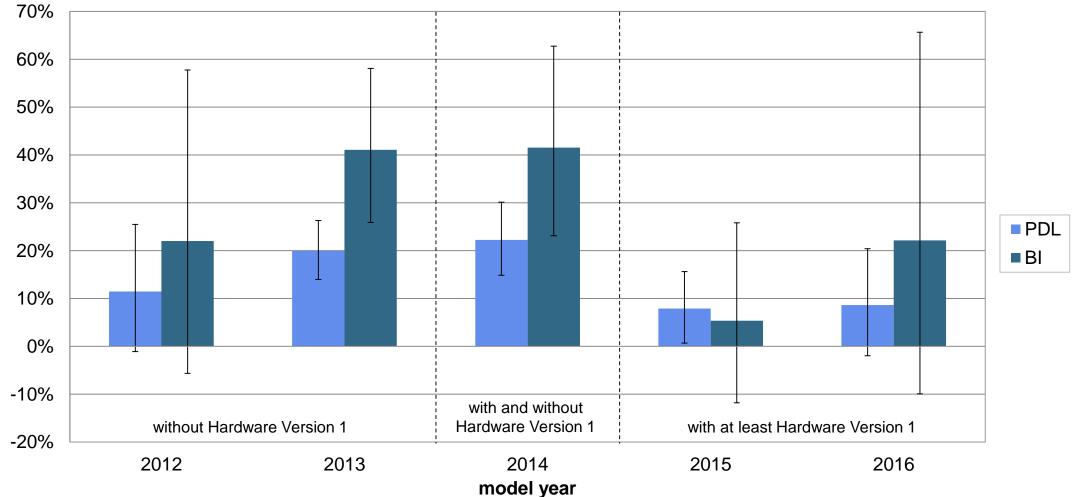
Collision claim frequency, by model year





Tesla Model S versus large luxury vehicles

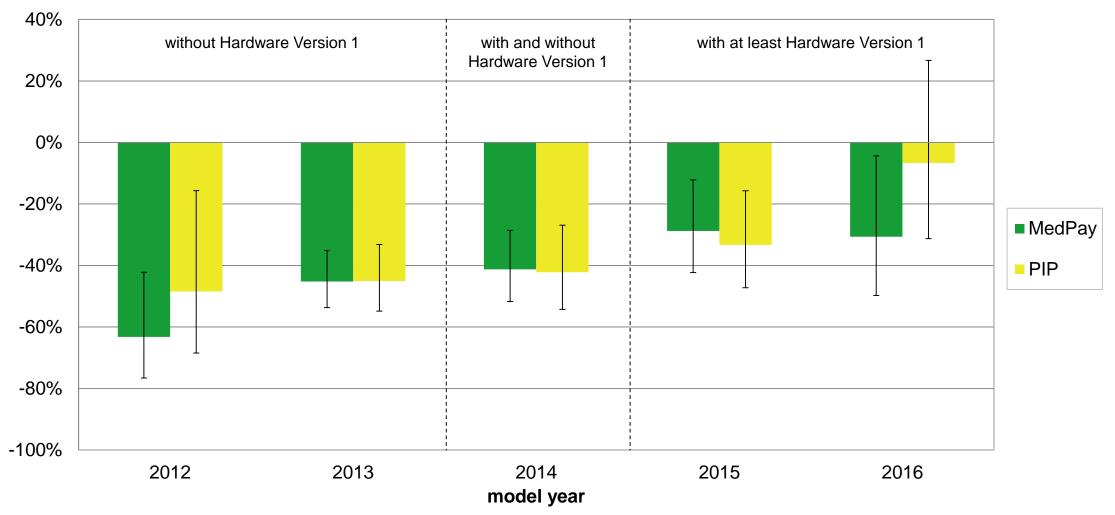
PDL and BI claim frequencies, by model year





Tesla Model S versus large luxury vehicles

MedPay and PIP claim frequencies, by model year





Estimating effect of driver assistance technology enabled by Tesla Model S Hardware Version 1

- Use "difference-in-differences" approach to compare the loss experience of Tesla Model S vehicles with and without driver assistance technology (including Autopilot) enabled to same aged large luxury vehicles
- With driver assistance technology: 2015-16 Tesla Model S vs 2015-16 conventional large luxury
- Without driver assistance technology: 2012-14 Tesla Model S vs 2012-14 conventional large luxury
- Adjustments made to account for:
 - Some 2014 MY had Hardware Version 1
 - Software update 6.1 in January 2015
 - 2016 MY vehicles with Hardware Version 2 did not have AEB enabled initially



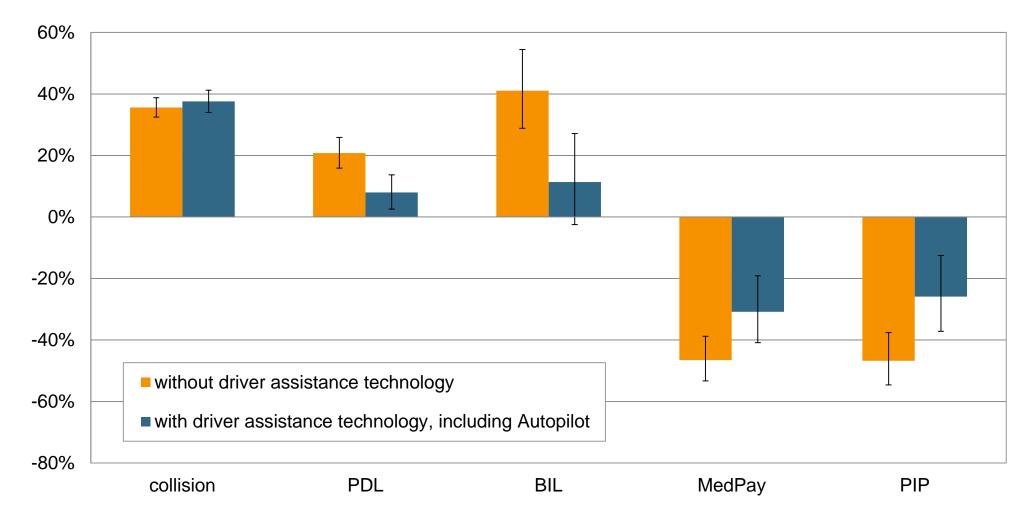
Driver assistance technology enabled by Hardware Version 1

- Version 6.1 (January 2015)
 - Traffic-aware cruise control, forward collision warning, automatic high beams
- Version 6.2 (March 2015)
 - -Automatic emergency braking, blind spot warning
- Version 7.0 (October 2015)
 - -Autopark, Autosteer (enabling Tesla Autopilot), automated lane change, side collision avoidance
- Version 7.1 (January 2016)
 - Summon, perpendicular Autopark



Tesla Model S claim frequencies with and without driver assistance technology versus large luxury vehicles

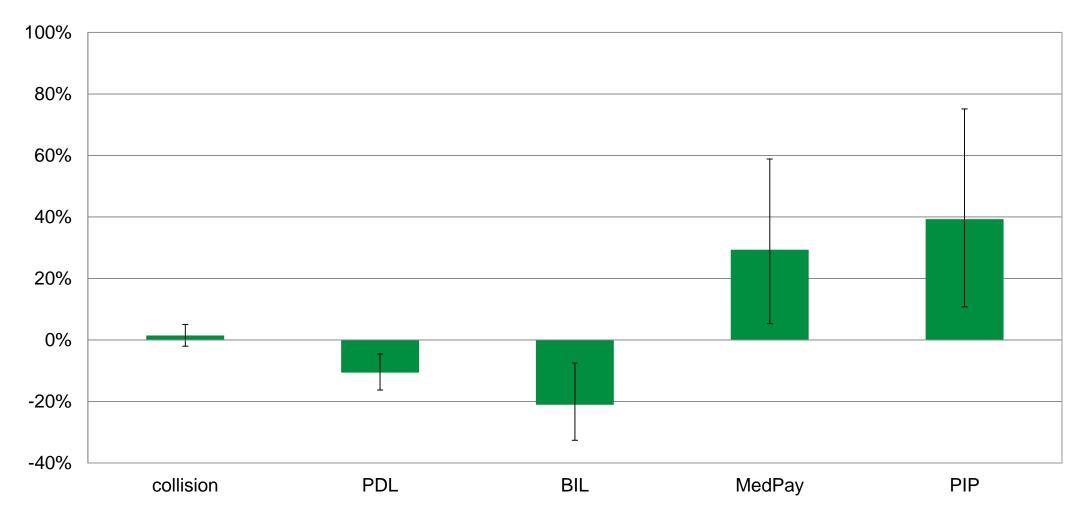
Effect of driver assistance technology, including Autopilot





Estimated effect of Tesla Model S driver assistance technology enabled by Hardware Version 1 on claim frequency

Effect of driver assistance technology, including Autopilot





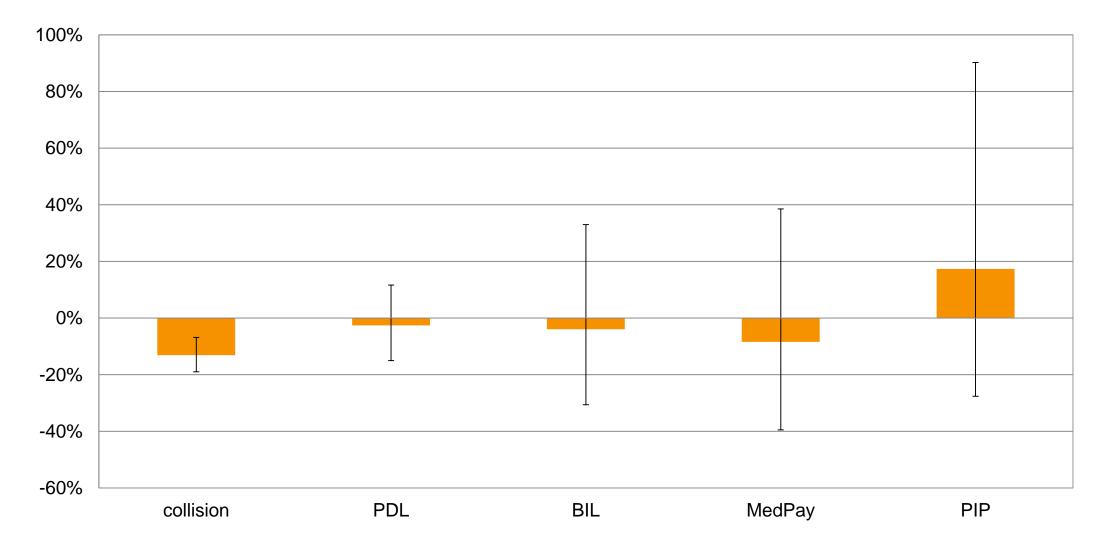
Estimated incremental effect of Tesla Model S Autopilot system Methods

- Assume that all Tesla Model S with Hardware Version 1 had Autopilot enabled after the software version 7.0 update in October, 2015
- Exclude loss experience for Tesla Model S without driver assistance technology
- Use "difference-in-differences" approach to compare the loss experience of Tesla Model S vehicles with and without Autopilot enabled to large luxury vehicles of the same age
- Note that the vehicles with Autopilot also had following features enabled during the same period and their effect is included:
 - Autopark
 - Automated lane change
 - Side collision avoidance
 - Perpendicular Autopark
 - Summon



Estimated effect of Tesla Model S Autopilot on claim frequency

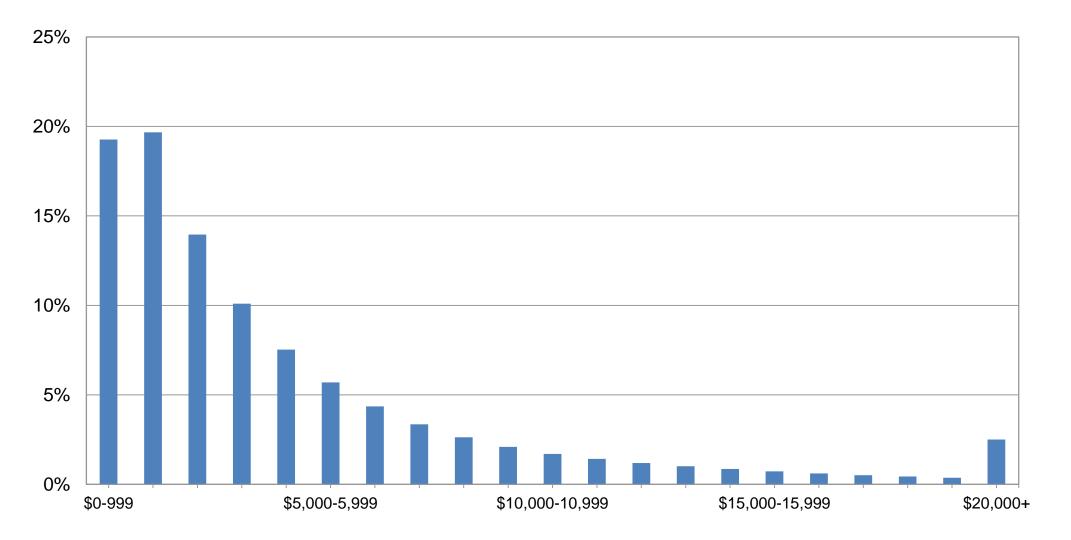
Driver assistance technology plus Autopilot vs. early driver assistance technology alone



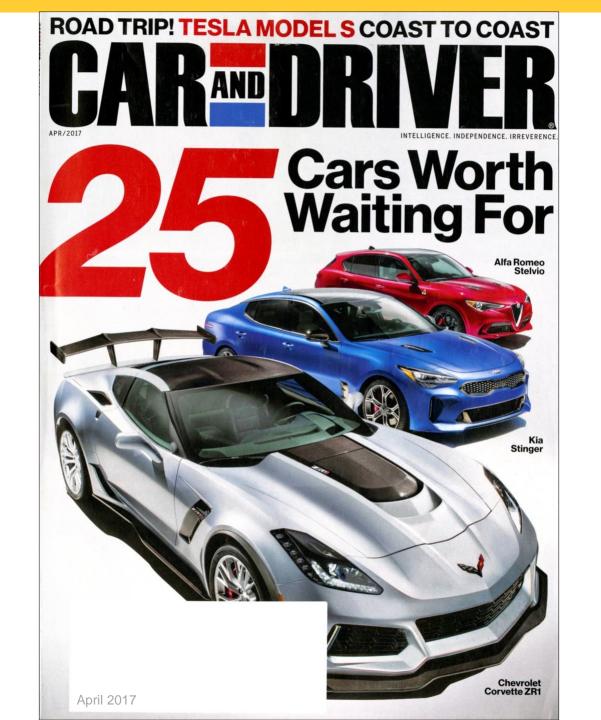


Distribution of collision claims, 2016 calendar year

By claim size, 1981-2017 models









Model S effortlessly covered our staff's dayto-day demands with plenty of juice to spare. It wasn't off-limits to staffers with long commutes, nor did we ever feel uneasy taking the car for a weekend, when charging was less convenient or assured. There's good reason newer EVs are targeting the 200-mile threshold that Tesla cracked.

We charged at our office every weekday. initially using a 240-volt, 40-amp circuit that required more than 10 hours to replenish the depleted pack. We soon upgraded to a 100-amp line that could push 58 miles' worth of electricity into the car every hour. Those who charge overnight at home can make do with 30- or 40-amp circuits, but we became convinced some form of 240-volt service is required for Tesla ownership, especially in cold-weather climates. Over the course of a 20-degree weekend with minimal charging, one editor saw 13.4 miles of driving range disappear to warming the battery, heating the cabin, and reduced efficiency. Our Model S rarely enjoyed the warmth of a garage, whether it was plugged in or not, which would have increased the vehicle's overall efficiency and reduced the



winter range losses we experienced. The quiet, smooth Model S is a prolific

ered 3647 miles in four days, spending 57 Rants & Raves hours behind the wheel and another 15 hours, 22 minutes plugged in (not including

Time certainly made our Tesla smarter. A software update in October 2015 enabled Autopilot, which combines adaptive cruise control, a self-steering lane-keeping program, and automated lane changes (activated by triggering the turn signal). Autopilot can cover scores of highway miles without driver involvement, and yet it occasionally yanked suddenly and alarmingly – at the steering wheel when it lost the scent of lane markers, causing the vehicle to swerve out of its lane.

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The 21-inch black

abeels wore summe

tires. The silver 19s

wore all-seasons of

a nuclear reactor, but the onboard batteries can only send enough power to generate 463 ponies. While correcting the record didn't make the Model S any slower, Tesla's own software did. In January 2017, Tesla admitted that its software limits maximum output after a car exceeds a predetermined number of launches and hard accelerations in order to protect the powertrain. We have no doubt that our adolescent drivers crossed that threshold. The company also said it will remove this protection with the next software update, probably to ward off lawsuits as much as to appease customers. Between its initial and final performance tests, our P85D slowed from a 3.3-second zero-to-60mph sprint to 3.7 seconds. The quarter-mile stretched another half-second beyond the first run of 11.8 seconds. Time certainly made our Tesla smarter.

A software update in October 2015 enabled

July 28, 2016 0 31,018 miles: Car bent: replace worn front tires, \$805 trucked to Tasia's Cleveland service center ust 17, 2016 where they replace the O 32.287 miles: driver's front lower raighten one front control arm to address a wheel and learn that the clutking noise and clean other is damaged beyond out the surroof drain lines to stop the leaving that persists, \$0 gust 25, 2016 O 32,698 miles: Driver's seat replaced at our

August 8, 2016 O 31,387 miles: Discover office \$0 both front wheels are

Marriell.

335110

Autopilot, which combines adaptive cruise control, a self-steering lane-keeping program, and automated lane changes (activated by triggering the turn signal). Autopilot can cover scores of highway miles without driver involvement, and yet it occasionally yankedsuddenly and alarmingly-at the steering wheel when it lost the scent of lane markers, causing the vehicle to swerve out of its lane.

Tesla's blind-spot monitor relies on the ultrasonic sensors that most automakers use only as parking-lot spotters. CEO Elon Musk says Tesla prefers this approach because, compared with the radarbased alternative, the sensors work at lower speeds and better detect "soft" objects, such as humans. But ultrasonic sensors have less range than radar, so they can't spot a fast-closing car in the next lane. That makes the automatic lane change a dicey proposition. New Teslas wear eight cameras that provide a 360-degree view around the car, upgrading their lane-changing capabilities.

While the instrument cluster implores the driver to keep their hands on the wheel during Autopilot use, the system's seeming competence easily lulls you into false confidence and dumb behavior such as texting or, in the case of our drivers, writing notes in the car's logbook. There's no doubt that Tesla's Autopilot is more capable than the nervous, lawyer-handicapped systems offered by every other automaker, but it's far from finished. Autopilot's inability to handle all scenarios was highlighted in the May 2016 fatal accident in which a Model S operating on Autopilot broadsided a semi-trailer that crossed the Tesla's path.

We've been promised that EVs will reduce operating costs, but Tesla's service prices don't reflect its vehicles' simplicity. The 12,500-mile maintenance stop involves replacing the cabin air

HOW TO TRAVEL FAST AND EAT WELL IN A TESLA

The Model S's enthedded trip planner keeps a conservative store of electricity in reserve and favors frequent but short charging. As we crossed middle America, the nav system recommended stopping at almost every Supercharger along our route. But because the charging rate slows as the battery fills found it quicker to ignore Tesla's recommendations, drive the car to near empty, and plug it in for only slightly longer charges. Our routine: Drive between 120 and 200 miles at roughly 5 mph over the speed limit, charge for 20 to 45 minutes to a predicted range 50 miles greater than what was needed for the next stint, then get back on the road. We typically arrived at the subsequent stop with 20 to 30 miles of remaining range, although uphill stints caused us to slash our speed or tuck in behind semis or couple occasions. Starting with 247 miles of range and climbing a little more than 1000 feet over 190 miles into Weatherford, Oklahoma, we rolled to the plug with just two miles of indicated range.

Traveling in this manner requires some advanced planning to know which chargers to visit and which to bypass. We used Google Maps and plugged in our chosen charging stops knowing that we wouldn't risk a run longer than 200 miles.

In hindsight, we would have added one preplanning task: Noting the nearby amenities that are listed on Tesla's Supercharger web page. You can't

escape mediocre megachain dining along the Supercharger network, but you can prevent the disappointment of pulling up to a charger at din ner time only to discover that it's located at a socluded hotel. And even the best-planned trip requires a good pair of walking shoes. It often takes a decent hike-semetimes across lawns. through landscaping berms, or along busy roads-to refuel the passengers. -ET

O Service ranger also

delivers a new front wheel, \$1188

Sectomber 27, 2008

O 34,174 miles; Repair

rock chip in windshield

34 549 miles: Cit

rebrieved by the Cleve

and service center to

eddress a clunking from

suspension. Technicians

mbar 16, 2016

replace the right-front anti-roll-bar end link and the chrome tailgate trim. which is allowing water in the tailights, \$0 cember 5, 2016

TOTAL COSTS MAINTENANCE \$1188 40,000 miles: Model S NORMAL WEAR \$805 In shes its long term REPAIR DAMAGE AND DESTRUCTION \$3180 FLECTRICITY (@ \$0.13 PER KWH) SERVICE DEALER VISITS (SCHEDULED/UNSCHEDULED) ... 2/5 DAYS OUT OF SERVICE





074 LONG-TERM TEST . CAR AND DRIVER . APR/2017

101215

\$0

Experiences with driving automation

IIHS HLDI

Opinions of level 2 driving automation technology after brief use

- 17-20 employees drove each vehicle on a 20-mile route while using level 2 driving automation the entire drive
- Completed a survey about their experience after the drive



2017 BMW 5 series with "Driving Assistant Plus"



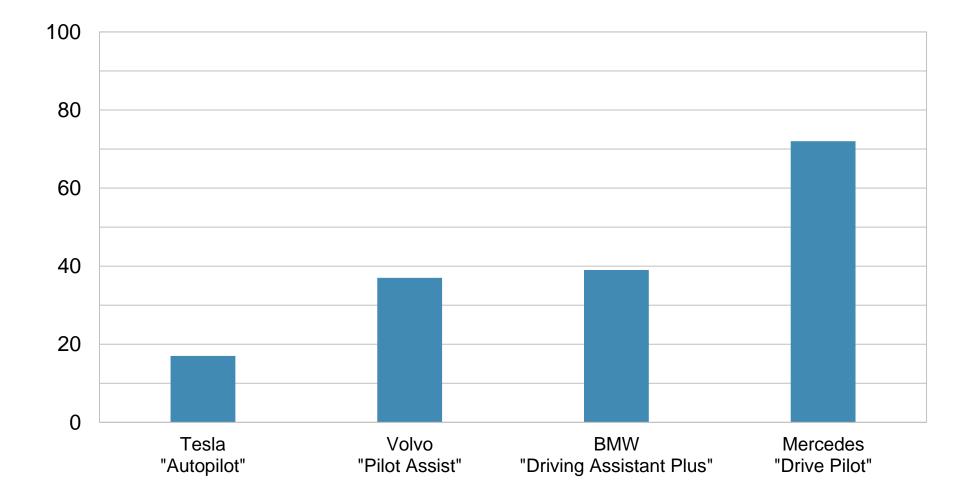
2017 Mercedes E-Class with "Drive Pilot"

2016 Tesla Model S with "Autopilot"

2018 Volvo S90 with "Pilot Assist"



Overall, I felt the automation improved my driving experience





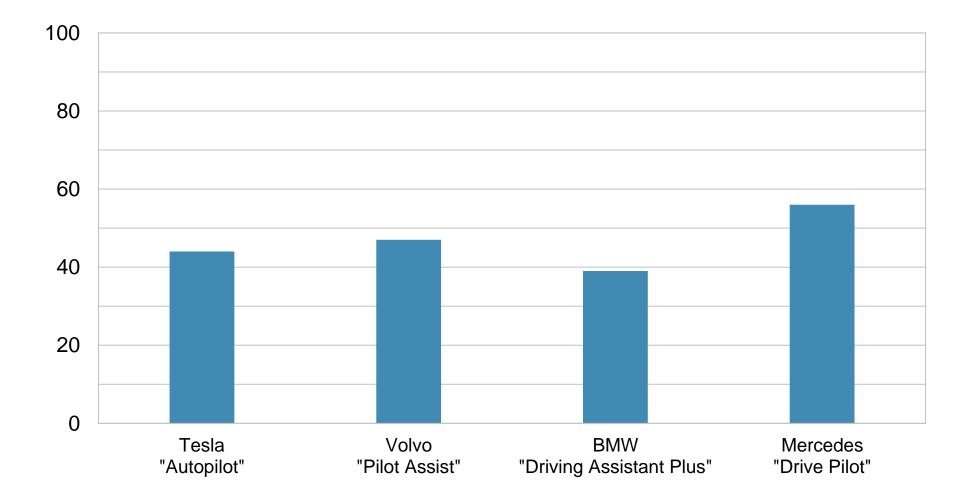
What did drivers think the systems did well and poorly?

Drivers reported their level of agreement with statements about the automation:

- -Accelerated and decelerated the vehicle smoothly
- Made smooth, gentle steering corrections
- Made infrequent steering corrections
- -Always knew whether the vehicle ahead was detected
- -Always knew whether the lane markings were detected
- Consistently detected lane markings
- Detected moving vehicles ahead
- Detected stopped vehicles ahead

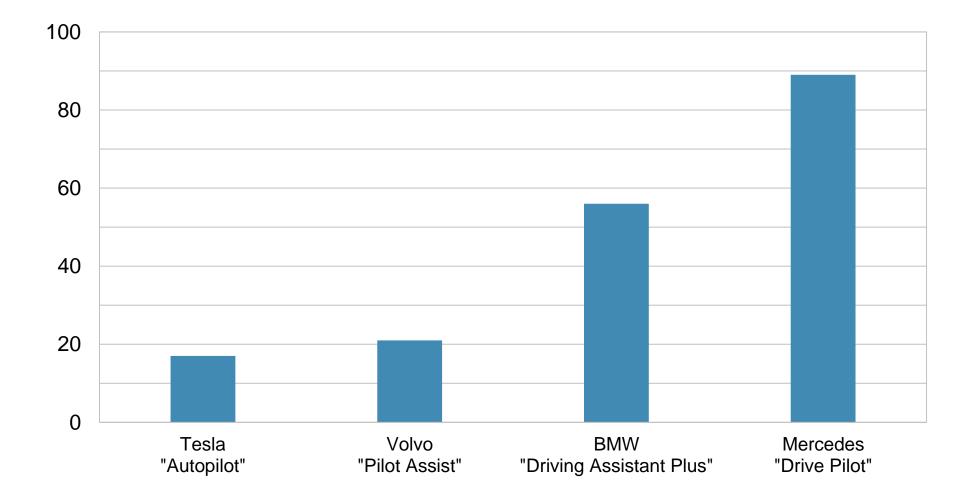


The automation detected stopped vehicles ahead in my lane



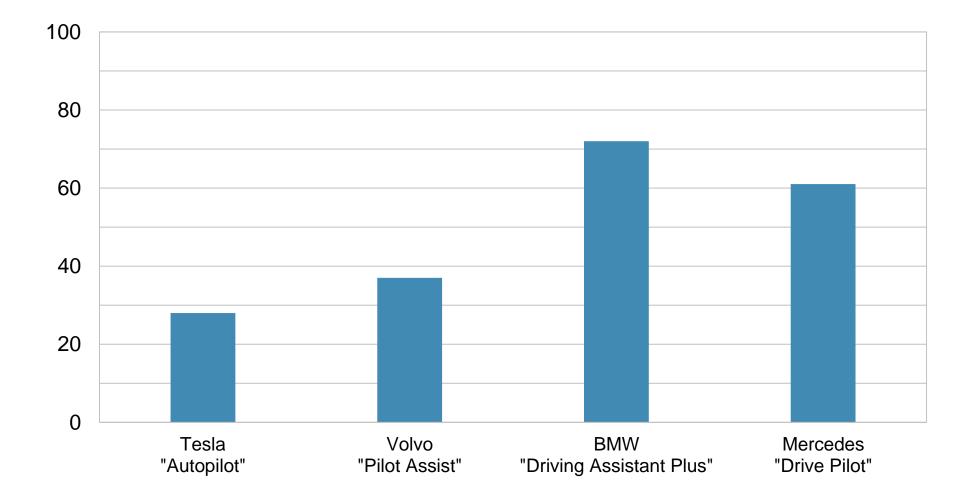


The automation made smooth, gentle steering corrections



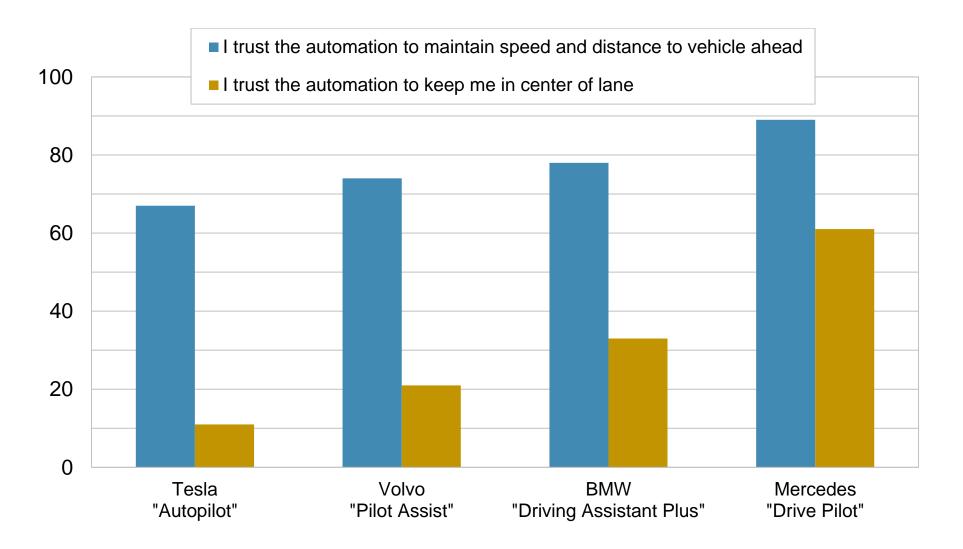


The automation made steering corrections infrequently





Adaptive cruise control trusted more than active lane keeping





Functional performance of adaptive cruise control and active lane-keeping systems

Functional performance testing of adaptive cruise control and lane-keeping systems

- Combination of track and on-road tests designed to discriminate differences seen in our driver experience study
- Scenarios based on driver experience study
 - Adaptive cruise control

stopped lead vehicle, vehicle exiting lane, acceleration/deceleration profiles

-Active lane keeping

lane tracking, steady-state lane position, curve handling and hill capability



2017 BMW 5 series with "Driving Assistant Plus"



2017 Mercedes E-Class with "Drive Pilot"



2016 Tesla Model S with "Autopilot"



2017 Volvo XC90 with "Pilot Assist"



Approach stationary target with ACC on





ACC acceleration from stop



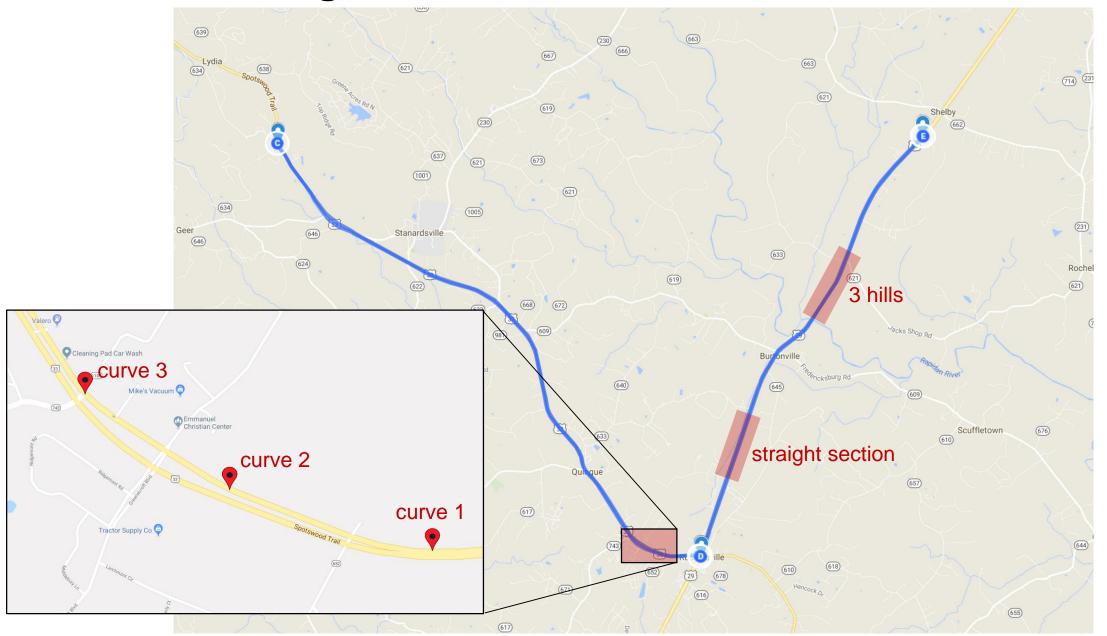


Revealed stationary vehicle





On-road testing





Lane keeping in curves - Tesla





Lane keeping in curves - BMW





Lane keeping on hills - Mercedes





Lane keeping on hills - Volvo





SAE Level 4 / Level 5 Systems

II**HS** HLDI

Uber Strikes Deal With Volvo to Bring Self-Driving Cars to Its Network

CNET, December 4, 2017

Nissan Begins Public Robo-taxi Trials Next Year

The Verge, December 6, 2017

Lyft is Now Offering Self-driving Car Trips in Boston

Wired, April 4, 2017

Mercedes promises self-driving taxis in just three years

CleanTechnica, November 11, 2017

Self-driving taxi service from Waymo set to begin shortly

Wall Street Journal, November 30, 2017

GM Aims for Self-Driving Taxi Fleet by 2019

Industry Week, December 6, 2017

Final Countdown: Nissan Introducing Fully Autonomous Cars in 2022

CarAdvice, December 4, 2017

BMW autonomous vehicles coming in 2021



How do experimental self-driving vehicles compare to human drivers?

IIHS

Google self-driving car program

2009-present

- Testing on public roads in Mountain View, Calif., and later expanded to Austin, Texas; Kirkland, Wash.; and metro Phoenix, Ariz.
- Self-driving technology includes detailed mapping, variety of sensors and advanced software
- Designed to operate free of active driver control in most situations
- Testing monitored by Google employees who will take over vehicle control when necessary



modified Toyota Prius

modified Lexus RX450h

Google prototype low-speed vehicle



Two studies comparing Google-car to human drivers

Two different conclusions

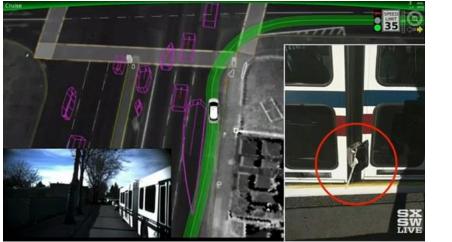
- University of Michigan Transportation Research Institute
 - Used estimates of underreporting to police to inflate General Estimates System crash count estimates
 - Found Google-car crash rate was higher than humans
- Virginia Tech Transportation Institute
 - Compared safety-related events in naturalistic driving studies to incidents reported by Google to California
 - -Found Google-car had lower rate of such incidents than humans

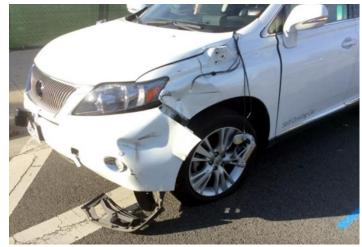


Crash involvements in autonomous operation

2009 – August 31, 2016

- 19 crash incidents reported by Google
 - 9 deemed possibly police-reportable by IIHS
 - 12 where the Google car was stopped or traveling < 2 mph
 - 2 involved contact with only the side mirror
- Crash rates and types were compared with those of conventionally-driven passenger vehicles

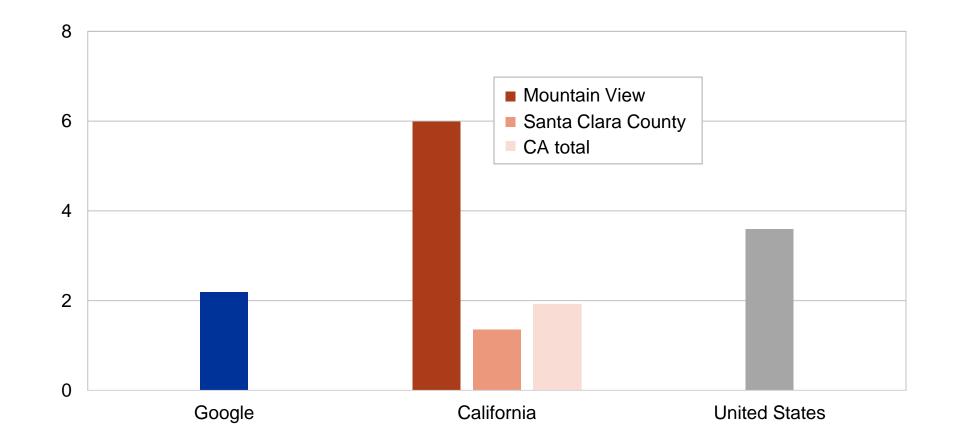






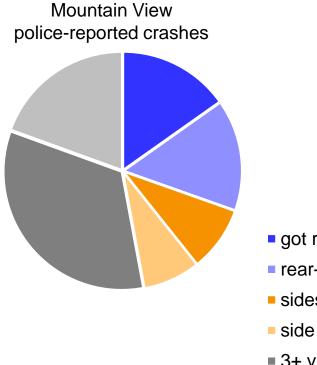
Police-reportable crashes per million vehicle miles traveled

2009-15

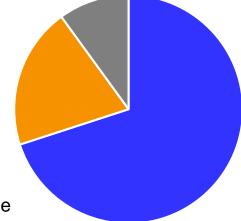




Crash types 2009-15







- got rear-ended
- rear-ended other vehicle
- sideswipe
- side impact
- 3+ vehicles
- single vehicle

Google car rear-ended by another vehicle that was also rear-ended * Includes all incidents, not just those possibly police-reportable

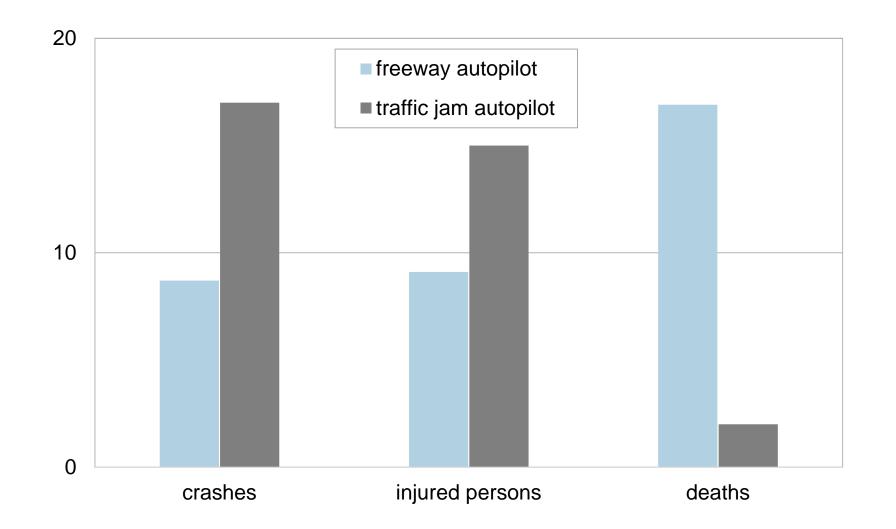


What crash reductions can we expect from limited automated driving systems?

II<mark>H</mark>S

Crash prevention potential of two domain restricted automated driving systems

Percent of crashes





What if NYC Taxicabs were replaced by robo-taxis that didn't crash?

2015

- ▶ 13,587 in operation
- > 13,282 crashes
- 0.98 crashes/cab/year
- 5 fatal crashes





- Assuming crash rates similar to Google car
 - 8,400 crashes prevented
 - About 3 fatal crashes prevented
- 29 taxicabs in fatal crashes in the U.S. in 2015



Automated driving system policy and legislation

Policy and legislation will not collect data to evaluate SAE level 3 and higher automated driving systems



115тн CONGRESS Ist Session	H. R. 3388
Received: read twice and referred to the	IN THE SENATE OF THE UNITED STATES SEPTEMBER 7, 2017 e Committee on Commerce, Science, and Transportation
	ANACT
	de, regarding the authority of the National Highway Traffic Safety Administration over highly automated sures for such vehicles, and for other purposes.
Be it enacted by the Senate an	d House of Representatives of the United States of America in Congress assembled,
SECTION 1 SHOPT TITLE, T	RI E OF CONTENTS

(a) SHORT TITLE.—This Act may be cited as the "Safely Ensuring Lives Future Deployment and Research In Vehicle Evolution Act" or the "SELF DRIVE Act".

September 28, 2017

July 25, 2017

115th CONGRESS 1st Session

S. 1885

To support the development of highly automated vehicle safety technologies, and for other purposes.

IN THE SENATE OF THE UNITED STATES

September 28, 2017

Mr. THUNE (for himself, Mr. PETERS, Mr. BLUNT, and Ms. STABENOW) introduced the following bill; which was read twice and referred to the Committee on Commerce, Science, and Transportation

A BILL

To support the development of highly automated vehicle safety technologies, and for other purposes.

Be it enacted by the Senate and House of Representatives of the United States of America in Congress assembled,

SECTION 1. SHORT TITLE; TABLE OF CONTENTS.

(a) SHORT TITLE.—This Act may be cited as the "American Vision for Safer Transportation through Advancement of Revolutionary Technologies Act" or the "AV START Act".



Public VIN database would support safety assessments



- IIHS and HLDI linked crash and exposure data using VINs supplied by OEMs
- Database at a minimum would include:
 - VINs of vehicles with SAE level 3 or higher systems
 - -Level of automation of each equipped system
 - Operational Design Domain of each equipped system
 - Exemptions from Federal Motor Vehicle Safety Standards
- VIN would be submitted at time of manufacture



States, law enforcement and insurers would benefit

VIN-indexed database would support:

- Motor vehicle registration
- Vehicle safety inspection
- Crash reporting and investigation
- Insurance underwriting and claim processing
- More robust database would include:
 - -Level 2 driving automation systems by VIN
 - Crash avoidance technologies by VIN
 - Marketing names of crash avoidance and automation technologies
 - -Current software version of each technology and software version history



Event data recorders would help determine the role of automation in a crash



- Event data recorders are not required only the data elements they must record
- Required data elements do not include information about crash avoidance or driving automation systems
- IIHS developed a list of data elements to describe the status of crash avoidance and automation in a crash



Event and exposure data are critical for understanding whether new vehicle technology improves safety

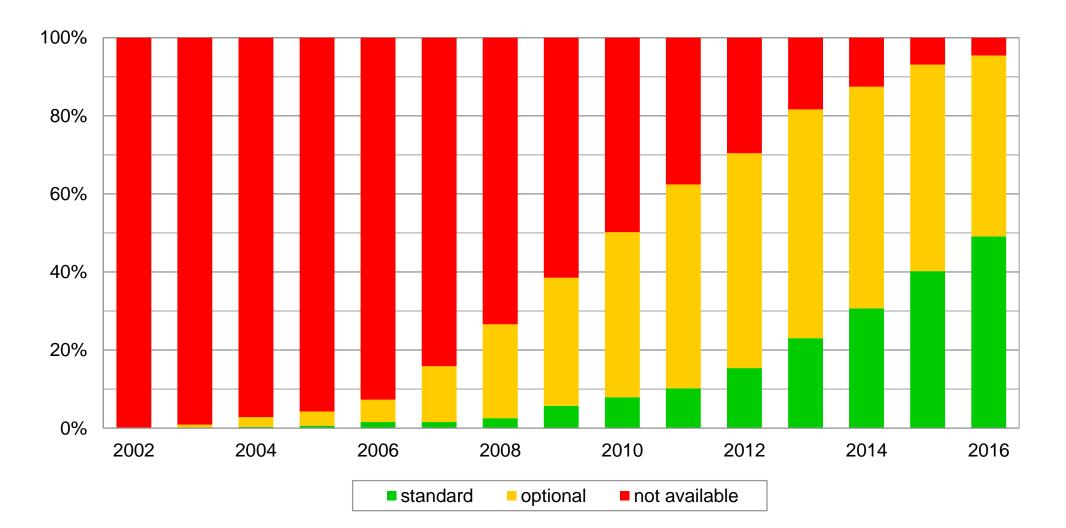
- Measuring the effect of a vehicle feature on safety requires:
 - -Knowing how the feature works and under what conditions
 - Identifying vehicles with and without the feature
- Information about the feature's status in a crash improves precision
- NHTSA voluntary guidance and proposed congressional legislation will gather incomplete information for assessing the real-world safety of automation
- Public database listing vehicles with automated driving systems by VIN will support proven methods for measuring safety benefits



Phase in of collision avoidance systems

New vehicle series with rear camera

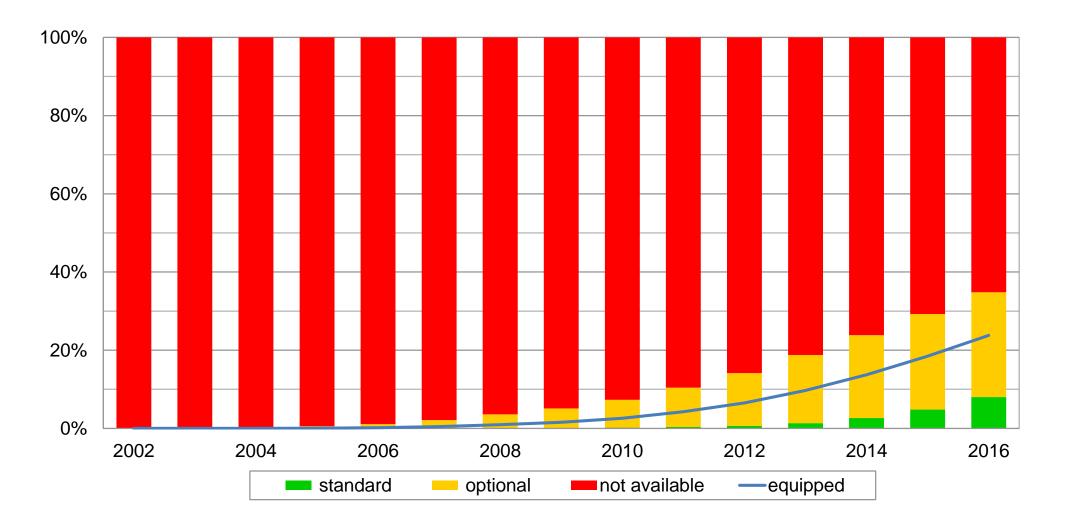
By model year





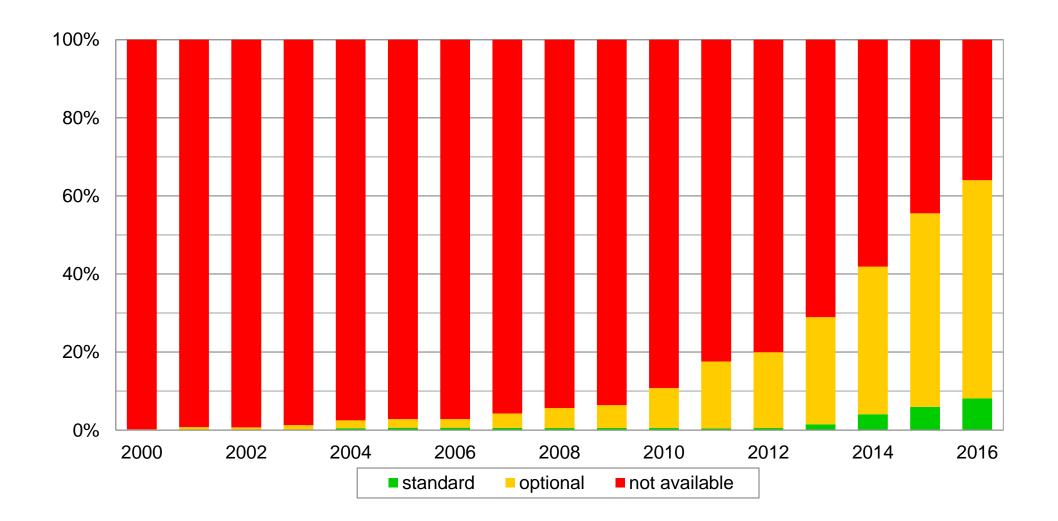
Registered vehicles with rear camera

By calendar year



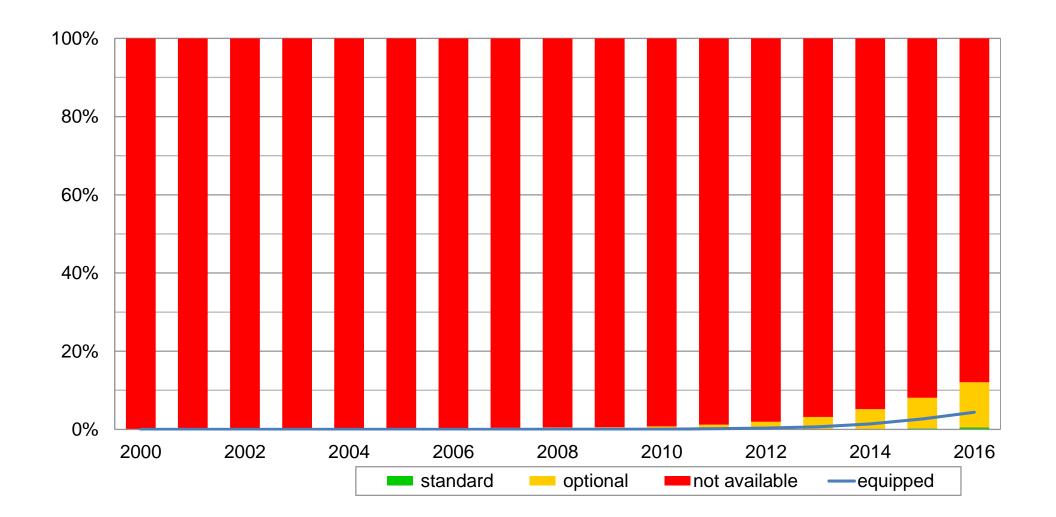


New vehicle series with forward collision warning By model year



Registered vehicles with forward collision warning

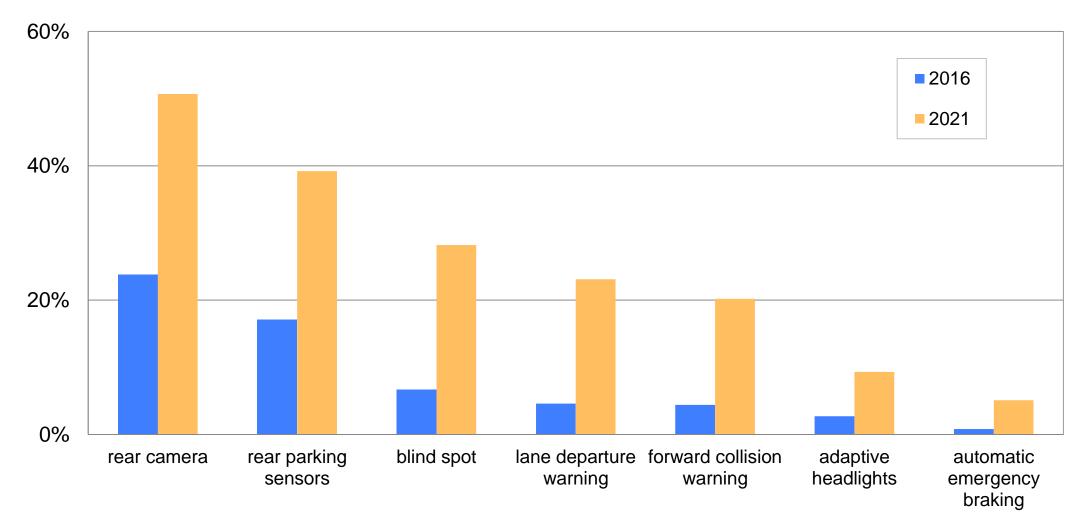
By calendar year





Estimated registered vehicles by feature

Calendar years 2016 and 2021







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