

The Future of Automobiles and Automobile Insurance: Separating Scientific Fact from Fiction

Casualty Loss Reserve Seminar

Austin, TX September 18, 2019

Matt Moore - Senior VP

iihs.org

IIHS is an independent, nonprofit scientific and educational organization dedicated to reducing the losses — deaths, injuries and property damage — from crashes on the nation's roads.

HLDI shares this mission by analyzing insurance data representing human and economic losses from crashes and other events related to vehicle ownership.

Both organizations are wholly supported by auto insurers.



IIHS and HLDI member groups

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Funding Associations

American Property Casualty Insurance Association National Association of Mutual Insurance Companies



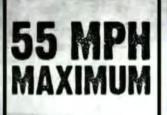
Haddon matrix

Recognizing opportunities to make a difference

	pre-crash	during crash	after crash
people	graduated licensing impaired driving laws automated enforcement	safety belts helmets	medical bracelets general health
vehicles	crash avoidance technology	airbags crashworthiness truck underride guards	automatic collision notification fuel system integrity
environment	roundabouts rumble strips	roadside barriers breakaway poles	emergency medical services long-term rehabilitation



CBS Evening News



HLDI data providers insure approximately 85% share of PPA

21st Century Insurance Alfa Alliance Insurance Corporation Allstate Insurance Group American Family Mutual Insurance American National Family of Companies Amica Mutual Insurance Company Auto Club Group Automobile Insurers Bureau of Massachusetts Chubb & Son **COUNTRY** Financial **CSAA** Insurance Group **Erie Insurance Group** Esurance Farm Bureau Financial Services Farmers Insurance Group of Companies Florida Farm Bureau Insurance Companies Foremost **GEICO** Corporation Hanover Insurance Group

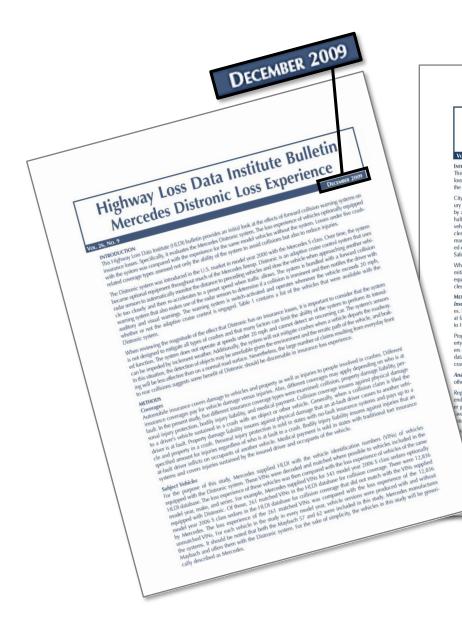
Kemper Preferred Kentucky Farm Bureau Insurance Liberty Mutual Insurance Company MetLife Auto and Home National General Nationwide New Jersey Manufacturers Insurance Group **PEMCO** Insurance **Plymouth Rock Assurance Progressive Corporation** Rockingham Group Safeco Insurance Companies **SECURA** Insurance Sentry Insurance State Farm Insurance Companies **Tennessee Farmers Mutual Insurance Company** Texas Farm Bureau The Travelers Companies USAA

The Hartford



Evaluations of Advanced Driver Assistance Systems (ADAS)

MAS ...



Highway Loss Data Institute Bulletin Volvo City Safety Loss Experience – Initial Results

Vol. 28, No. 6

This Highway Loss Data Institute (HLDI) bulletin provides an initial look at the effects of Volvo's City Safety technology on insurance losses. The loss experience for Volvo XC60s equipped with City Safety was compared with losses for comparable vehicles without the system. Losses under property damage liability, buddly injury liability, and collision coverage were examined.

LINE 2011

City Safety, a low-speed collision avoidance system, was released as standard equipment on the 2010 Volvo XC6.0, a midsize lucury SUV. The system was developed by Volvo to reduce low-speed fornt-k-owar crashes, which commonly occur in unban taffic, by assisting the driver in bading. According to a Volvo news release, 75 percent of all crashes occur at speeds up to 19 mph, and half of these occur in city taffic: The City Safety system has an infrared laser sensor built into the windshield that detects other vehicles traveling in the same direction up to 18 feet in front of the XC60. The system infially treacts to slowing or stoppet vehicles by pre-changing the brakes. The vehicle will brake automatically if forward collision risk is detected and the driver does not react in time, but only at travel speeds up to 19 mph, the vC60 speed will be reduced to lessen the collision carbe avoided entirely. If the speed difference is between 9 and 19 mph, the XC60 speed will be reduced to lessen the collision severity. City Safety is automatically activated when the vehicle gring in its inter of the tach me pranet up decirated by the driver.

When examining the magnitude of City Safety on insurance losses, it is important to consider that the system is not designed to mitigate all types of crashes and that many factors can limit the system's ability to perform its intended function. City Safety works equally well during the day and night, but fog, heavy rain, or snow may limit the ability of the system's infrared laser to detect vehicies. If the sensor becomes blocked by dirt, ice, or snow, the driver is advised.

METHODS

Insurance Data – Automobile insurance covers damages to vehicles and property as well as injuries to people involved in crashes. Different insurance coverages pay for vehicle damage versus injuries, and different coverages may apply depending on who is at fault. The current study is based on property damage liability, bodily injury liability, and collision coverages. Data are supplied to HDD by its member companies.

Property damage liability coverage insures against physical damage that at-fault drivers cause to other people's vehicles and proetry in crashes. Bodily injury liability coverage insures against medical, hospital, and other expenses for injuries that at-fault drives inflict on occurants of other vehicles or others on the road. In the cauret study, bodily injury liability loses were restricted to data from traditional fort states. Collision coverage insures against physical damage to an at-fault driver's vehicle sustained in a crash with an object or other vehicle.

Analysis Methods – Loss data for the 2010 Volvo XC60 were compared with two control groups: other midsize luxury SUVs and other Volvo vehicles. Vehicle models with two- and four-wheel drive versions were combined to provide sufficient data for analysis.

Regression analysis was used to quantify the effect of Clip Safety while controlling for other covariates. The covariates included calendar year, model year, ganging state, vehicle density (number of registered vehicles per square mile), rated driver age, rated drive regreder, marila stats, deductible, and risk. Calim frequency was modeled using a Poisson distribution, whereas claim severity average loss payment per claim) was modeled using a Camma distribution. Both models used a logarithmic link function, timates for overall losses were derived from the claim frequency and claim severity models.

icle series was included as a variable in the regression models, with the Volvo XC60 assigned as the reference group. The model luced estimates for each series' losses relative to the XC60. When predicted losses were calculated, the XC60's value was posed to be equal to the actual losses, whereas for any other series the losses were calculated by multiplying the XC60's value was posestimate obtained from the regression. For example, the actual property damage liability claim frequency for the Volvo equaled 2.2 claims per 100 insured vehicle years. The model estimated that the claim frequency for the Volvo XC70 output values and the same distribution of drivers and garaging locations. The comparable estimate for the Volvo XC70 property damage liability claim frequency was calculated as 2.2 x 1.096 ims per 100 insured vehicle years.





Vehicles with forward collision warning



2000 Mercedes-Benz S Class \$73,095

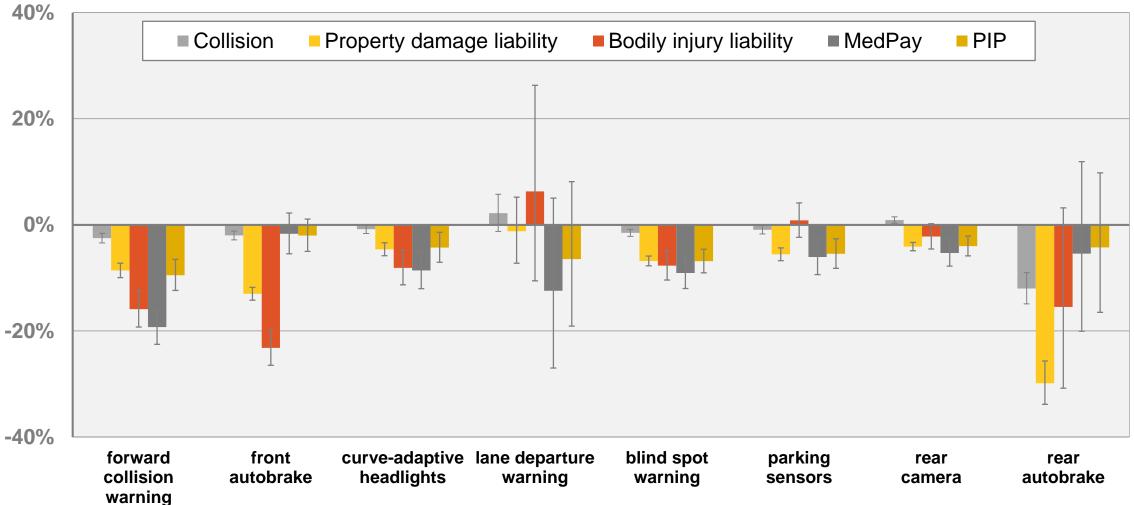
2018 Chevrolet Spark \$18,015



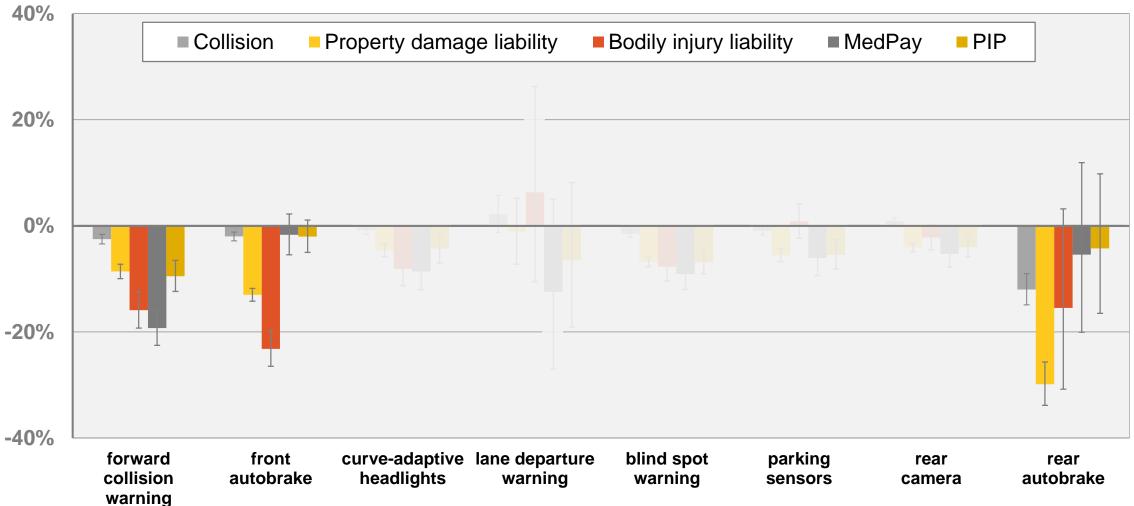
HLDI collision avoidance analysis

- The HLDI database includes data from companies that represent about 85% of private passenger auto insurance in the U.S.
- On a monthly basis, HLDI processes 320 million insurance data transactions
- The insurance data includes the garaging zip code and rated driver demographics
- Manufacturers shared with us 17 digit VINs and information about collision avoidance systems fitted to those vehicles
- Our collision avoidance analysis used the manufacturer supplied feature data along with our geographic and demographic data
- Large amount of timely data
- Limited information on crash circumstances

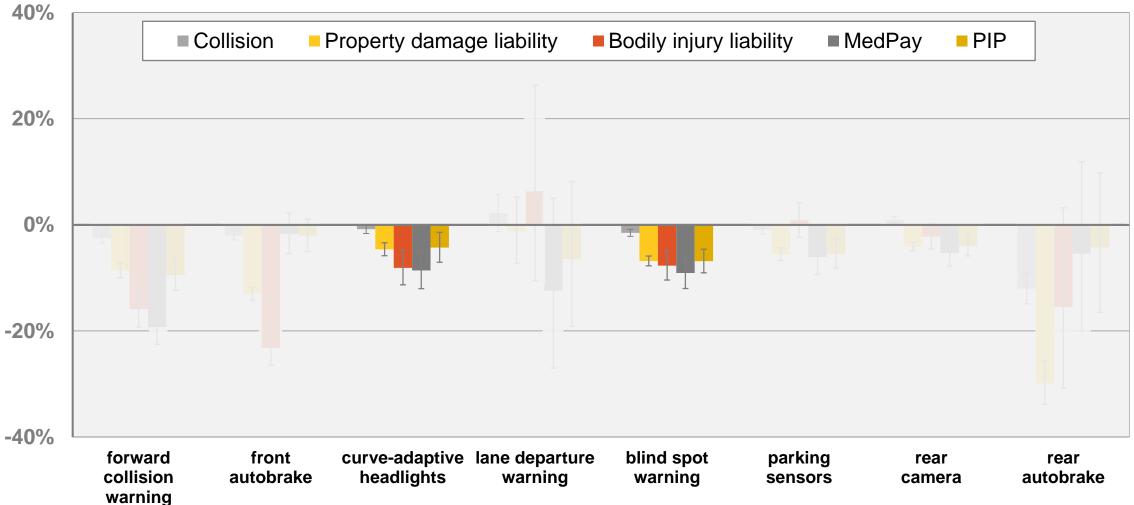




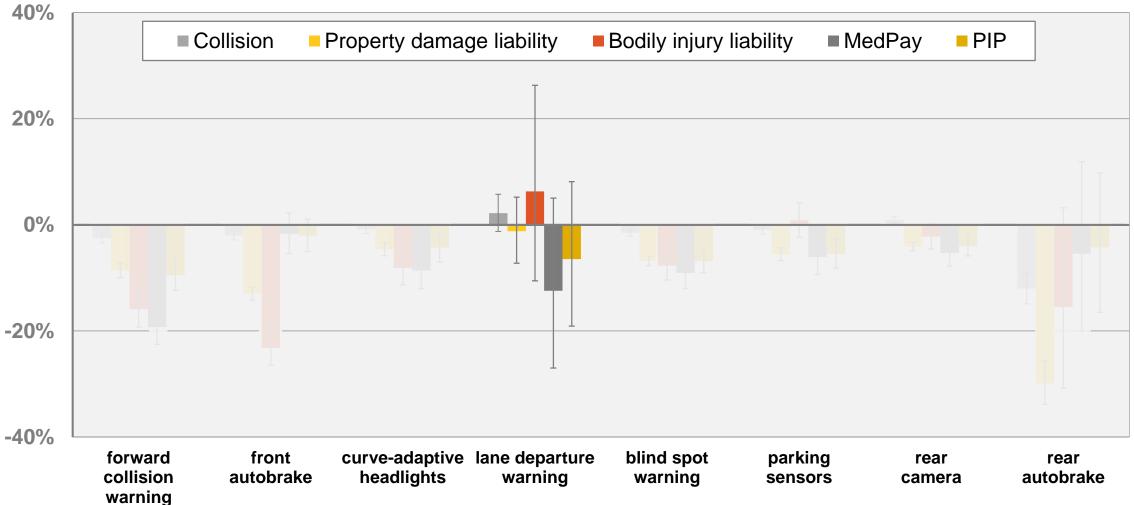




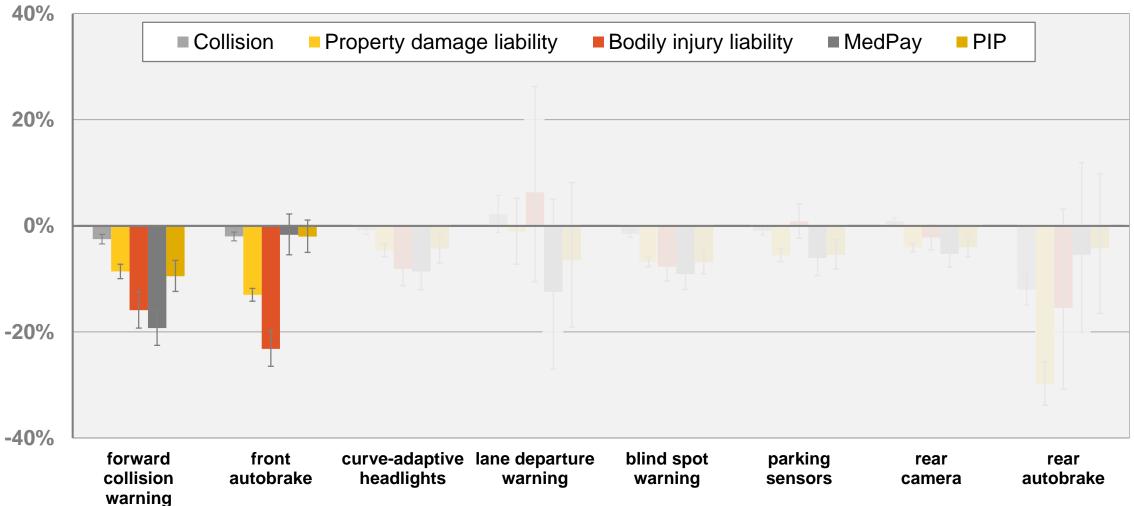




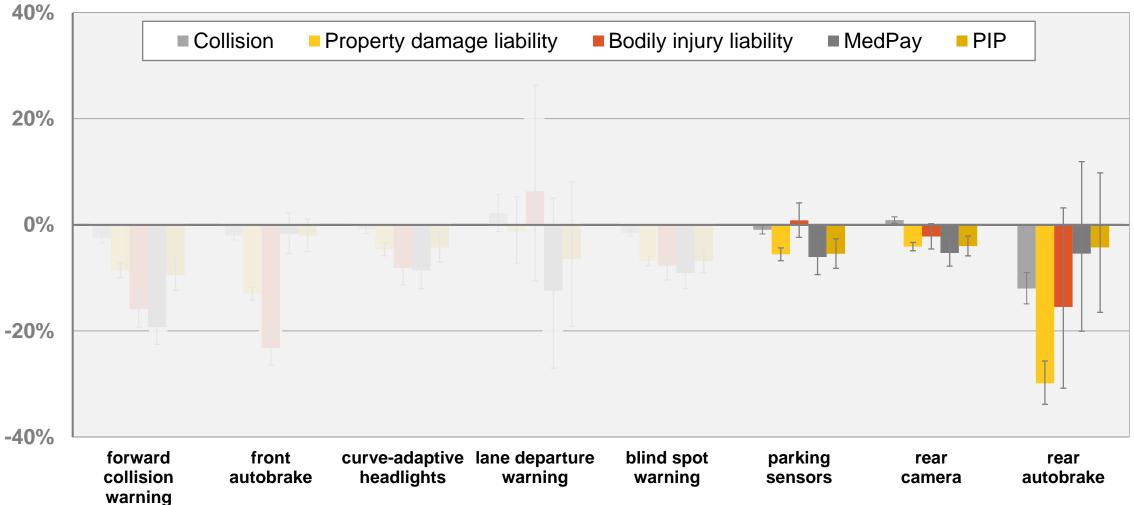














HLDI and police-reported crash data

Insurance data

- Large amount of timely data
- Limited information on crash circumstances

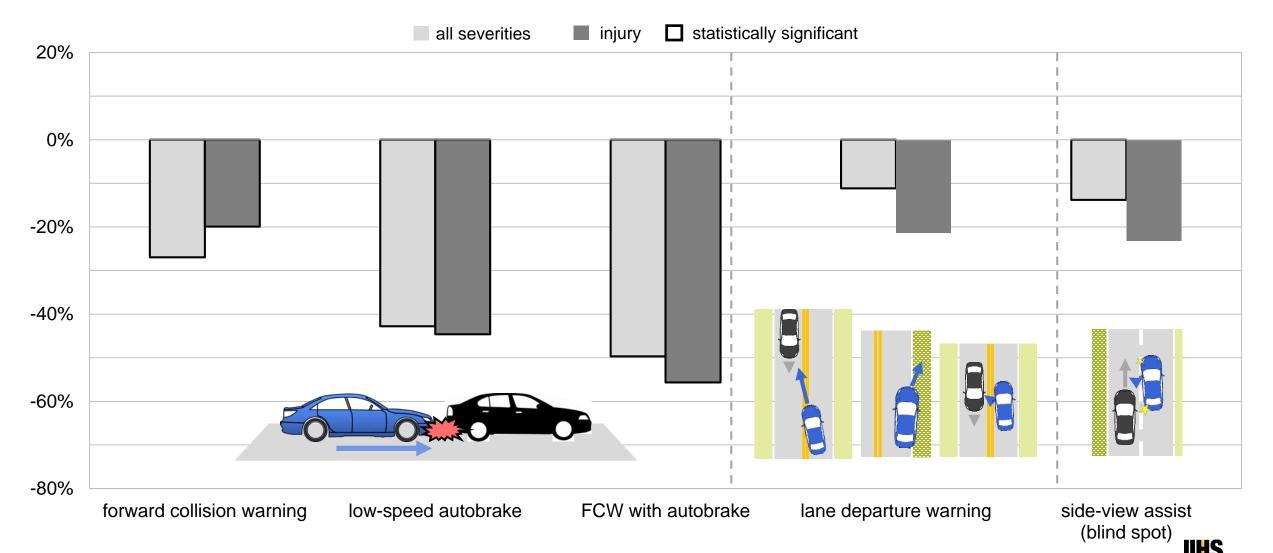
Police-reported crash data

- More detailed information on crash type
- Limitations
 - Some crashes not reported to police
 - Delay in obtaining data
 - Data collected not uniform among states, and not all states have information to determine crash types

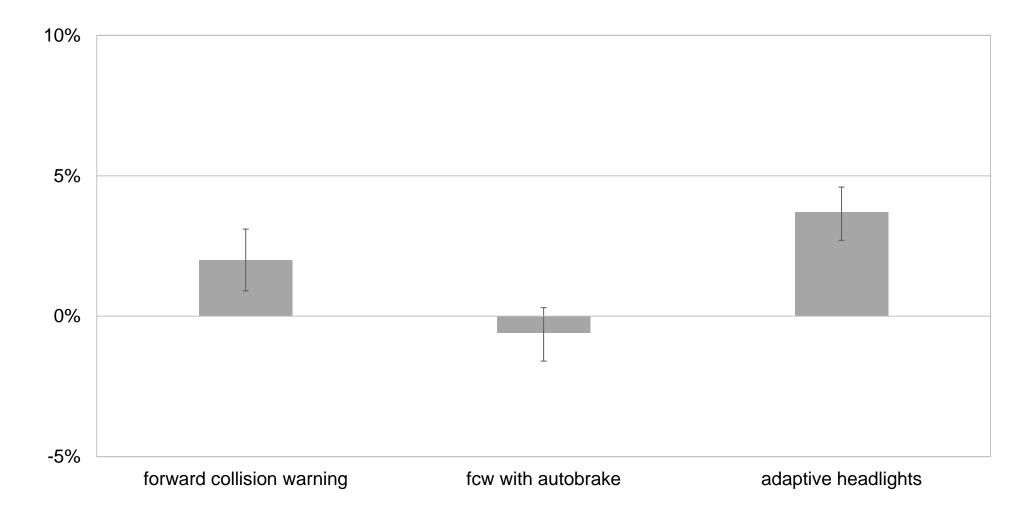


Most crash avoidance technologies are living up to expectations

Effects on relevant police-reported crash types



Summary of technology effects on collision claim severity





GM collision avoidance features

IIHS HLDI

Change in insurance losses for GM vehicles

With parking sensors and rearview camera

	fr	claim claim frequency severity		/	overall losses				
collision	-9.3%	-7.1%	-4.8%	\$151	\$283	\$418	-\$21	-\$7	\$9
property damage liability	-19.9%	-16.6%	-13.2%	\$7	\$139	\$277	-\$20	-\$15	-\$9
	fr	claim equenc	су	low high severity severit frequency frequen		severity	5		
bodily injury liability	-23.3%	-14.2%	-4.0%	-28.2%	-11.7%	8.6%	-21.5%	-3.7%	18.2%
medical payment	-21.5%	-12.6%	-2.7%	-31.9%	-7.9%	24.6%	-23.6%	-10.6%	4.7%
personal injury protection	-12.1%	-4.6%	3.5%	-29.4%	-12.3%	9.1%	-16.3%	-6.7%	4.0%



Change in insurance losses for GM vehicles

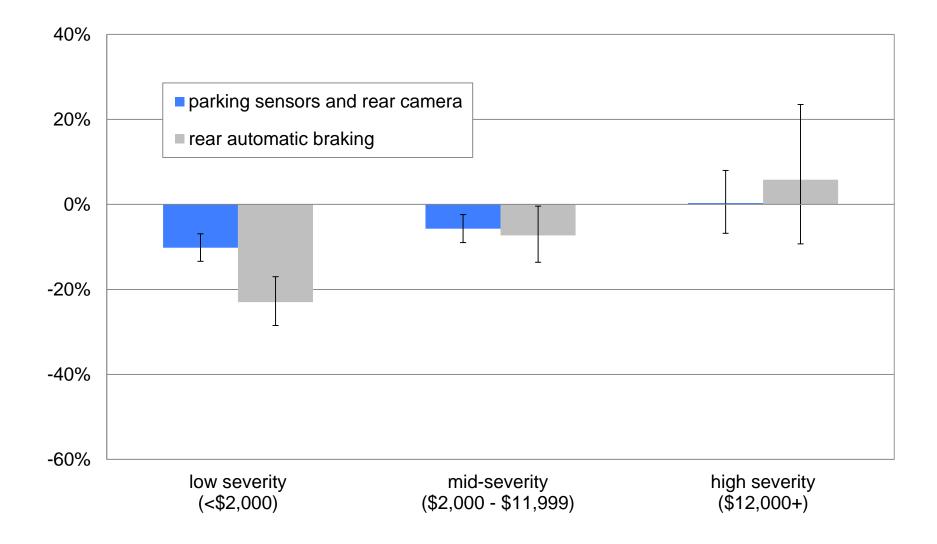
With rear automatic braking

	claim claim frequency severity			overall losses					
collision	-17.2%	-13.1%	-8.7%	\$537	\$846	\$1,173	-\$21	\$7	\$37
property damage liability	-32.1%	-26.3%	-20.1%	\$300	\$601	\$926	-\$22	-\$13	-\$3
	fr	claim equenc	су	low high severity severity frequency frequency					
bodily injury liability	-28.8%	-8.9%	16.5%	-30.5%	8.3%	68.8%	-46.5%	-15.1%	34.8%
medical payment	-22.6%	-1.5%	25.4%	-63.4%	-23.8%	58.3%	-32.4%	-4.5%	34.9%
personal injury protection	-19.9%	-1.8%	20.4%	-46.0%	-7.9%	57.1%	-17.0%	9.6%	44.7%



Change in collision claim frequency

By severity range





Front crash prevention testing and rating

Front crash prevention ratings



vehicles without forward collision warning or autobrake; or vehicles equipped with a system that doesn't meet NHTSA or IIHS criteria



vehicles earning 1 point for forward collision warning or 1 point in either 12 or 25 mph test



vehicles with autobrake that achieve 2-4 points for forward collision warning and/or performance in autobraking tests



vehicles with autobrake that achieve 5-6 points for forward collision warning and/or performance in autobraking tests



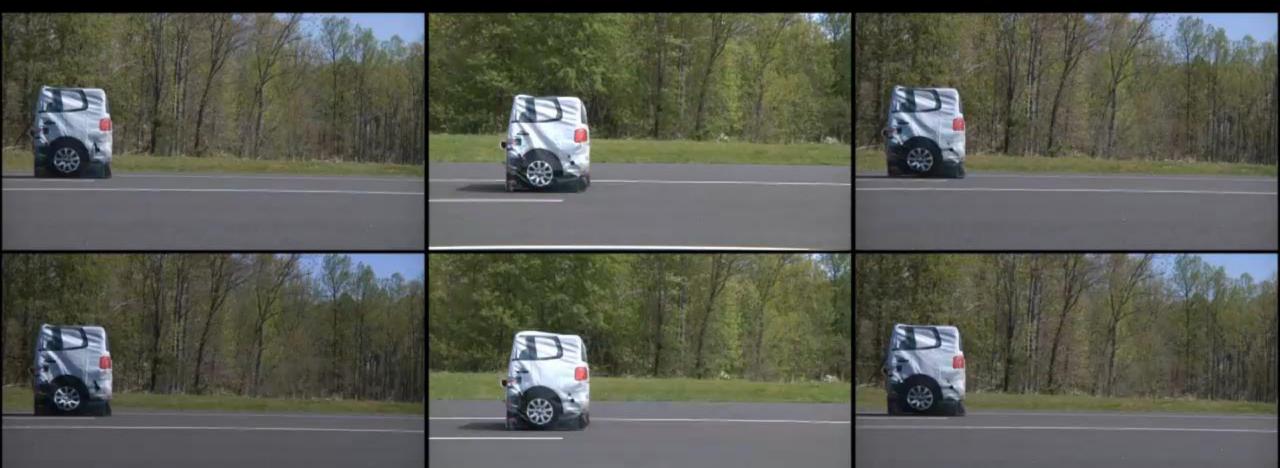


25 mph \$28,131

12 mph \$5,715

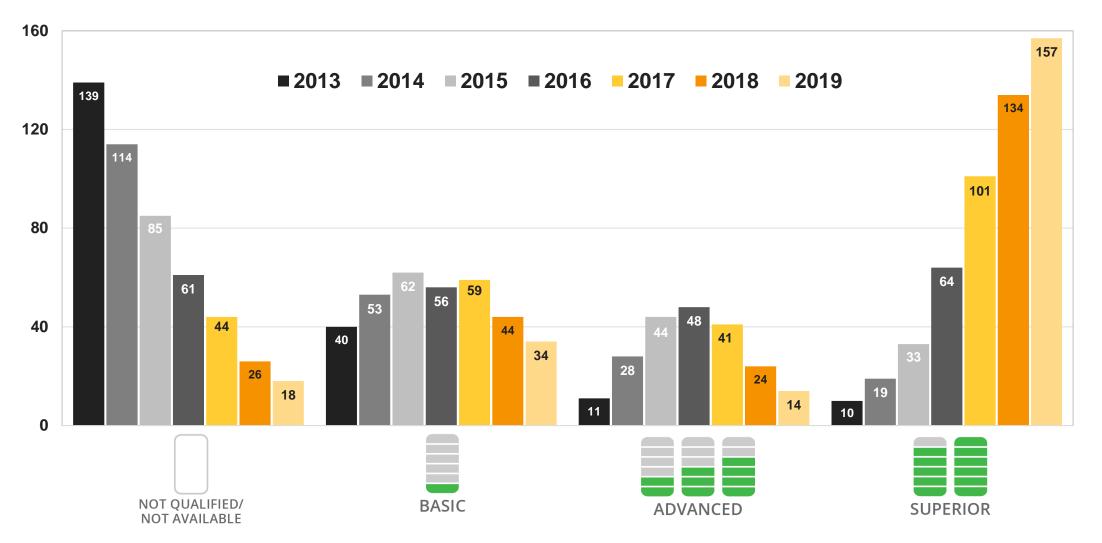
Speed reduction in 12 and 24 mph tests

Volvo S60 2 point advanced Dodge Durango 3 point advanced Subaru Outback 6 point superior



Front crash prevention ratings

2013-19 models, as of September 2019





20 automakers have committed to make AEB a standard feature by September 2022



Hyundai advertisement

Headlight testing and ratings

Toyota Prius v LED and BMW 3 series halogen

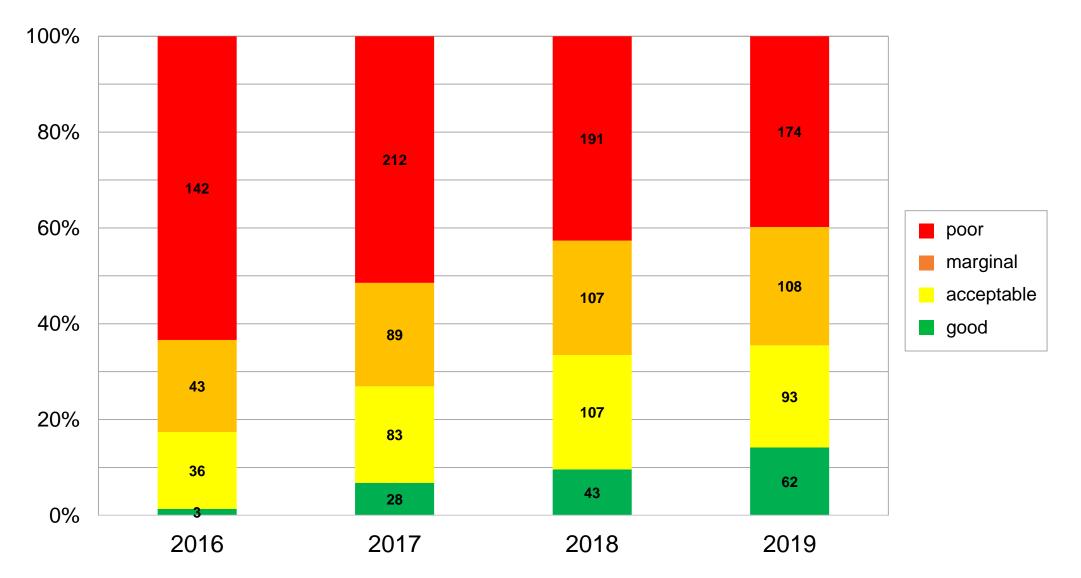
On-road comparison





Headlight ratings (as of September 2019)

2016-19 model years – all headlight variants





Evaluations of system status

IIHS HLDI

On-off status of front crash prevention systems

By manufacturer

	percent with system on	number observed
Cadillac	92	206
Chevrolet	87	142
Honda	98	239
Mazda	95	20
Volvo	94	52
total	93	659



On-off status of lane-maintenance systems

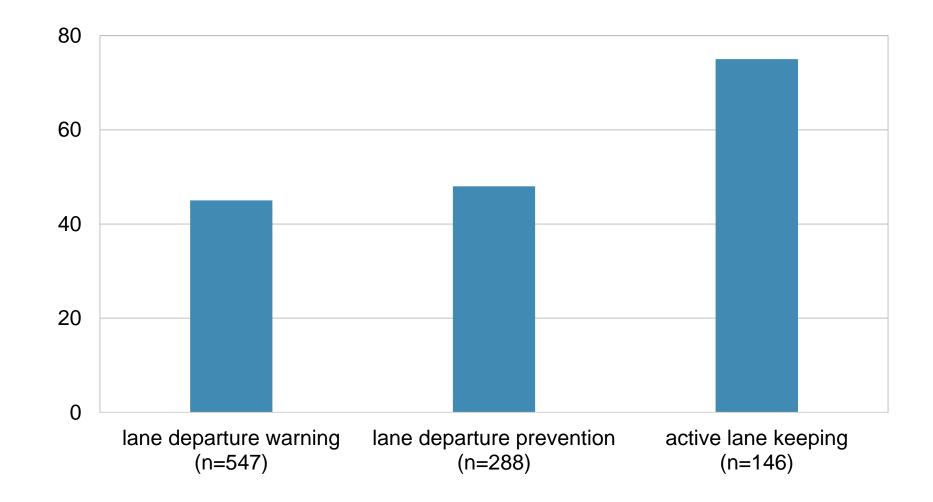
By manufacturer

	percent with system on	number observed
Cadillac	56	204
Chevrolet	50	147
Ford/Lincoln	21	115
Honda	36	239
Lexus/Toyota	68	147 26
Mazda	77	
Volvo	75	105
total	51	983



On-off status by maximum observable lane-maintenance intervention level

Percent with system on





GM lane departure warning on-off status by warning modality

		percent with system on	number observed
beep	Cadillac	33	18
	Chevrolet	39	66
	total	38	84
vibrating seat	Cadillac	58	142
	Chevrolet	49	49
	total	56	191



Advertisement:

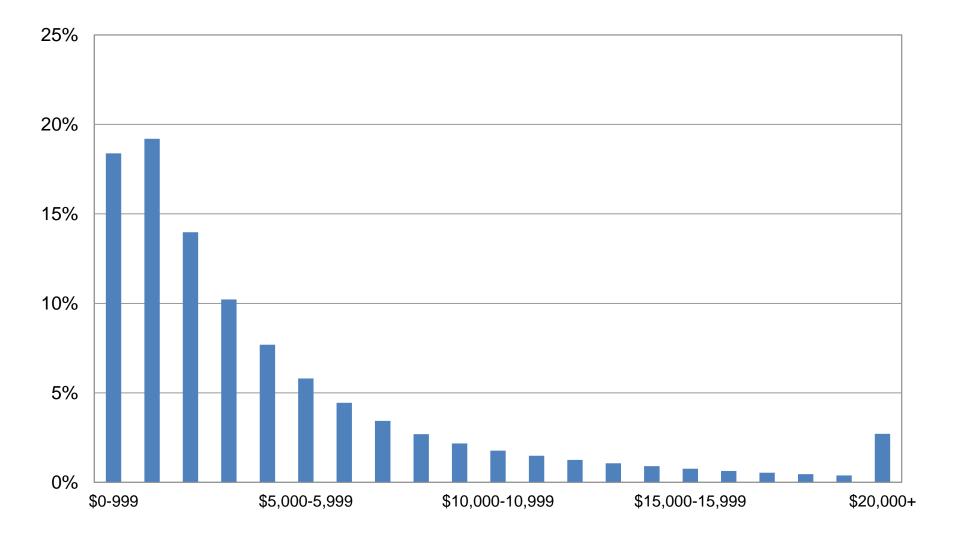
Lane valet

Park assist systems

IIIS Hldi

Distribution of collision claims, 2017 calendar year

By claim size, 1981–2018 models





Drivers must respond to sensors for them to work





Objects are not always easy to see in the camera display



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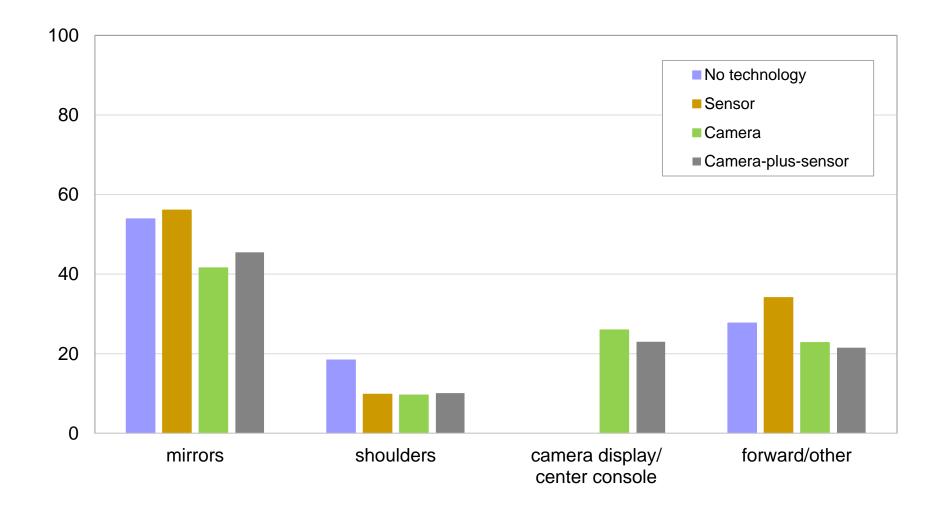
Rearview cameras can help drivers avoid backing over objects in reverse



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Technology influences the way we look around the vehicle while backing

Percentage of time spent looking at different fields of view



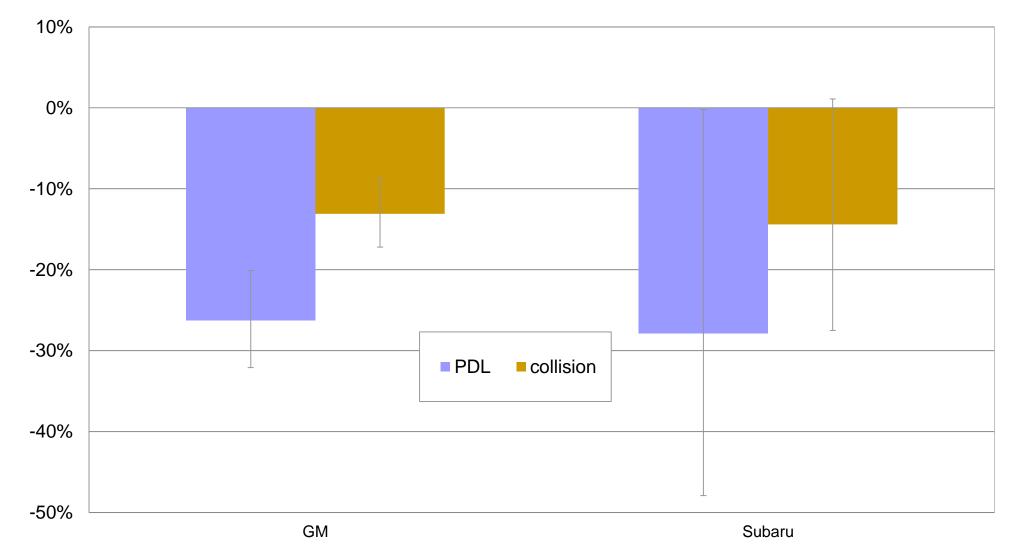


Rear automatic braking

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Rear automatic braking

Change in claim frequency



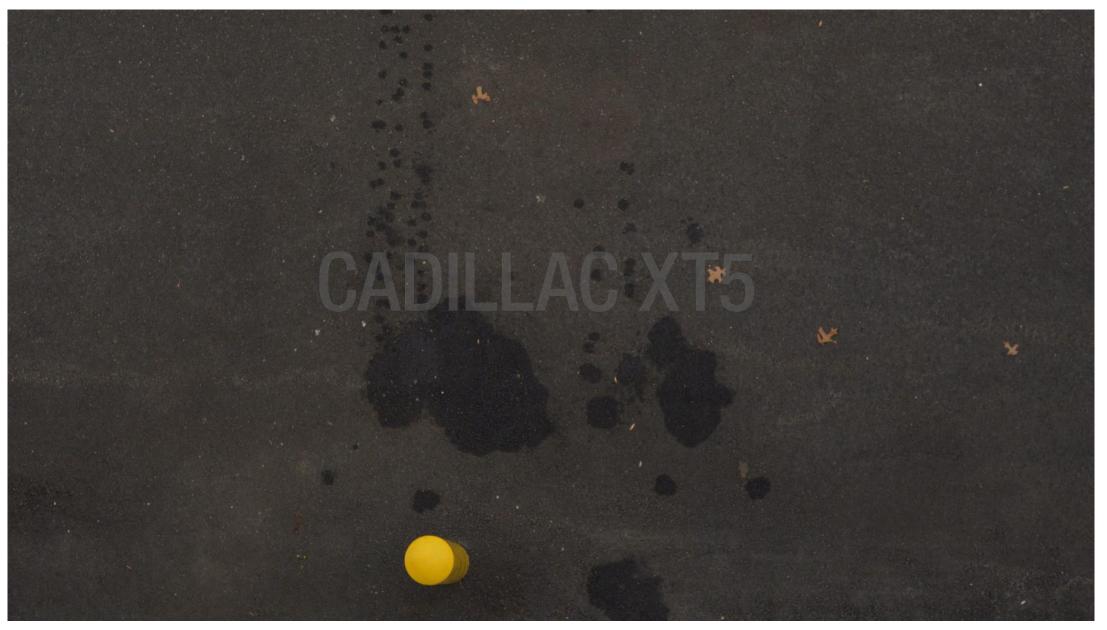


Benefit of rear autobrake





Benefit of rear autobrake

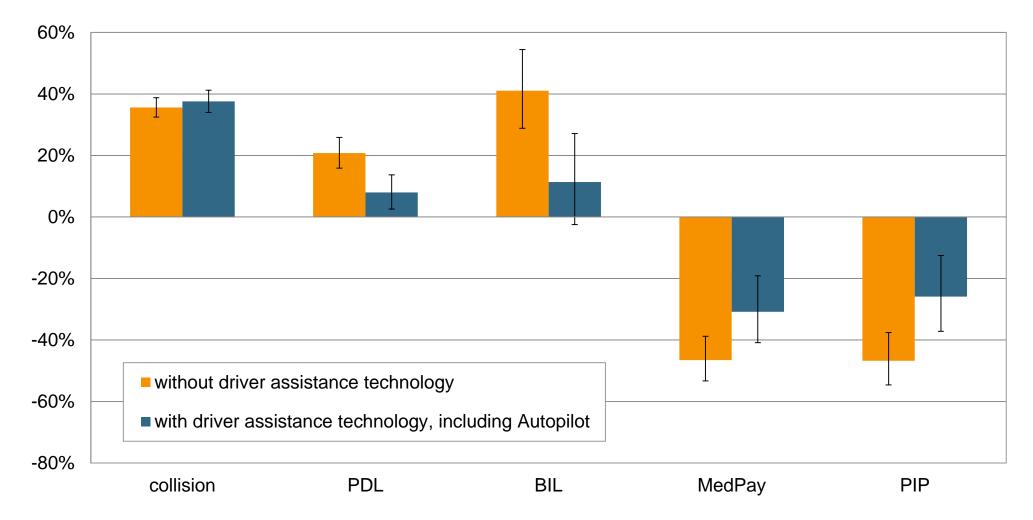




Insurance results for Level 2 systems

Tesla Model S claim frequencies with and without driver assistance technology versus large luxury vehicles

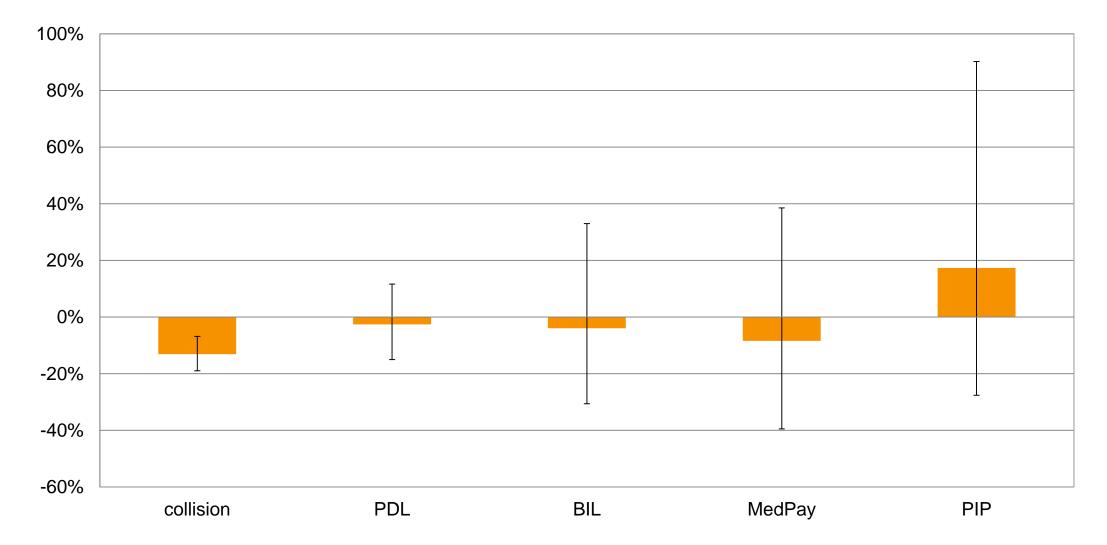
Effect of driver assistance technology, including Autopilot





Estimated effect of Tesla Model S Autopilot on claim frequency

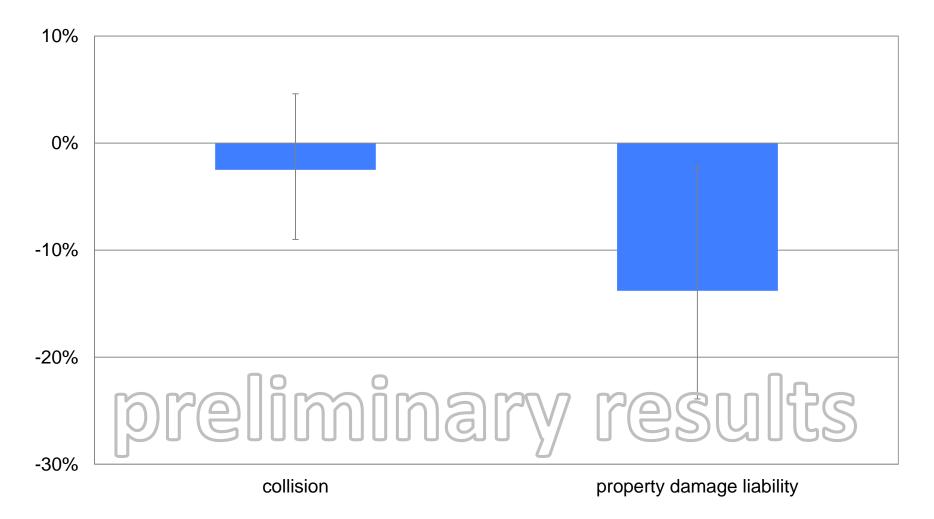
Driver assistance technology plus Autopilot vs. early driver assistance technology alone





Effect of Audi Traffic Jam Assist, adaptive cruise control, active lane assist and high-beam assist on claim frequency

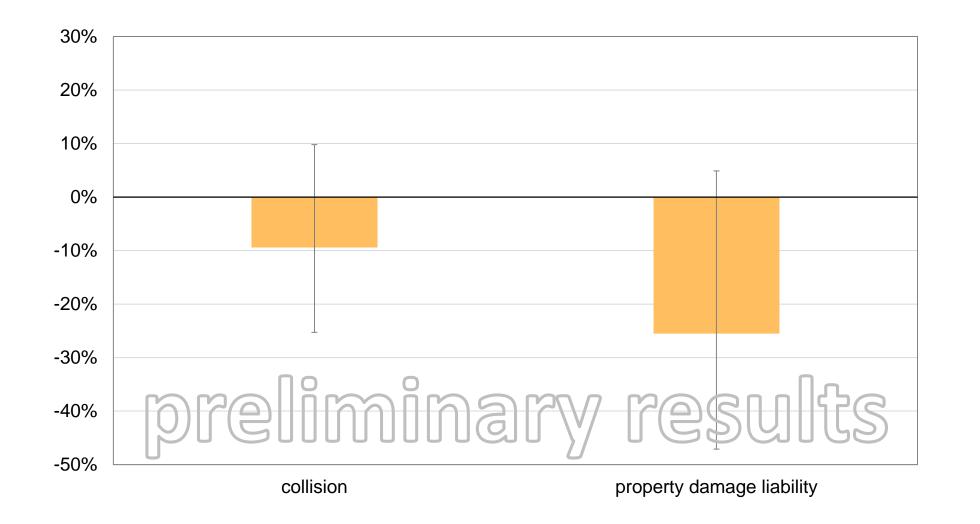
2017 Audi A4 and Q7, by insurance coverage type





Effect of Nissan ProPilot Assist on claim frequency

2016–18 Leaf and 2017–18 Rogue, by insurance coverage type





Experiences with driving automation

Opinions of level 2 driving automation technology after brief use

- 17-20 employees drove each vehicle on a 20-mile route while using level 2 driving automation the entire drive
- Completed a survey about their experience after the drive

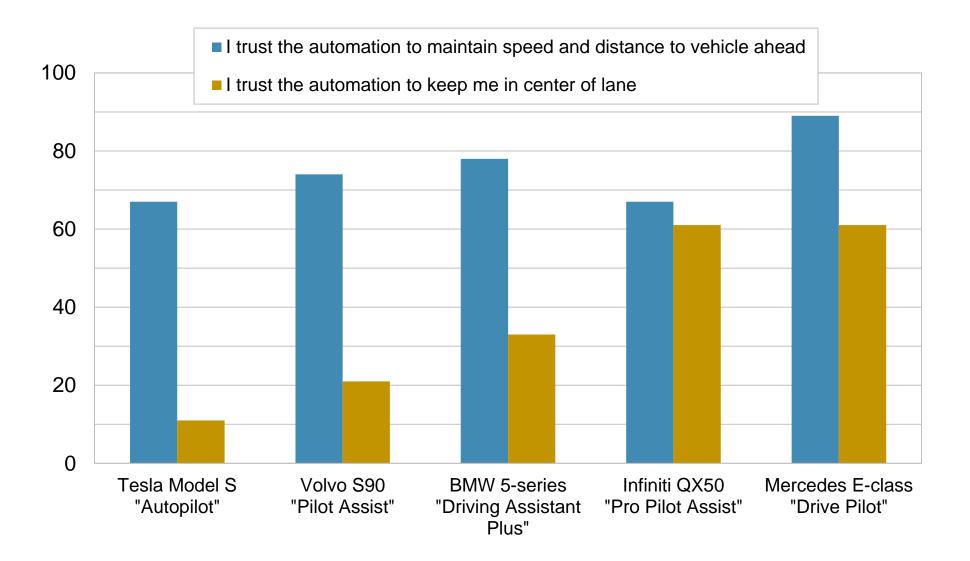
Five vehicles:

- -2017 BMW 5 series with "Driving Assistant Plus"
- -2017 Mercedes E-Class with "Drive Pilot"
- -2016 Tesla Model S with "Autopilot"
- -2018 Volvo S90 with "Pilot Assist"
- Pre-production 2019 Infiniti QX50 with "Pro Pilot Assist"



Adaptive cruise control trusted more than active lane keeping

Percentage of drivers who agreed or strongly agreed





Functional performance of adaptive cruise control

Functional performance testing of adaptive cruise control









2016 Tesla Model S with Autopilot software ver. 7.1

2017 BMW 5 series with Driving Assistant Plus

2017 Mercedes E-Class with Drive Pilot





2018 Volvo S90 with Pilot Assist 2018 Tesla Model 3 with Autopilot software ver. 8.1



Functional performance testing of adaptive cruise control

- Combination of track and on-road tests
- Adaptive cruise control scenarios
 - Stopped lead vehicle
 - -Vehicle exiting lane
 - Acceleration/deceleration profiles



Approach stationary target with ACC on





Test track performance was not necessarily replicated on road

On-road testing – approaching stationary vehicles





Less common hazards may or may not be detected On-road testing





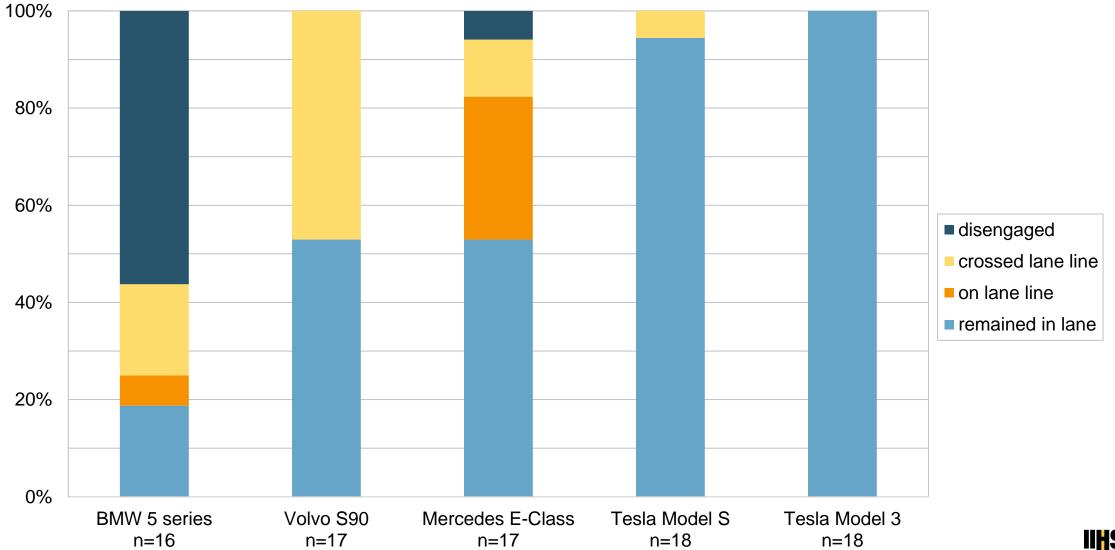
Functional performance of lane-keeping systems

Lane keeping in curves





Lane keeping in curves



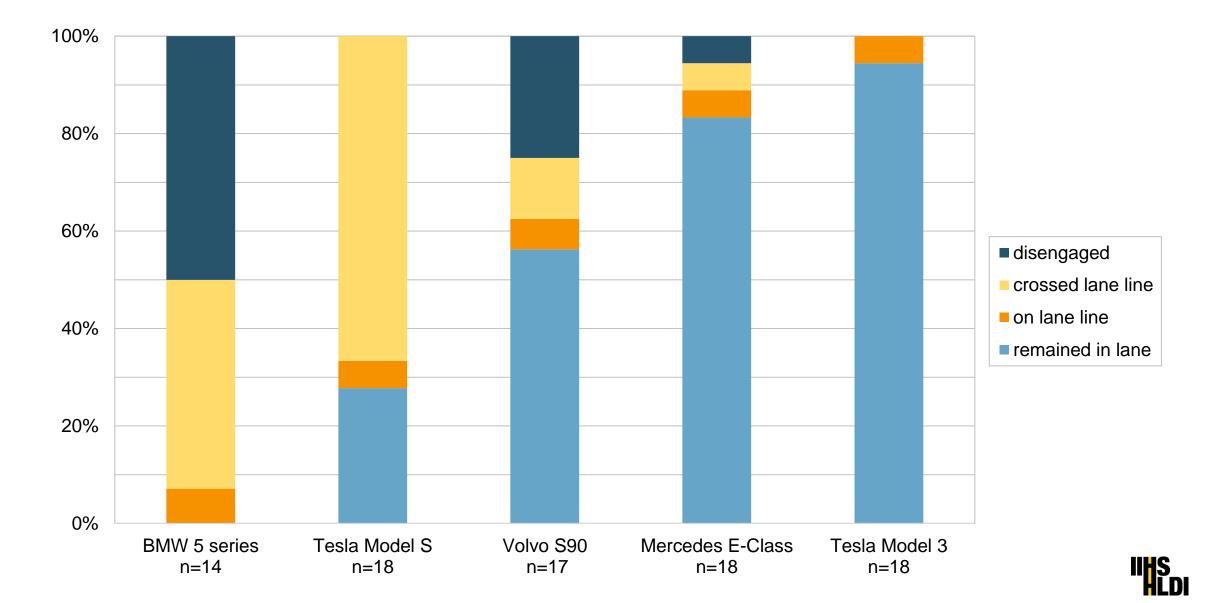


Lane keeping on hills





Lane keeping on hills



Can automation eliminate all crashes caused by human error?

II<mark>H</mark>S

Human error contributes to most crashes

Necessary conditions for automation to be safer than human drivers

Better than human driver crash rates.¹ Fewer than...

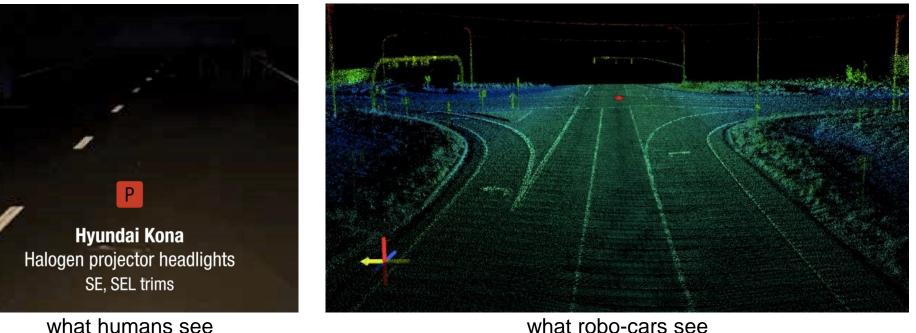
- -560 people in police-reported crashes
- -99 injuries
- -1.2 fatalities
- ...per 100 million miles travelled
- The critical precrash event was attributed to drivers in 94 percent of crashes²



Forty-one percent were recognition errors

Automated driving systems need to reliably "recognize" and avoid critical situations better than humans

- Inadequate surveillance
- Distraction
- Inattention
- Other



what robo-cars see



Thirty-three percent were decision errors

ADS need to make better decisions, obey traffic laws and predict the future better than humans



Speed

- Wrong assumptions about other road users
- Illegal maneuver
- Aggressive driving



Eleven percent performance and 7 percent nonperformance errors

ADS need to reliably control the vehicle better than humans



- No or insufficient braking
 Over or under steering
 Freezing
- Other



Did the Uber self-driving system avoid humanlike errors?



PRELIMINARY REPORT HIGHWAY

HWY18MH010 The information in this report is preliminary and will be supplemented or corrected during the course of the investigation.

About 9:58 p.m., on Sunday, March 18, 2018, an Uber Technologies, Inc. test vehicle, based on a modified 2017 Volvo XC90 and operating with a self-driving system in computer control mode, struck a pedestrian on northbound Mill Avenue, in Tempe, Maricopa County, Arizona. The Uber test vehicle was occupied by one vehicle operator, a 44-year-old female. No passengers were in the vehicle.

In the area of the crash, northbound Mill Avenue consists of two left-turn lanes, two through lanes, and one bike lane. The crash occurred before the formation of a right-turn lane. Roadway lighting was present. The posted speed limit was 45 mph.

The crash occurred as the pedestrian, a 49-year-old female, walked a bicycle east across Mill Avenue. The Uber test vehicle was traveling in the right through lane when its right front side struck the pedestrian (see figure 1). As a result of the crash, the pedestrian died. The vehicle operator was not injured.

In this area, northbound Mill Avenue is separated from southbound Mill Avenue by a center median containing trees, shrubs, and brick landscaping in the shape of an X. Four signs at the edges of the brick median, facing toward the roadway, warn pedestrians to use the crosswalk. The nearest crosswalk is at the intersection of Mill Avenue and Curry Road, about 360 feet north of where the crash occurred.



Figure 1. (Left) Location of the crash on northbound Mill Avenue, showing the paths of the pedestrian in orange and of the Uber test vehicle in green. (Right) Postcrash view of the Uber test vehicle, showing damage to the right front side.

Recognition error?

 Uber's AV detected pedestrian and classified her as an unknown object, then a vehicle, finally a bicycle

Paths were converging at 6 seconds before impact, but
 Uber's AV computed varying expectations of future path

Decision error?

Six seconds before impart, Uber's AV was moving 43 mph in 45 mph zone

-Impact speed was 39 mph

NTSB preliminary report gives no explanation for speed change

Should Uber's AV have slowed more?

Performance error?

-Emergency braking maneuvers were disabled

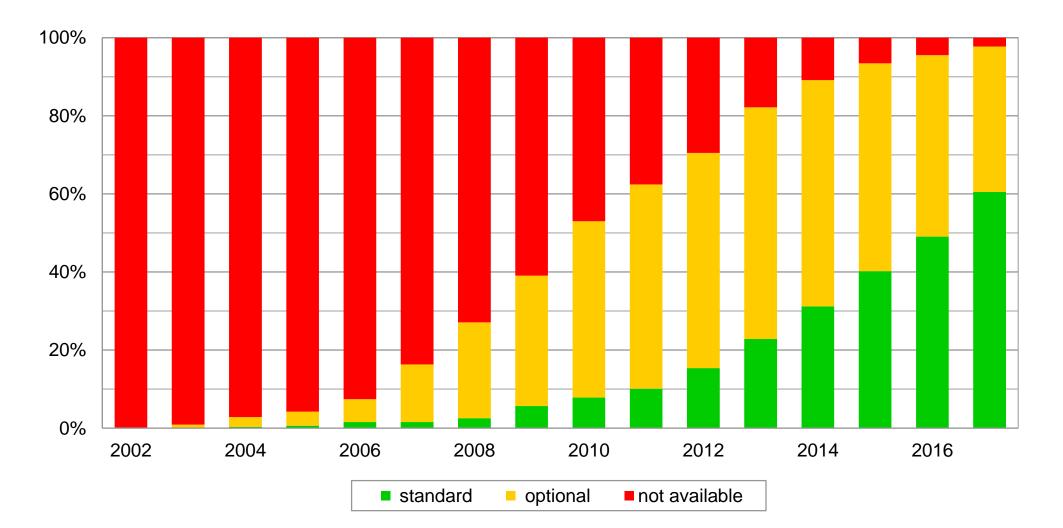


Fleet fitment of ADAS

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New vehicle series with rear camera

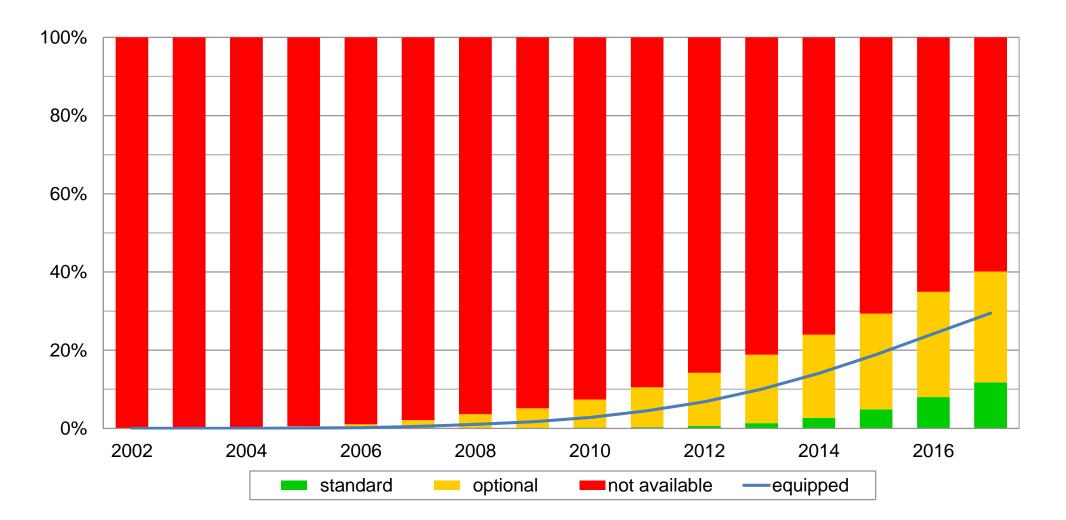
By model year





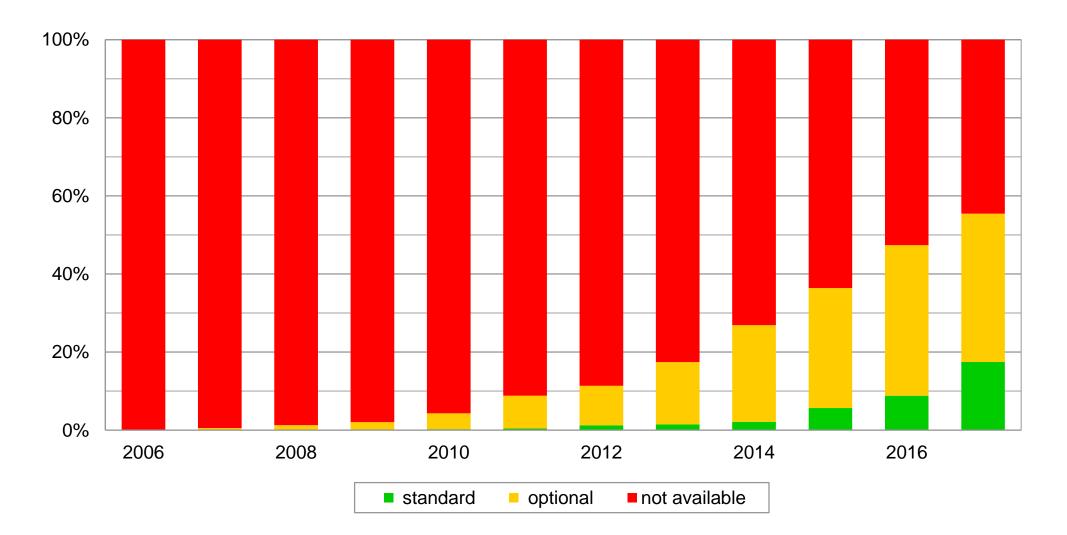
Registered vehicles with rear camera

By calendar year



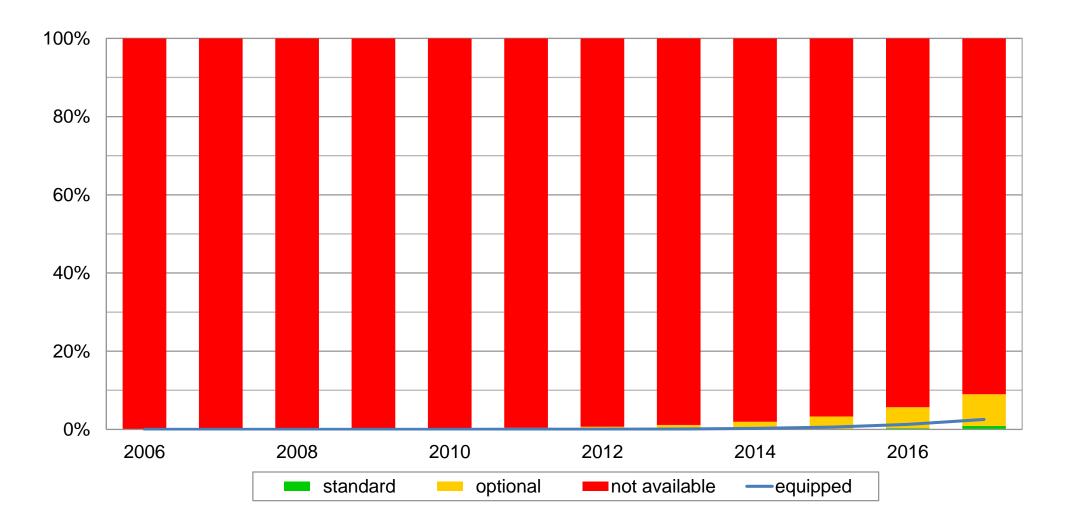


New vehicle series with autonomous emergency braking By model year



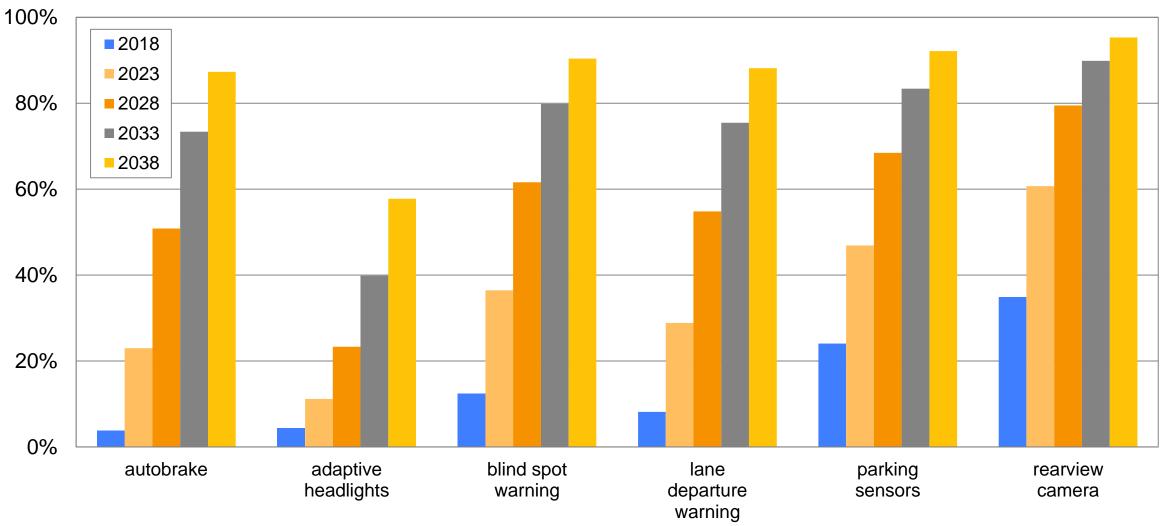


Registered vehicles with autonomous emergency braking By calendar year



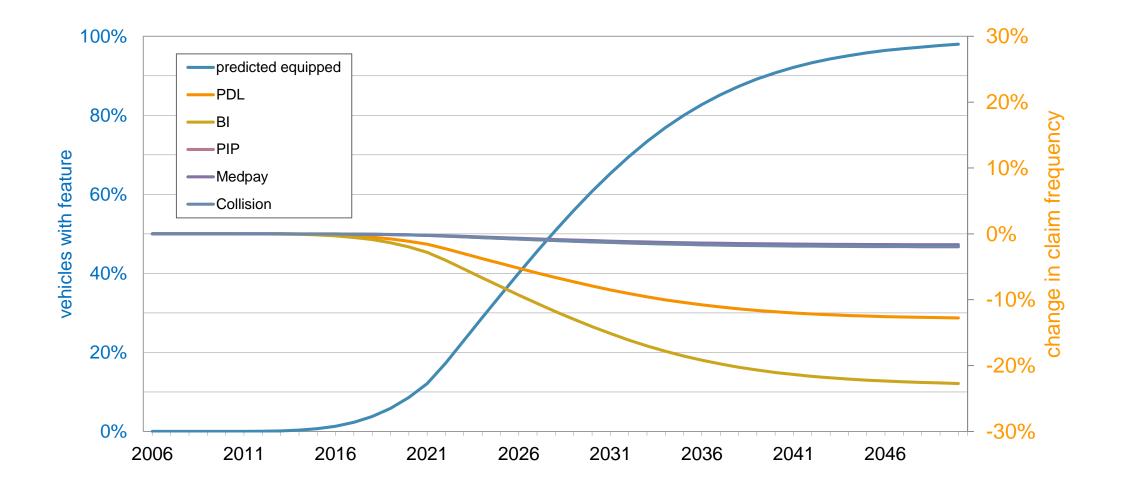


Predicted registered vehicles by feature by calendar year





Estimated change in claim frequency due to increased fitment of front autobrake systems







More information at iihs.org and on our social channels:



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