CUMULANTS OF CONVOLUTION—MIXED DISTRIBUTIONS

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1. CONVOLUTION—MIXED DISTRIBUTIONS

Consider a risk process which is characterised by three stochastic variables

- (1) the number of accidents, N,
- (2) the number of claims per accident, C, and
- (3) the amount of a claim, X.

Let Y be a random variable denoting the total loss in a given period. Suppose that

$$p_n = \text{Prob}(N = n)$$
 $n = 0, 1, 2...$ and

$$v_c = \text{Prob}(C = c \mid \text{an accident has occurred}) \quad c = 1, 2, 3...$$

If P_r represents the probability that exactly r claims occur in the period, then Kupper [4] has shown on certain simplifying assumptions that

$$P_r = \sum_{n=0}^{\infty} p_n v_r^{\bullet n} \tag{I}$$

where $v_r^{\bullet n}$, the probability of exactly r claims in n accidents, is given by

$$v_r^{*n} = \sum_{c=n-1}^{r-1} v_c^{*(n-1)} v_{r-c} \qquad \text{for } r \geqslant n, \ n = 1, 2, 3....$$
 and $v_r^{*n} = 0 \quad \text{for } r < n$

Further

$$v_r^{*1} = v_r$$
 $v_r^{*0} = I$ for $r = 0$
and $v_r^{*0} = 0$ for $r \neq 0$

Suppose that

$$F(x) = \text{Prob } (Y \le x)$$

and $S(x) = \text{Prob } (X \le x)$

The total loss can be expressed on certain simplifying assumptions by the well known formula

$$F(x) = \sum_{r=1}^{\infty} P_r S^{*r}(x)$$
 (2)

where $S^{\bullet r}(x)$, the $r^{\bullet h}$ convolution of the distribution function S(x), is given by

$$S^{\bullet r}(x) = \int_{0}^{x} S^{\bullet (r-1)}(x-z)dS(z)$$
 for $r = 1, 2, 3...$
 $S^{\bullet 1}(x) = \int_{0}^{x} S^{\bullet (r-1)}(x-z)dS(z)$ for $r = 1, 2, 3...$
 $S^{\bullet 0}(x) = \int_{0}^{x} S^{\bullet (r-1)}(x-z)dS(z)$ for $r = 1, 2, 3...$

Combining equations (1) and (2) together we obtain

$$F(x) = \sum_{r=0}^{\infty} \sum_{n=0}^{\infty} p_n v_r^{*n} S^{*r}(x)$$
$$= \sum_{r=0}^{\infty} \sum_{r=0}^{\infty} p_n v_r^{*n} S^{*r}(x)$$

if we interchange the order of summation

Auxiliary Functions Associated with Probability Distributions

There are several useful auxiliary functions associated with a distribution function F(x) of the random variable Y (see [3])

(1) Probability generating function

$$G_Y(z) = E_Y(z^x) = \int_0^\infty z^x dF(x)$$
 (z real, positive)

(2) Moment generating function

$$M_Y(u) = E_Y(e^{ux}) = \int_{-\infty}^{\infty} e^{ux} dF(x)$$
 (u real)

(3) Characteristic function

$$\phi_Y(t) = E_Y(e^{itx}) = \int_0^\infty e^{itx} dF(x)$$
 (t real)

(4) Cumulant generating function

$$K_{Y}(u) = \log M_{Y}(u)$$

Provided the various integrals exist we can change from one auxiiary function to another by the transformations

For instance
$$\begin{aligned} u &= it = \log z \\ G_Y(e^u) &= M_Y(u) \\ M_Y(it) &= \log M_Y(it) \\ &= \log \phi_Y(t) \end{aligned}$$

The Application of Generating Functions to Convolution—Mixed Distributions

We depend heavily on the following well-known (see [3])

Lemma

If X_1, X_2, \ldots, X_n are independent and identically distributed random variables

and
$$Z = X_1 + X_2 + \dots + X_n$$
then
$$G_Z(u) = [G_X(u)]^n$$

Now from equation (3) we have

$$G_{Y}(z) = \sum_{n=0}^{\infty} \sum_{r=0}^{\infty} p_{n} v_{r}^{*n} S^{*r}(x) z^{x}$$

$$= \sum_{n=0}^{\infty} \sum_{r=0}^{\infty} p_{n} v_{r}^{*n} G_{X_{1}+X_{2}+....X_{r}^{*n}}$$

$$= \sum_{n=0}^{\infty} \sum_{r=0}^{\infty} p_{n} v_{r}^{*n} [G_{X}(z)]^{r}$$

$$= \sum_{n=0}^{\infty} p_{n} G_{C_{1}+C_{2}+....+C_{n}} (G_{X}(z))$$

$$= \sum_{n=0}^{\infty} p_{n} [G_{C}(G_{X}(z))]$$

$$= G_{N}(G_{C}(G_{X}(z)))$$

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Thyrion [5] has introduced a very wide class of distributions, the distributions in a bunch (m=2), and in a bunch of bunches (m>2), defined by generating functions in the following general form

$$G_Y(z) = G_1(G_2(G_3, \ldots, G_{m-1}(G_m(z)) \ldots))$$
 $m \geqslant 2$

where $G_j(z)$ are probability generating functions of integer valued variables, j = 1 to (m-1), and $G_m(z)$ is any probability generating function.

A special case where the G_j , j=1 to m are all identical, occurs in the theory of branching processes, where Y is the size of the m^{th} generation. The principal result of this paper is contained in the following theorem, which is a generalisation of a known result in the theory of branching processes (see [2]).

Theorem

If
$$G_Y(z) = G_N(G_C(G_X(z)))$$
 then $K_Y(n) = K_N(K_C(K_X(u)))$ (4)

Proof

Let $u = \log z$ then $M_Y(u) = G_Y(z)$ $= G_N(G_C(G_X(z)))$ $= G_N(G_C(M_X(u)))$ $= G_N(G_C(M_X(u)))$ $= G_N(G_C(K_X(u)))$ $= G_N(M_C(K_X(u)))$ $= G_N(M_C(K_X(u)))$ so that $K_Y(u) = K_N(K_C(K_X(u)))$ as required

This theorem can obviously be extended to include the distributions, a bunch of bunches. By differentiating the cumulant generating function and setting u = o we can obtain the cumulants of a distribution. Using an obvious notation we can derive the following relationships between the cumulants of a low order from equation (4).

$$\mathsf{x}_{1Y} = \mathsf{x}_{1N} \, \mathsf{x}_{1C} \, \mathsf{x}_{1X} \tag{5}$$

$$x_{2Y} = x_{2N} x_{1C}^2 x_{1X}^2 + x_{1N} x_{2C} x_{1X}^2 + x_{1N} x_{1C} x_{2X}$$
 (6)

$$\mathbf{x}_{3Y} = \mathbf{x}_{3N} \mathbf{x}_{1C}^{3} \mathbf{x}_{1X}^{3} + 3\mathbf{x}_{2N} \mathbf{x}_{1C} \mathbf{x}_{2C} \mathbf{x}_{1X}^{3} + 3\mathbf{x}_{2N} \mathbf{x}_{1C} \mathbf{x}_{2X} \mathbf{x}_{1X}
+ \mathbf{x}_{1N} \mathbf{x}_{3C} \mathbf{x}_{1X}^{3} + 3\mathbf{x}_{1N} \mathbf{x}_{2C} \mathbf{x}_{2X} \mathbf{x}_{1X} + \mathbf{x}_{1N} \mathbf{x}_{1C} \mathbf{x}_{3X} \tag{7}$$

$$\begin{aligned}
\mathbf{x}_{4Y} &= \mathbf{x}_{4N} \, \mathbf{x}_{1C}^{4} \, \mathbf{x}_{1X}^{4} + 6\mathbf{x}_{3N} \, \mathbf{x}_{2C} \, \mathbf{x}_{1C}^{2} \, \mathbf{x}_{1X}^{4} + 6\mathbf{x}_{3N} \, \mathbf{x}_{1C}^{3} \, \mathbf{x}_{2X} \, \mathbf{x}_{1X}^{2} \\
&+ 4\mathbf{x}_{2N} \, \mathbf{x}_{3C} \, \mathbf{x}_{1C} \, \mathbf{x}_{1X}^{4} + 3\mathbf{x}_{2N} \, \mathbf{x}_{2C}^{2} \, \mathbf{x}_{1X}^{4} + 18\mathbf{x}_{2N} \, \mathbf{x}_{2C} \, \mathbf{x}_{1C} \, \mathbf{x}_{2X} \, \mathbf{x}_{1X}^{2} \\
&+ 4\mathbf{x}_{2N} \, \mathbf{x}_{1C}^{2} \, \mathbf{x}_{3X} \, \mathbf{x}_{1X} + 3\mathbf{x}_{2N} \, \mathbf{x}_{1C}^{2} \, \mathbf{x}_{2X}^{2} \\
&+ \mathbf{x}_{1N} \, \mathbf{x}_{4C} \, \mathbf{x}_{1X}^{4} + 6\mathbf{x}_{1N} \, \mathbf{x}_{3C} \, \mathbf{x}_{2X} \, \mathbf{x}_{1X}^{2} + 4\mathbf{x}_{1N} \, \mathbf{x}_{2C} \, \mathbf{x}_{3X} \, \mathbf{x}_{1X} \\
&+ 3\mathbf{x}_{1N} \, \mathbf{x}_{2C} \, \mathbf{x}_{2X}^{2} + \mathbf{x}_{1N} \, \mathbf{x}_{1C} \, \mathbf{x}_{4X}
\end{aligned} \tag{8}$$

These formulae, given in equations (5)-(8) can be used in the normal power expansion [1]

$$F(x) = \Phi(y)$$

where $\Phi(y)$ is the cumulative Normal distribution and

$$\frac{x - x_{1Y}}{(x_{2Y})^{1/2}} = y + \frac{x_{3Y}}{6(x_{2Y})^{3/2}} (y^2 - 1) + \frac{x_{4Y}}{24x_{2Y}^2} (y^3 - 3y) + \frac{x_{3Y}^2}{36x_{2Y}^3} (2y^3 - 5y) + \dots$$
 (9)

In particular if the number of accidents, N, has a Poisson distribution with expected value λt , where λ is a constant, then the cumulants

$$x_{jN} = \lambda t$$
 for all $j > 0$

It follows that

$$\kappa_{jY} = o(t)$$
 for all $j > o$

which is all that is required to establish the validity of the asymptotic expansion (9) for large values of t.

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