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Dave Clark Diana Rangelova Munich Reinsurance America, Inc.

CLRS – September 2019



# Agenda



- Introduction
- Visualization of Multidimensional Data
- Clustering Methods Applied to Overlapping Groups
- Outliers and Noise
- Practical Considerations

#### Introduction What is Clustering?

- > A cluster is a group of similar objects
- Clustering is an unsupervised learning technique: No need to define the groups in advance
- It is essential to assess the usefulness and meaning of the identified groups

Munich RE



Hubble Spies Glittering Star Cluster in Nearby Galaxy



Source: https://www.nasa.gov Image Credit: ESA/Hubble & NASA

### Introduction Publications on Clustering

Cluster Analysis has grown rapidly, especially as computer software has become more readily available





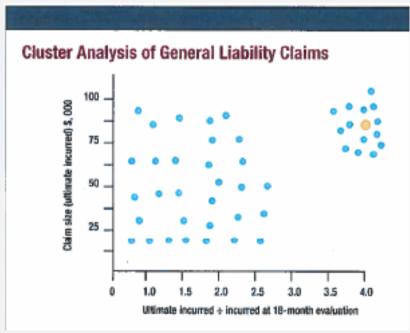


#### Introduction Why Clustering?

- > What questions could be answered with cluster analysis?
  - Exploratory analysis
  - Test the data homogeneity
  - Find a benchmark
- What kind of data can be clustered?
  - Segments, contracts, claims...
  - Counties, regions...
  - Loss development patterns, loss ratios, severity, frequency, etc.

#### Introduction What Does Reserving Data Look Like?

### Text book example



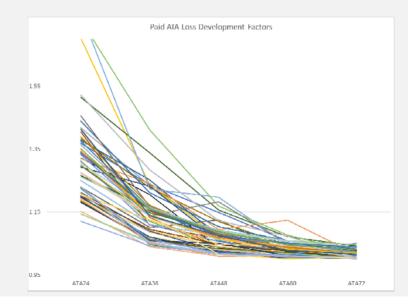
Source: Associates in Data Analytics (AIDA) 181 textbook

- One or two dimensions
- No outliers
- Distinct clusters



#### Introduction What Does Reserving Data Look Like?

- Real data example
  - Multidimensional observations
  - Overlapping clusters
  - Outliers and noise are present



- > Schedule P Example:
  - CAS Schedule P data for Loss Reserving [10]
  - 3 lines: CAL, PPAL,WC
  - 20 observations per line
  - Each observation represents a company

|      | r aiu i |      | 133 DE V | eiohiii | ent rat | ,1015 |
|------|---------|------|----------|---------|---------|-------|
| Line | 12      | 24   | 36       | 48      | 60      | 72    |
| CAL  | 1.87    | 1.32 | 1.20     | 1.04    | 1.04    | 1.01  |
| CAL  | 1.99    | 1.42 | 1.23     | 1.08    | 1.03    | 1.02  |
|      |         |      |          | •       |         |       |
| PPAL | 2.26    | 1.21 | 1.07     | 1.02    | 1.01    | 1.00  |
| PPAL | 1.78    | 1.20 | 1.06     | 1.04    | 1.02    | 1.01  |
|      |         |      | ••       | •       |         |       |
| WC   | 2.22    | 1.34 | 1.16     | 1.09    | 1.06    | 1.05  |
| WC   | 2.47    | 1.44 | 1.21     | 1.10    | 1.06    | 1.03  |
|      |         |      | ••       | •       |         |       |

#### **Paid ATA Loss Development Factors**



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# Agenda

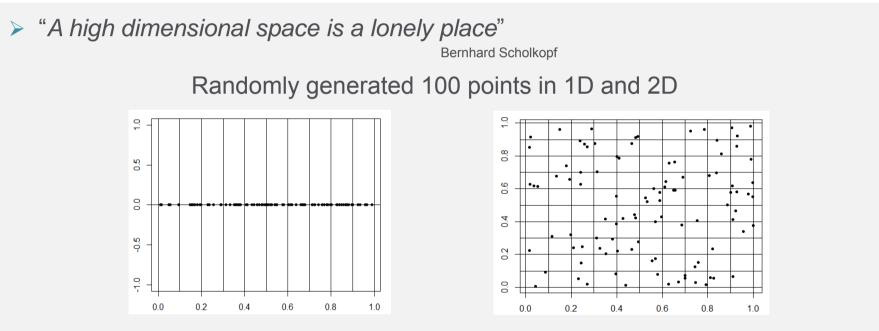


# > Introduction

- Visualization of Multidimensional Data
  - Statistical Challenge
  - Why it is Important to Visualize Data
  - Dimension Reduction Techniques
- Clustering Methods Applied to Overlapping Groups
- Dealing with Outliers and Noise
- Practical Considerations



#### Visualization Statistical Challenge



"…Thus, it is often said, "in high dimensional spaces, distances between points become relatively uniform." In such cases, the notion of the nearest neighbor of a point is meaningless…." [8]

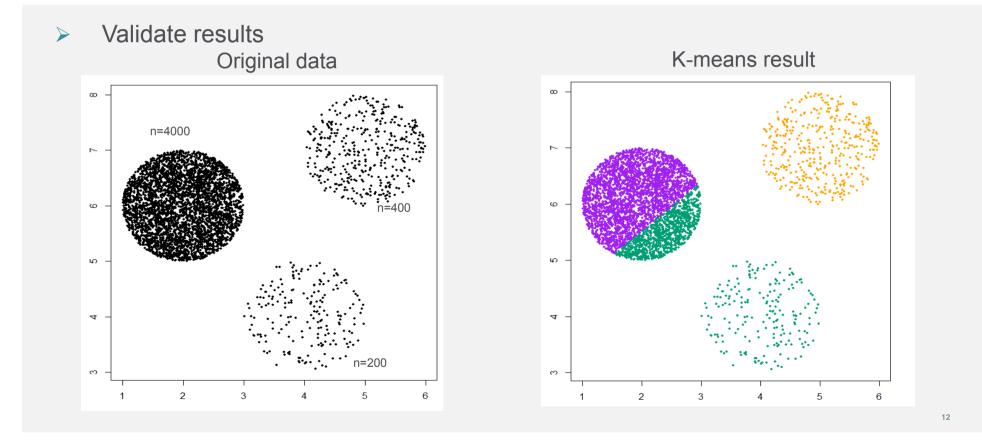


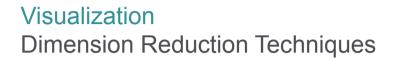
Visualization Why Is It Important to Visualize Data?

- > Choose the most appropriate clustering model for your data
  - Are the clusters spherical? (K-means)
  - Are the clusters overlapping? (Fuzzy clustering, Gaussian Mixture Models)
  - Noise points (Density-based clustering)
  - Select the number of clusters
- Explain clusters and communicate results

### Visualization Why Is It Important to Visualize Data?







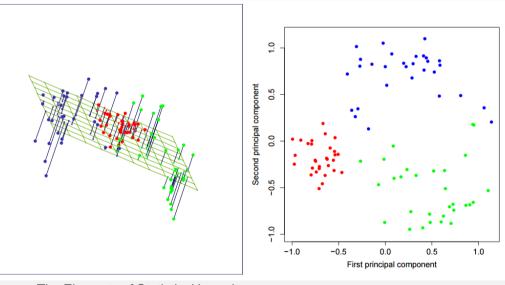


- Principal Component Analysis (PCA)
- Data Transformation (Curve Fitting)



# PCA Principal Component Analysis

PCA stretches and rotates data with the goal to derive the best possible k-dimensional representation of the Euclidean distance among objects.



Source: The Elements of Statistical Learning



# PCA Principal Component Analysis

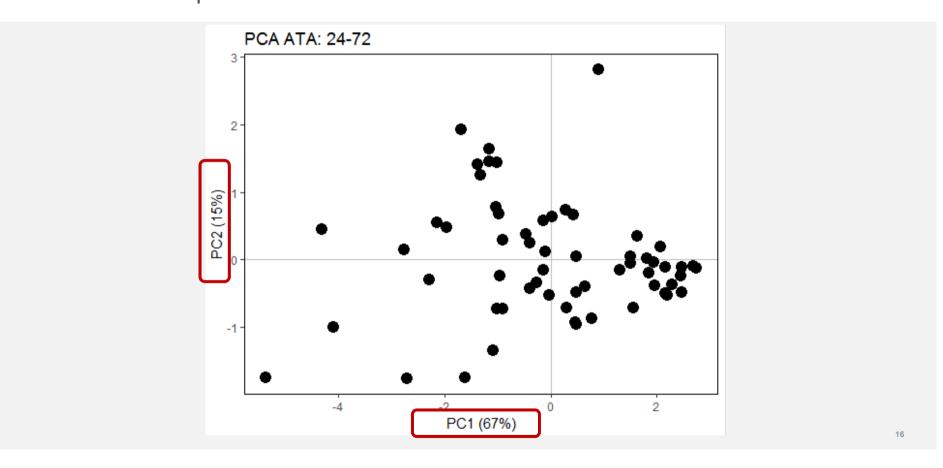
Think about viewing a galaxy from "above" rather than the side: what angle do we want in order to get the most understanding of the "shape" of the galaxy?



*Source:* <u>https://www.nasa.gov/feature/goddard/2017/a-new-angle-on-two-spiral-galaxies-for-hubbles-27th-birthday:</u> Credits: NASA, ESA, and M. Mutchler (STScI)

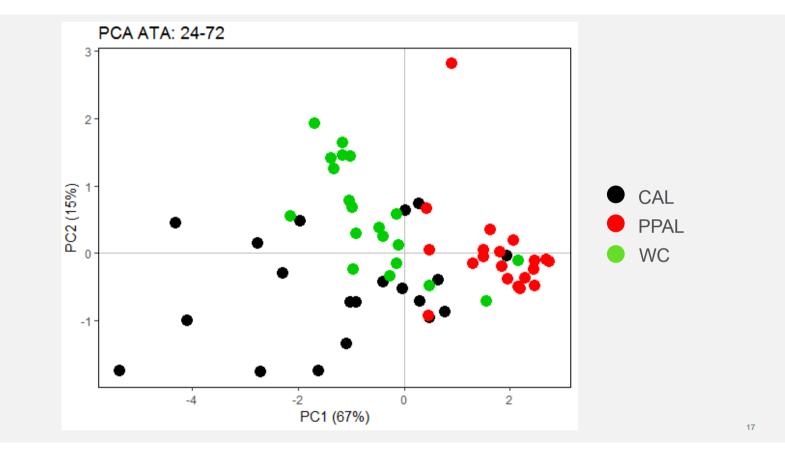


PCA Schedule P example: Visualization



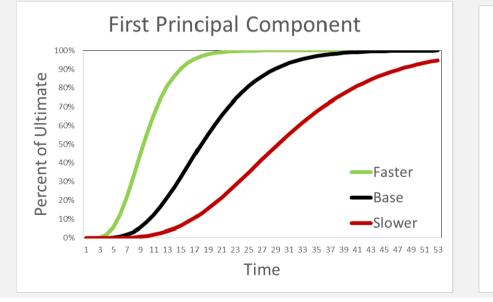


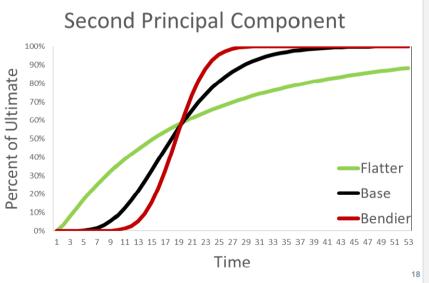
PCA Schedule P example: Visualization - LOB



#### PCA Interpretation

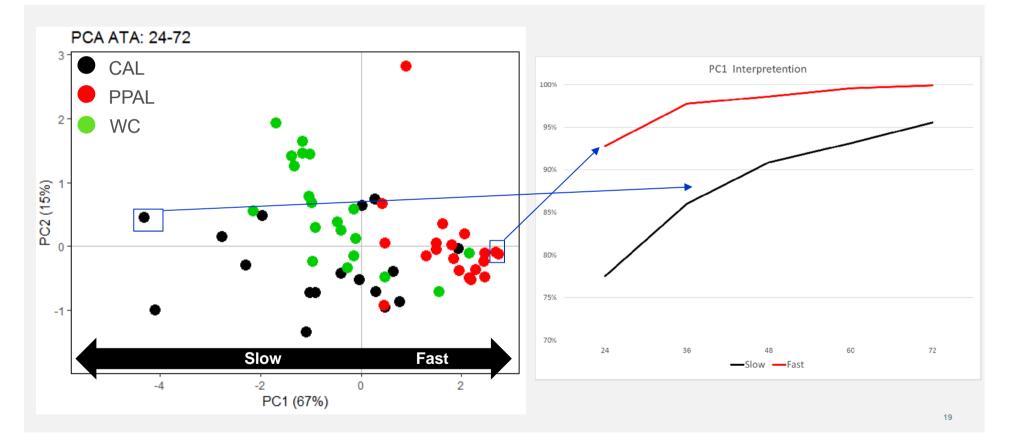
- > PCA provides an opportunity for interpretation
  - PC1 captures the mean loss development
  - PC2 indicates a change in the loss curve shape





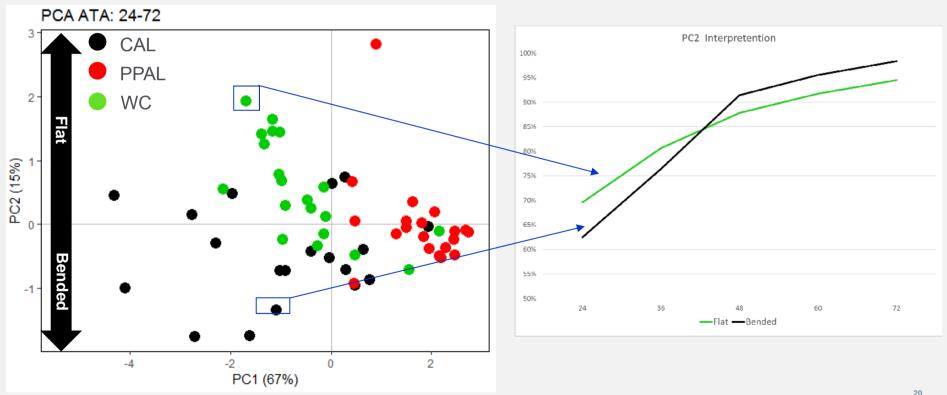


# PCA PC1 Interpretation

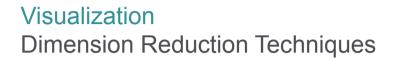


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# PCA PC2 Interpretation







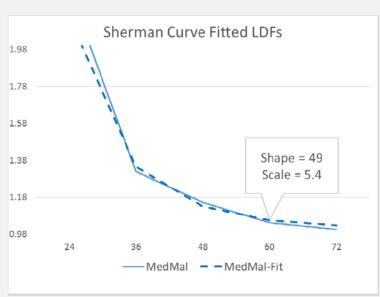


- Principal Component Analysis (PCA)
- Data Transformation (Curve Fitting)

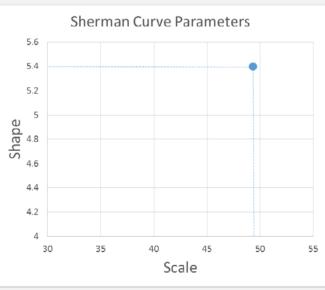


#### Data Transformation Sherman Curve

> Sherman proposed a curve that fits to the typical LDF pattern



$$ATA_t = 1 + \left(\frac{Scale}{t+c}\right)^{Shape}$$



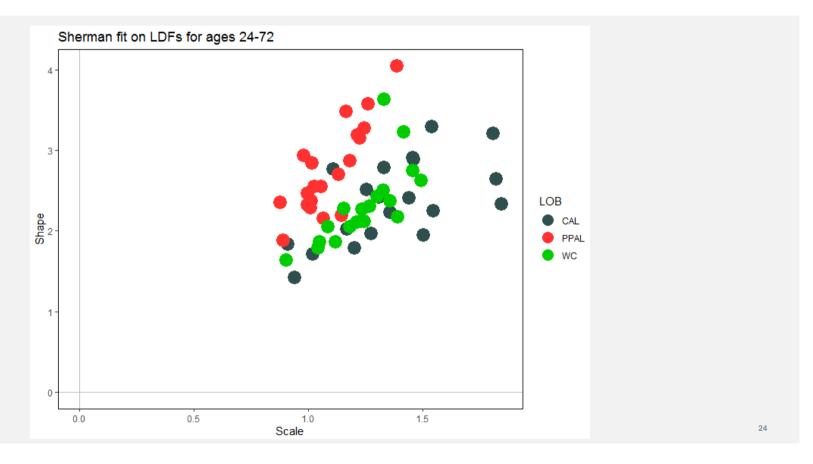




- > Sherman recommends estimating the parameters by using log-linear regression
  - All actual age-to-age factors must be strictly greater than 1
  - Fitting a logged value rather than actual amounts
- > GLM to the rescue!
  - Apply GLM with log-link on actual data



### Data Transformation Schedule P example



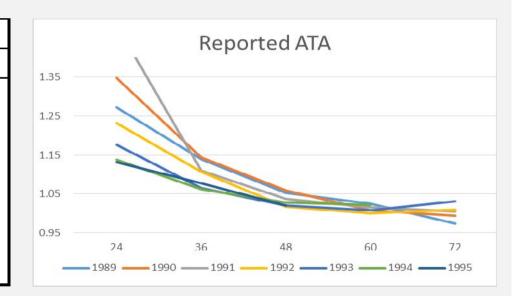


#### Data Transformation Pros & Cons

- > Allows comparison of loss development patterns of different sizes
- Does not work well for flat curves
- > The focus is on the fit, not on maintaining the distances between points

### Data Transformation Another Schedule P Example

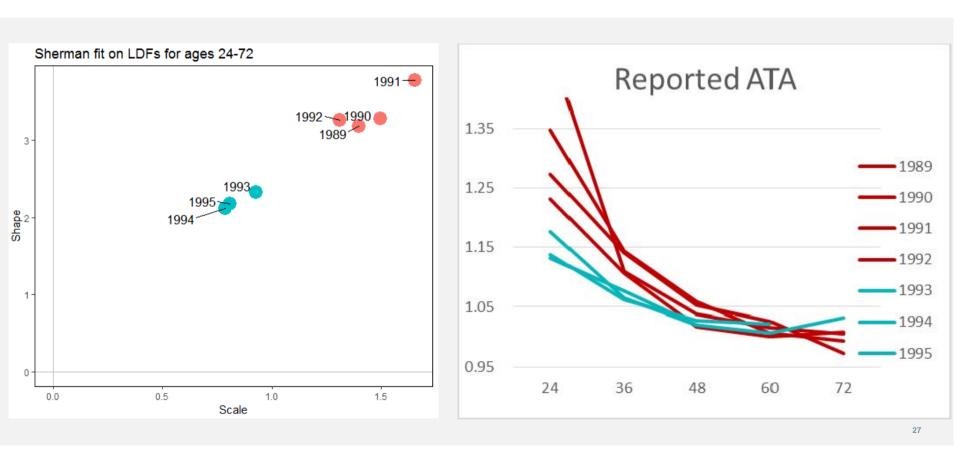
|      | Reported ATA |      |      |      |      |
|------|--------------|------|------|------|------|
|      | 24           | 36   | 48   | 60   | 72   |
| 1989 | 1.27         | 1.14 | 1.05 | 1.03 | 0.97 |
| 1990 | 1.35         | 1.14 | 1.06 | 1.01 | 0.99 |
| 1991 | 1.48         | 1.11 | 1.04 | 1.02 | 1.01 |
| 1992 | 1.23         | 1.11 | 1.02 | 1.00 | 1.01 |
| 1993 | 1.18         | 1.06 | 1.02 | 1.01 | 1.03 |
| 1994 | 1.14         | 1.06 | 1.03 | 1.02 |      |
| 1995 | 1.13         | 1.08 | 1.02 |      |      |



Source: CAS Schedule P Reported LDF - CAL



#### Data Transformation Another Schedule P Example





# Agenda

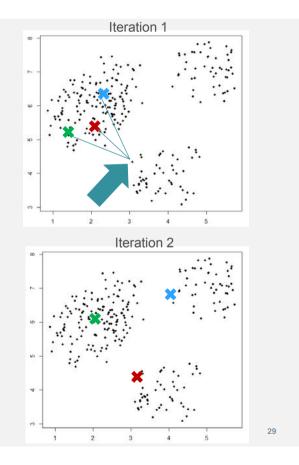


- Introduction
- Visualization
- Clustering Methods Applied to Overlapping Groups
  - K-means
  - Fuzzy Clustering
  - Gaussian Models
- Dealing with Outliers and Noise
- Practical considerations

#### Clustering Methods Applied to Overlapping Groups K-means

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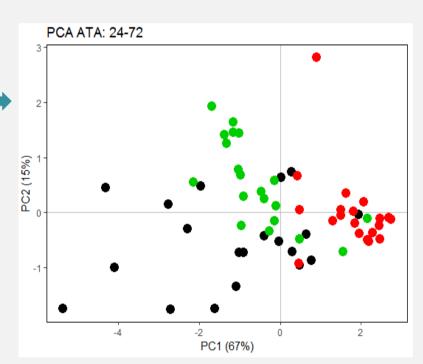
- ➢ K-means is simple, fast and efficient
- How does K-means work?
  - Initiate the centroids
  - Assign points to the closest centroid
  - Recalculate new centroid
  - Iterate until no point left to be reassigned
- In R, use kmeans() from package "stats"



Clustering Methods Applied to Overlapping Groups K-means



- K-means does not perform well when:
  - There are no natural distinct clusters —
  - Clusters are of different size
  - Clusters are not roughly spherical
  - Outliers exist



Clustering Methods Applied to Overlapping Groups Fuzzy Clustering: Schedule P Example

- Soft (a.k.a. fuzzy) clustering allows each data point to belong to more than one cluster
- Membership grades are assigned to each data point
- Results are obtained using R function fanny() from the package "cluster"

| LOB  | Fuzzy 1 | Fuzzy 2 | Fuzzy 3 |
|------|---------|---------|---------|
| CAL  | 68%     | 18%     | 14%     |
| CAL  | 67%     | 27%     | 6%      |
| CAL  | 49%     | 37%     | 14%     |
| CAL  | 31%     | 64%     | 6%      |
|      |         | •••     |         |
| PPAL | 2%      | 1%      | 97%     |
| PPAL | 9%      | 3%      | 88%     |
| PPAL | 4%      | 2%      | 94%     |
| PPAL | 2%      | 1%      | 96%     |
|      |         |         |         |
| WC   | 16%     | 80%     | 4%      |
| WC   | 17%     | 81%     | 3%      |
| WC   | 75%     | 21%     | 4%      |
| WC   | 65%     | 31%     | 4%      |
|      |         |         |         |



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Clustering Methods Applied to Overlapping Groups Gaussian Mixture Models: Motivation



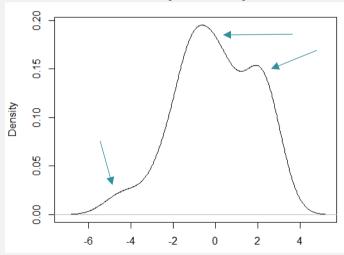
# **Probabilistic clustering:**

- Each cluster is represented by a distribution
- All observations are described by a mixture of these distributions
- Well defined mathematical structure allows for:
  - Probabilistic assignments to clusters (soft clustering)
  - o Generation of new points from a given cluster
  - Hypothesis testing
- Allows for overlapping, non-spherical clusters, and clusters with varying size
- Danger of overfitting and inappropriate distribution selection

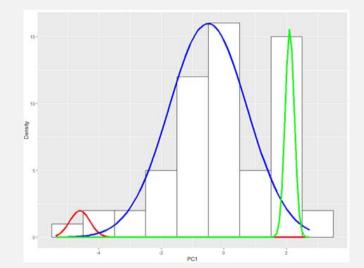
Clustering Methods Applied to Overlapping Groups Gaussian Mixture Models: PC1 Density



- > One dimensional example: using PC1 of our Schedule P example
- Fit a Gaussian distribution for each cluster



#### **First Principal Component**



Clustering Methods Applied to Overlapping Groups Gaussian Mixture Models: Schedule P Example



- GMM work well for overlapping, non-spherical clusters, and clusters with varying size
- Results were obtained using R package "*Mclust*". Multiple other options are possible (ex: mixtools, Rmixmod...)
- Bayesian Information Criterion is used to determine the number of clusters.

| LOB  | 1     | 2    | 3    |
|------|-------|------|------|
| CAL  | 93%   | 7%   | 0%   |
| CAL  | 98%   | 2%   | 0%   |
| CAL  | 0%    | 100% | 0%   |
| CAL  | 17%   | 83%  | 0%   |
| PPAL | 0%    | 0%   | 100% |
| PPAL | 0%    | 0%   | 100% |
| PPAL | 0%    | 0%   | 100% |
| PPAL | 0%    | 0%   | 100% |
| 14/0 | 0.00/ |      | 00/  |
| WC   | 98%   | 2%   | 0%   |
| WC   | 98%   | 2%   | 0%   |
| WC   | 100%  | 0%   | 0%   |
| WC   | 98%   | 2%   | 0%   |
|      |       |      |      |

# Agenda



- Introduction
- Multidimensional Data
- Clustering Methods Applied to Overlapping Groups
- Outliers and Noise
  - Recognizing outliers and noise points
  - Dealing with outliers and noise points
- Practical considerations



#### Outliers and Noise Points Recognizing Outliers and Noise points

# > Types of outliers / noise

- Points that are very different from the rest
- Points that are too small
- Erroneous points

### Recognising Outliers and Noise points:

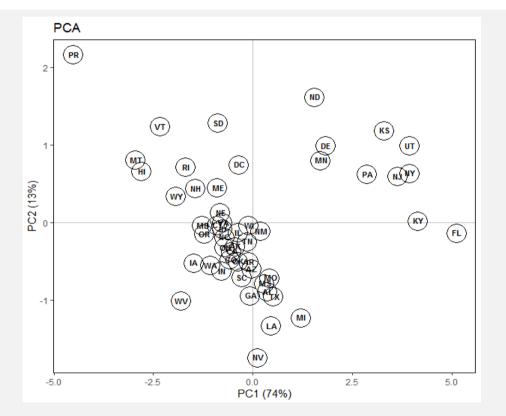
- Visualization of the data
- Increase the number of groups to detect and isolate small clusters
- Fuzzy clustering: outliers are "equally remote" to all clusters. They will have similar membership to all clusters

#### Outliers and Noise Points ISO Example

- ISO Commercial Auto patterns by State (51 obs. incl. Puerto Rico)
- Reported Loss and ALAE for AYs 2013-2017
- Percentage of Ultimate Loss centered and standardized

# How many clusters are there and what is the Explanatory Variable?







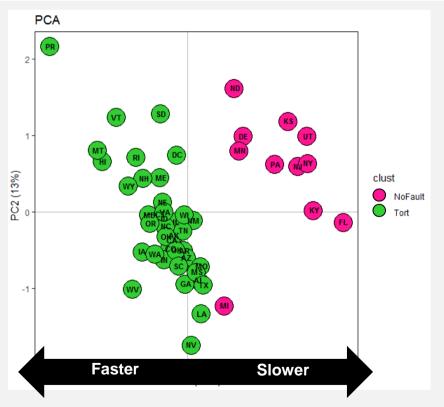
#### Outliers and Noise Points ISO Example





### Outliers and Noise Points ISO Example

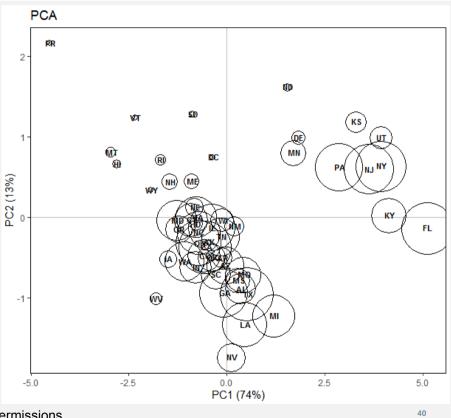
- Noticeable differences in the patterns of the states that have adopted No-Fault auto insurance laws
- Most "No-Fault" states have slower patterns



#### Outliers and Noise Points ISO Example –Weights



- The weight for each state is based on the rank of the average ultimate loss for AYs 2013-2017
- Natural clusters become even more clear



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Outliers and Noise Points Recognizing Outliers and Noise points

#### Recognising Outliers and Noise points:

- Visualization of the data
- Increase the number of groups to detect and isolate small clusters
- Fuzzy clustering: outliers are "equally remote" to all clusters. They will have similar membership to all clusters



- Outliers and Noise Points How to deal with them?
- Remove outliers before clustering
- Partial clustering algorithms that leave noise/outlier points outside the clusters (DBSCAN)
- Some methods are more robust than others when outliers are present (ex: Kmedoids)
- Clustering with weights



#### Outlier and Noise Points K-Medoids

- > Similar to K-means but uses real data points as centroids for the clusters
- K-medoids is minimizing the distance to the "median" of the cluster and this makes it more robust.
- > Its robustness is unlikely to work for:
  - Multi-dimensional space
  - > Many outliers points

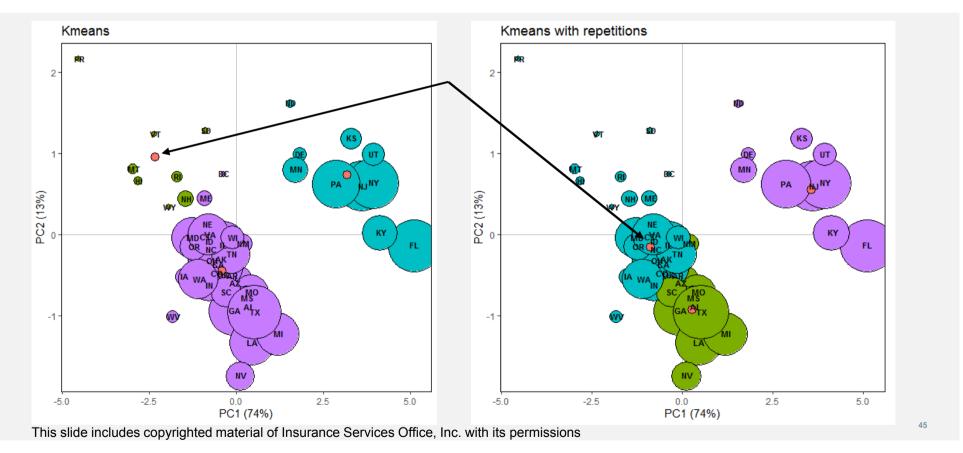


#### Outliers and Noise Points Clustering with Weights

- Easy way to introduce weights in the clustering model is to repeat several times the more important points
- ISO example: Repeat the observation based on the rank of their premium or ultimate values
  - TX is the largest of 51 observations
    =>repeat TX values 51 times
  - PR is the smallest
    - =>PR will be in the data only once



### Outlier and Noise Points Clustering with Weights



## Agenda



- Introduction
- Visualization of Multidimensional Data
- Cluster Analysis
- Dealing with Outliers and Noise
- Practical Considerations
  - Correlations between LOB
  - Identifying drivers of loss development

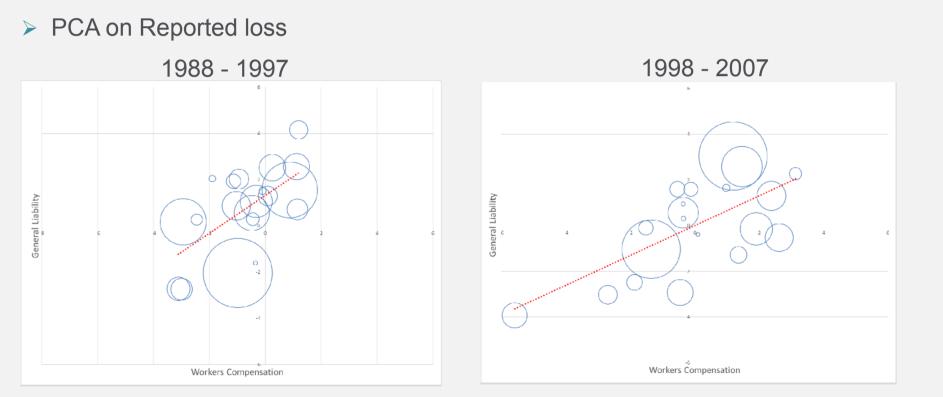


#### Practical Considerations Correlations Between Lines of Business

- Compare the first principal component for two different lines, written by the same company
- Schedule P data for loss reserving posted on the CAS website
  - 54 companies with CAL and GL lines
  - 20 companies with WC and GL lines
  - Data is from 1988 to 1997
- Check if historical dependency is preserved in more recent years

### Practical Considerations First Principal Component for WC/GL

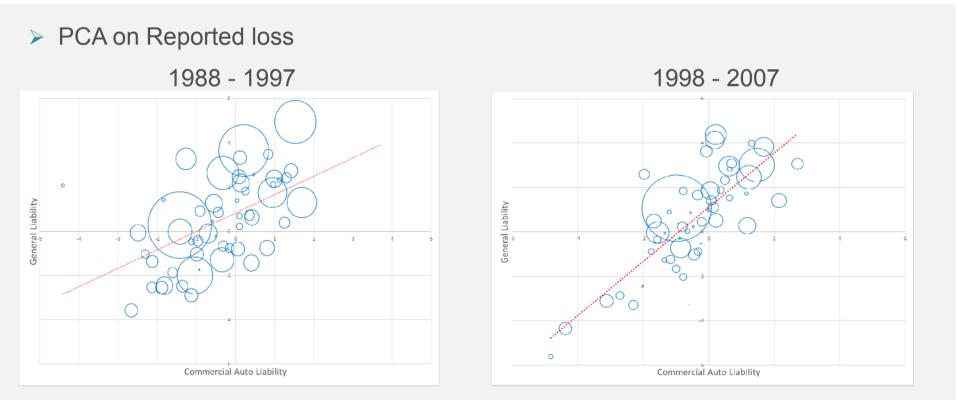




Note: bubble size corresponds to a company's average yearly premium volume

### Practical Considerations First Principal Component for CAL/GL





Note: bubble size corresponds to a company's average yearly premium volume

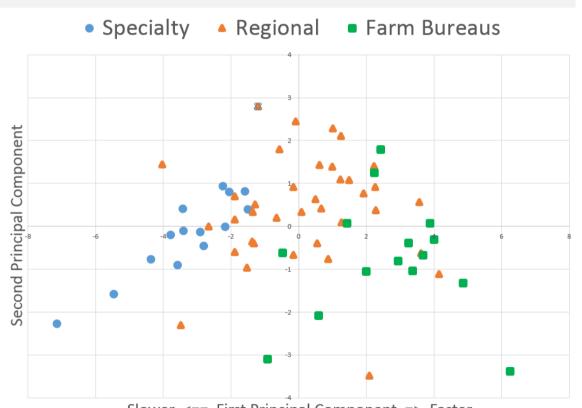
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### Practical Considerations Visualization: Finding the Right Variables

- Schedule P & SNL company profile
- GL paid development
  - 15 Farm bureaus
  - 14 Specialty
  - 37 Regional
- Loss data is from 2009 to 2019

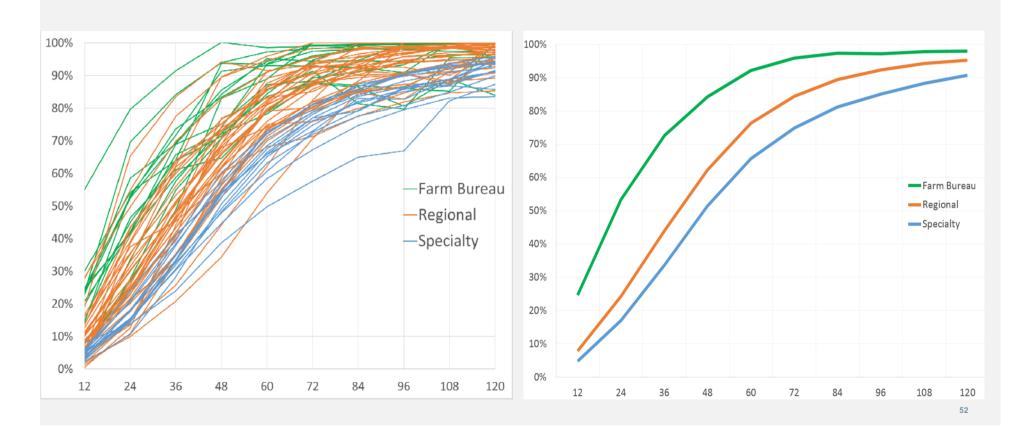


Slower <== First Principal Component => Faster



### Practical Considerations Visualization: Finding the Right Variables







#### Conclusion Key Takeaways

- Clustering techniques help us obtain a better understanding of the loss development:
  - Explore the structure of data
  - Go beyond "just" practical grouping of data
  - Identify variables impacting the development
- Each method has strengths and weaknesses
  - Look for robustness between methods

#### Selected References



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- 8. M. Steinbach, L. Ertoz, V. Kumar, **"The Challenges of Clustering High Dimensional Data"**, <u>https://www-users.cs.umn.edu/~kumar001/papers/high dim clustering 19.pdf</u>
- 9. J. VanderPlas, "Python Data Science Handbook", O'Reilly Media, <u>http://shop.oreilly.com/product/0636920034919.do</u>
- 10. CAS Schedule P data for Loss Reserving: http://www.casact.org/research/index.cfm?fa=loss reserves data



Thank you!

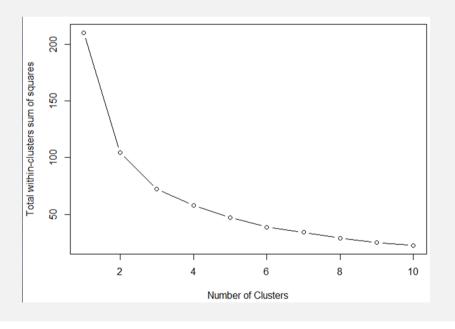
daveclark@munichreamerica.com drangelova@munichreamerica.com





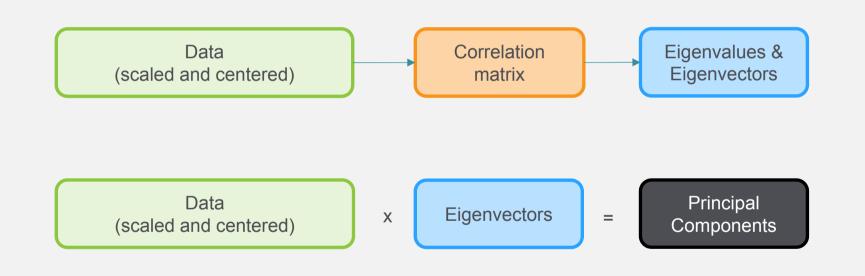
#### Cluster Analysis K-means Algorithm

- K-means partitions the data in a user-specified number of clusters (K), in which each observation belongs to the cluster with the nearest mean
- > No definitive answer for selecting K
  - Scree plot: locate the sharpest drop in within-cluster sum of squares



## PCA How to perform a PCA?





## Clustering Methods Applied to Overlapping Groups Fuzzy Clustering



- Fuzzy clustering is an iterative process that optimizes a cost function (similar to Kmeans) and at each iteration recalculates a membership function.
- > Fuzzy: min:  $\sum_{i=1}^{n} \sum_{k=1}^{c} u_{ik}^{m} d_{ik}^{2}$  where

$$\iota_{ij} = \frac{d_j^{-\frac{2}{m-1}}}{\sum_{k=1}^c d_k^{-\frac{2}{m-1}}}$$

- > K-means: min:  $\sum_{i=1}^{n} \sum_{k=1}^{c} d_{ik}^2$
- >  $d_{ik}^2$ : squared Euclidean distance
- > *m*: controls the fuzziness (m>1, m $\rightarrow$ 1 increases the crispiness of the cluster)
- >  $u_{ik}$ : membership degree of the i-th object to the k-th cluster

**Clustering Methods Applied to Overlapping Groups** Gaussian Mixture Models: The Theory

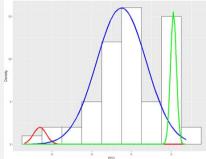
> Assume that the density of the data (y) is described by a mixture of number (g) of component densities f(y) in some unknown proportions  $(\pi)$ .

$$pdf = \sum_{i=1}^{g} \pi_i f_i(y)$$

- > For clustering, **g** will be the number of clusters
- > Calculate the posterior probability (Bayes Theorem) that an observation  $y_i$  belongs to the *i-th* component of the mixture:

$$\tau_i(y_j) = \frac{\pi_i f_i(y_j)}{f(y_j)}$$

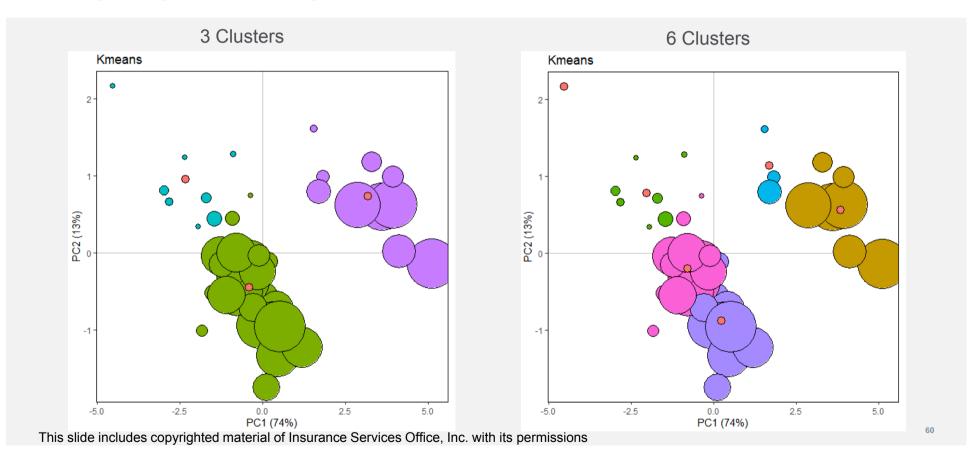
If we assume that the data in the clusters is independent and normally distributed, we can use a Gaussian Mixture Model (GMM).





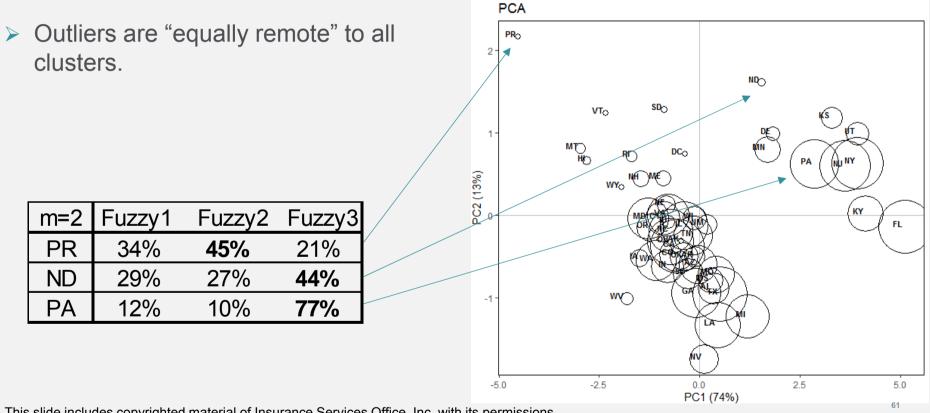
### Outliers and Noise Points Recognising Outliers: Large Number of Clusters







### **Outlier and Noise Points** Recognising Outliers: Fuzzy Clustering

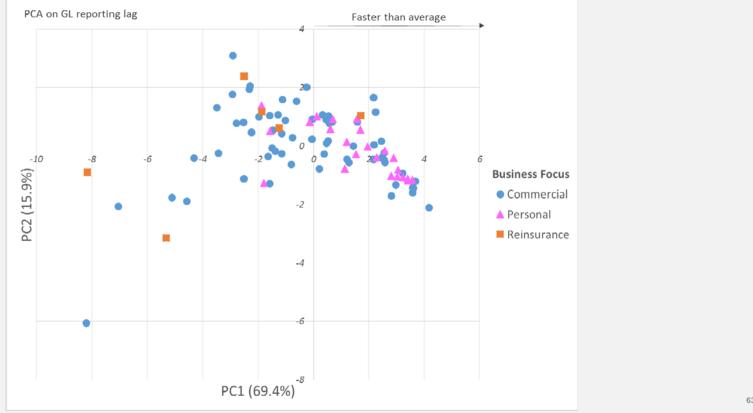


#### Practical Considerations What Are the Drivers of Loss Development?

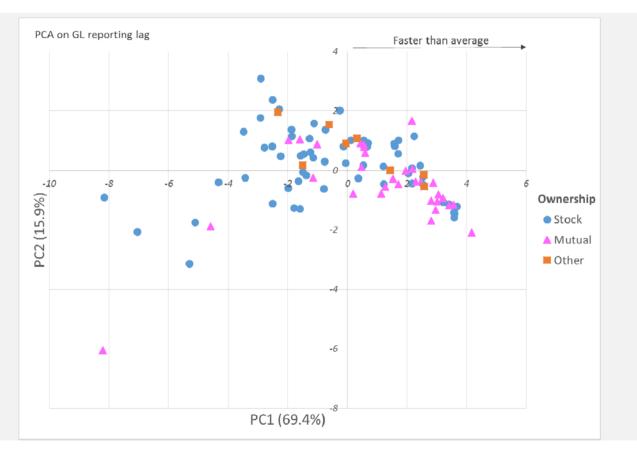
- Identify potential predictors
  - Business focus (Commercial, Personal, Reinsurance)
  - Ownership (Stock, Mutual, Others)
  - Distribution channel (Broker vs Non-Broker)
  - Geography (Regional vs National)
- Schedule P GL data & SNL company profile
  - Top 100 insurers by market share
  - Loss data is from 2008 to 2017



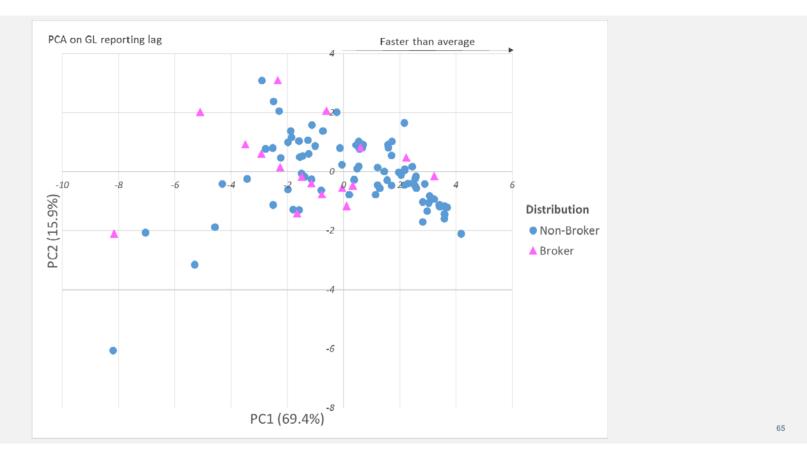




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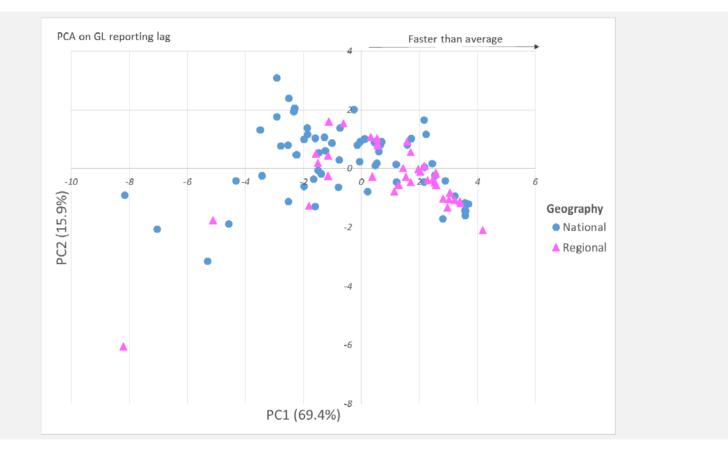






Munich RE





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#### **R** Packages



#### Important R packages:

- > Package "stats" (kmeans, prcomp,...) <u>https://stat.ethz.ch/R-manual/R-devel/library/stats/html/00Index.html</u>
- > Package "cluster" (pam, fanny,...) https://cran.r-project.org/web/packages/cluster/cluster.pdf
- > Package "factoextra" (get\_eigenvalue, fviz\_cluster,...) https://cran.r-project.org/web/packages/factoextra/factoextra.pdf
- > Package "ggplot2" https://cran.r-project.org/web/packages/ggplot2/ggplot2.pdf
- > Package "mclust" (mclust) https://cran.r-project.org/web/packages/mclust/mclust.pdf